

MATH 761-SYLLABUS- FALL 2014

- Course : Math 761. It meets TR at Van Vleet 131 from 9:30 am to 10:45 pm.
- Texts: *Lectures on Differential Geometry* by Shlomo Sternberg, Prentice-Hall Inc.; and *A comprehensive introduction to Differential Geometry*, by Michael Spivak, V. I. Publish or Perish Inc. 2005. I will follow Spivak and shift to Sternberg's occasionally for topics Spivak does not cover (like Hamiltonian mechanics, or Lie groups if we have time).
- Lecturer : Prof. Gloria Mari Boffa, mariboff@math.wisc.edu
- Office: Van Vleet Hall 309/218, office phone #: 263-1634
- Office hours: T II-12 am, R 4-5 pm or by appointment.

Math 761 is an introduction to Differential Geometry and a preparatory class for the Geometry preliminary exam. The following is a rough description of lectures (note for my own discipline than your information...). You will need to come to class if you want to know what we are covering. The dates of midterms are fixed, you will be able to take them home and complete them. You will be assigned homework in class and I will collect them every 2-3 weeks. I expect students to at least try solving the problems to get computational skills and a better understanding.

Lectures

1. Manifolds: definition, examples and review of the basics.
2. Non trivial examples. Manifolds with boundaries.
3. Differentiable structures on a manifold: differentiable maps, regularity, diffeomorphisms.
4. Sard's Theorem. Immersions and imbeddings.
5. Submanifolds. Partitions of Unity.
6. Tangent vectors and the differential.
7. Vector bundles. The tangent bundle.
8. Properties of the tangent bundle. Vector fields.
9. Orientation of vectors, orientable manifolds and preservation of orientation.
10. The cotangent bundle. The differential map. Tensors and tensor bundles.
11. Covariant, contravariant and mixed tensors. Contractions.
12. Integration of vector fields: existence and uniqueness. Contraction maps.
13. Integration (cont.).
14. Lie derivative. Lie brackets.
15. Lie brackets (cont.). Commuting vector fields.
16. Distributions and integral manifolds. Integrable distributions.
17. Frobenius Theorem. Foliations and global picture.
18. Alternating tensors and wedge products. Forms.
19. Differentials. A second version of Frobenius Theorem.
20. Closed and exact forms. Poincaré's Lemma.
21. Hamiltonian structures.
22. Introduction to integration: the integral of n -forms over n -cubes.
23. Chains and boundaries. Closed chains.

24. Stoke's Theorem (first version on chains).
25. Orientation of a manifold with boundary; Stoke's Theorem.
26. De Rham Cohomology, examples.
27. Lie Groups, introduction and examples.
28. Invariant fields, Lie algebras and structure equations. Homogeneous spaces.

First midterm is October 13, due October 20. Second midterm is November 17, due November 24. Final exam is to be announced.

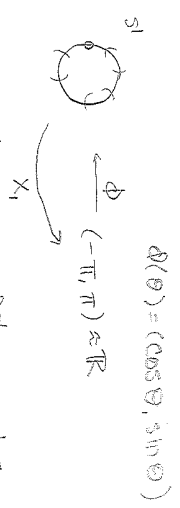
Assume M is a Hausdorff sp. (top. sp. for which separate pts have disc. nbhd's) w/ a countable basis. Ex in \mathbb{R}^n , take $\{B_{1/n}(q)\}$ & call pt $\{i\}$ countable

Def: M is an n -mfd if for any pt $p \in M$, $\exists (U, \alpha)$, $p \in U \subset M$ open, $\alpha: U \rightarrow \mathbb{R}^n$ a homeomorphism (pts w/ pts inverse). n is called the dimension of the mfd & (x, U) are called the coordinates around p .

Def: M is an n -mfd w/ boundary if for any pt $p \in M$, $\exists (U, \alpha)$ s.t. U is a homeo. to either \mathbb{R}^n or \mathbb{H}^n , where \mathbb{H}^n is the closed half-sp. $\mathbb{H}^n = \{(x_1, \dots, x_n) \in \mathbb{R}^n, x_n \geq 0\}$. The pts for which \mathbb{H}^n is chosen form the boundary (not to be confused w/ the top boundary - not nec. same - depends on the topology chosen)

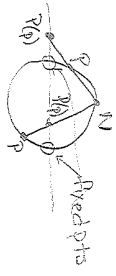
ex: $\mathbb{H}^n =$ rim matrices, w/ entries ≥ 0 . Those w/ entries = 0 are the boundary.

Ex: (a) \mathbb{R}^n
 (a) S^1 w/ top induced by \mathbb{R}^2 (always need sp. & topology)
 Consider the parametrization $\phi: (-\pi, \pi) \rightarrow S^1$



ϕ is a homeo & can choose $X_1 = \phi^{-1}$, $U_1 = S^{-1}\{(-1, 0)\}$
 If we use $\phi: (-\pi, \pi) \rightarrow \mathbb{R}$, $\phi(\theta) = \phi(\theta + \pi)$, & $X_2 = \hat{\phi}^{-1}$, $U_2 = S^{-1}\{(1, 0)\}$
 We cover S^1 w/ $(X_1, U_1), (X_2, U_2)$.
 * If you have a parametrization of your set, you probably have a mfd - just invert it.

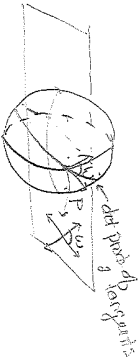
A 2nd coord system: Define the stereographic projection from the North pole to be the map that assoc. to each pt on circle to one on the line as in:



This gives coord sys for all pts but N, to get N, project from south pole. Maps for $p: S^n \rightarrow \mathbb{R}^n$.

Ex 1 Write down eqns (use \vec{v} , not $\vec{v} = (v_1, \dots, v_n)$)
 explicit formula for S^n & prove it is a conformal map, i.e. it preserves angles.

That is, if we choose 2 intersecting large circles on the sphere of on $\pm \omega$, the 2 circ. line images of the circles via P also form on $\pm \omega$.



choose 2 that project to lines - those that pass through north pole.
 (still well-def w/ circle & line - use tangents)

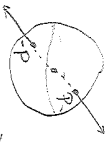
(3) M, N 2 mfd. of dim n & m . Then $M \times N$ is a mfd of dim $m+n$, w/ coordinates given by $U \times V \rightarrow \mathbb{R}^{m+n}$ a homeo. b/w $U \times V \subseteq \mathbb{R}^n \times \mathbb{R}^m \cong \mathbb{R}^{n+m} \Rightarrow$ product of mfd's is a mfd.

Thus, $T^n = S^1 \times \dots \times S^1$ is also a mfd.

(4) Projective space $\mathbb{R}P^n = \{ \text{sp of lines in } \mathbb{R}^{n+1} \text{ through origin} \}$, i.e.

$$\mathbb{R}P^n = \{ [p], p \in \mathbb{R}^{n+1}, p \neq 0, [p] = [\lambda p], \forall \lambda \in \mathbb{R} \setminus \{0\} \}.$$

Topology: $\mathbb{R}P^n = S^n / \sim$, where $p \sim q \Leftrightarrow p = -q$.



from top in S^n , induced from $\mathbb{R}P^n$.

- Consider all sets that have p but not $-p$, & use these to generate the topology

Coordinates: If $p = (p_i)$ w/ $p_n \neq 0$, then we define the coord's around p to be given by the affine coordinates $\pi(p) = \hat{p} \in \mathbb{R}^n$, where $p/p_n = (\hat{p}, 1)$. If $p_n = 0$, same $p_i \neq 0$, & use $p/p_i = (\hat{p}_1, \dots, \hat{p}_{i-1}, \hat{p}_{i+1}, \dots, \hat{p}_n)$.

(4a) $V^0 = \text{even}$ matrices is a field w/ coords the entries 2/2

(5) Grassmannian $Gr(k, n) \rightarrow$ subsp. of dim k through origin \mathbb{R}^n
i.e. $\mathbb{R}^{2n} \ni Gr(k, n) \hookrightarrow$ extension of \mathbb{R}^n

It is the set of k -dim'd linear subsp's in \mathbb{R}^n , i.e. one pt in $Gr(k, n)$ is a set of k ind. vectors.

Topology: identify a pt in $Gr(k, n)$ w/ the orthogonal proj. from \mathbb{R}^n to it. [Find orth compl. to your subsp. v_1, \dots, v_{n-k} : $v_1, \dots, v_{n-k}, u_1, \dots, u_k$. Take pt $\in \mathbb{R}^n$ write it in terms of this basis, then drop the last $(n-k)$ -coords]. This is a linear map, so if we fix a basis in \mathbb{R}^n , the map is described by a matrix. Then top. is induced by this matrix rep (as a subsp of \mathbb{R}^{n^2}).

HW ② Define coords in $Gr(k, n)$ by choosing a basis for the subsp.

Hint, each \vec{v}_i an n -vector, so put them as columns, \vec{v} get $n \times k$ matrix. These cannot be coords b/c not a homeo have a lot of choices. Could have diff. basis: but it would be $(v_1 \dots v_k) \mathcal{R}_{k \times k}$. Try to find identity matrix by multiplying on right by sq. matrix.

Same, if $k=1$: $\begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix} (y_n) = \begin{pmatrix} \vdots \\ 1 \end{pmatrix}$. rest will be coords.

What is the dim of $Gr(k, n)$?

[$Gr(k, n)$ are examples of flag manifolds]

③ Use the orthogonal complement to show that $Gr(2, 3)$ is equivalent to $\mathbb{R}P^2$.

Note: The $Gr(k, n)$, S^n , $\mathbb{R}P^n$ are all examples of homogeneous sp's, those of the form G/H , G a gp, H a subgp.

ex: S^n : fix North pole. Then each pt in S^n can be tied w/ a rotation taking pt to N , a $\mathbb{R}P^n = G$. But there are multiple ways to rotate — they differ by a rotation that leaves N invariant = H .
 $S^n \cong \text{SO}(n) / \text{SO}(n-1)$.

Differentiable Structures

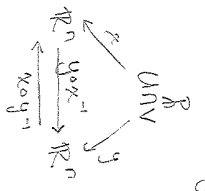
$\mathbb{R}^n \subset \mathbb{R}^m \rightarrow \mathbb{R}^k$, is f differentiable?

Def: Let $x: U \rightarrow \mathbb{R}^n$ & $y: V \rightarrow \mathbb{R}^m$ be 2 homeos, $U, V \subset \mathbb{R}^n$ open, $U \cap V \neq \emptyset$
 We say x & y are C^∞ related if the maps

$$x \circ y^{-1}: y(U \cap V) \rightarrow x(U \cap V) \text{ are } C^\infty$$

(open sets in \mathbb{R}^n)

[could use analytic or C^k]



$x \circ y^{-1}$ & $y \circ x^{-1}$ are called the transition maps (transition from x - to y -coords, or vice versa).

A family \mathcal{H} of C^∞ -related homeos that cover M is called a differentiable atlas for M .

non-ex: $\mathbb{R} \rightarrow \mathbb{R}$ are transition fcn in \mathbb{R} , which is not C^∞ ,
 $x_1 \rightarrow x_2$
 $x_2 \rightarrow x_1$
 coords.

Ex: \mathbb{R}^2 have S^1 w/ $(\cos \theta, \sin \theta)$ & $\mathbb{R}^2 \rightarrow \mathbb{R}^2$, need map $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ to be diff.

Then, if a map is diff in one coord, it will be in all others.
 An alt $(x, y) \in \mathcal{H}$ is called a chart or a coord system, & \mathbb{R}^n are the coords of \mathcal{P} .

Def: The pair (M, \mathcal{H}) , where \mathcal{H} is a max'l atlas (contains all possible C^∞ -rel. coords), is called a C^∞ (smooth, differentiable) manifold. The max'l atlas is said to define a differentiable structure.

9/4 - Diff. Maps

If a manifold has ∂ , we say a map $f: M^n \rightarrow \mathbb{R}^k$ is differentiable if we can extend it to a diff. fn on an open nbhd of M^n

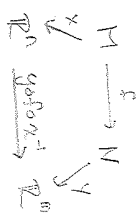
Def: Two smooth manifolds $(M, \mathcal{A}) \hat{=} (N, \mathcal{B})$ are differentiable if \exists map $f: M \rightarrow N$ (called a differentiability) which is 1-1 & s.t. $g \in \mathcal{B} \iff g \circ f \in \mathcal{A}$

ex: $(\mathbb{R}, \mathcal{A}) \xrightarrow{f: \mathbb{R} \rightarrow \mathbb{R}} (\mathbb{R}, \mathcal{B})$ & any fn that's C^∞ -rel. to \mathcal{D}
 $\mathcal{A}(x) = x$ $\mathcal{B}(x) = x^3$ is smth C^∞ -rel. to \mathcal{D} comp. w/ f^{-1}

Thus, f is a diff. map.

Note: f^{-1} not C^∞ , so analytically not a diff. map, b/c in analysis have same diff. structure on both \mathbb{R} 's - here, we are allowed to change diff. structure on target \mathbb{R} .

Def: A fn $f: M \rightarrow N$ is differentiable if for any $(x, U) \in M \hat{=} (y, V)$ in N , the $g \circ f \circ \alpha^{-1}: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is differentiable.



• what if change (y, V) to g ?
 Then have $g \circ f \circ \alpha^{-1} = g \circ \beta^{-1} \circ g \circ f \circ \alpha^{-1}$

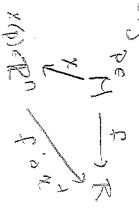
So, need only to check one set of coords & rest will be by tran. of coords \rightarrow i.e. one fn's diff. \hookrightarrow b/c transition

Task: Prove 1-5 in pg. 31 of Spivak, for practice.

Def: Let $f: M \rightarrow \mathbb{R}$ be diff, (x, U) coords at $p \in M$. We call

$\frac{\partial f}{\partial x_i}(p) = D_i(f \circ \alpha^{-1})(x(p))$ the i^{th} partial derivative of f at p .

Note: coords. are giving you directions on the manifold so can find rate of change in those directions.



Prop (Change of Variable): Let (x, y) & (u, v) be 2 coord. systems M ,
 let $f: M \rightarrow \mathbb{R}$ be diff. Then

$$\frac{\partial f}{\partial y_i}(p) = \sum_{j=1}^k \frac{\partial f}{\partial x_j}(q) \frac{\partial x_j}{\partial y_i}(q)$$

↑ def above w/ x instead of f & y instead of x .
 * be sure your fens go from $\mathbb{R}^m \rightarrow \mathbb{R}^n$

PF: $\frac{\partial f}{\partial y_i}(p) = D_i(f \circ g^{-1})(y(p)) = D_i \left(\underbrace{f \circ g^{-1}}_{\mathbb{R}^m \rightarrow \mathbb{R}^n} \right) (y(p))$

chain rule
 $\mathbb{R}^m \rightarrow \mathbb{R}^n$
 $= \sum_{j=1}^n D_j(f \circ g^{-1})(x(p)) D_i(x_j \circ g^{-1})(y(p))$
 $= \sum_{j=1}^n \frac{\partial f}{\partial x_j}(p) \frac{\partial x_j}{\partial y_i}(q)$ □

We can write this as

$$\rho_p = \frac{\partial f}{\partial y_i} \Big|_p = \sum_{j=1}^n \frac{\partial x_j}{\partial y_i}(p) \frac{\partial f}{\partial x_j} \Big|_p$$

• w/o the p , we have a diff. operator (ie, a derivation), ρ .

Def: Let $f: M \rightarrow \mathbb{R}$ be a smooth fcn. We say the rank of f at p is equal to the rank of the $n \times n$ matrix w/ (i, j) th entry

$$\frac{\partial^2 y^{i \circ f}}{\partial x_j^2}(p) = D_j \left(\underbrace{y^{i \circ f} \circ x^{-1}}_{i^{th} \text{ comp of map } \mathbb{R}^m \xrightarrow{y^{i \circ f} \circ x^{-1}} \mathbb{R}^n} \right) (x(p))$$

where x are coords around p & y are coords around $f(p)$.
 (essentially, the rank of Jacobian matrix of $y \circ f \circ x^{-1}$)

If f has rank less than $\dim N = m$ at p , we say p is a critical point. Otherwise p is a regular point. If all $p \in f^{-1}(q)$ are regular pts, q is called a regular value. Otherwise, q is a critical value.

Thm from analysis: If $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a C^1 fcn, [if $n < m$, then all pts are critical].
 Then critical values have measure zero. (Sard's Thm).

Sard's Theorem: Let $f: M \rightarrow N$ be a C^1 map. Assume M has at most countably many old components. Then the critical values of f have measure 0 on N .

- When does a subset of N have measure 0?

1. A subset of \mathbb{R}^n has measure 0 if for any ϵ, \exists a countable set of balls $\{B_i\}$ covering the set with $\sum V(B_i) < \epsilon$.

2. A subset of a metric N has measure zero if \exists a ^{countable} sequence of coords (x_i, U_i) s.t. $A \subset \cup U_i \subseteq X(A \cap U_i) \subseteq \mathbb{R}^n$ has measure 0. w/ this def, Sard's thm will be true whenever it is true for $N = \mathbb{R}^m$ & $M = \mathbb{R}^n$. We will assume this is the case.

• What does a fen look like in coordinates depending on the rank? It depends on whether it has constant rank around a pt or not.

Thm: Let $f: M \rightarrow N$ be a smooth fm.

1. If f has rank k at p , then \exists coordinates (x, U) & (y, V) , $p \in U$ $f(p) \in V$ s.t.

$$y \circ f \circ x^{-1}(a_1, \dots, a_n) = (a_1, \dots, a_k, \phi^{k+1}(a), \dots, \phi^m(a))$$

where ϕ^i are smooth & other than order y can be any coord sys.

2. If the rank is k in a nbhd of p , then coords exist s.t.

$$y \circ f \circ x^{-1}(a_1, \dots, a_n) = (a_1, \dots, a_k, 0, \dots, 0).$$

[i.e. it is just a projection w/ the right coordinates]

Pr: We can assume $M = \mathbb{R}^n$ & $N = \mathbb{R}^m$, b/c this is a local thm.

(1) Let us choose (u, U) & (y, V) around p & $f(p)$, ordered s.t.

$$\det \left(\frac{\partial(y_i \circ f_j)}{\partial u_i} \right) \neq 0, \quad i, j = 1, \dots, k, \quad \text{ie. the top left } k \times k \text{ block of}$$

Jacobian matrix, which has rank k , & therefore has a $k \times k$ minor w/ det $\neq 0 \rightarrow$ so reorder.

Define $x^i = y^i \circ f$, $i = 1, \dots, k$; $x^i = u^i$, $i = k+1, \dots, n$. Is this a coord sys? Is it C^1 rel. to U ? In these coords, is our fen what we want?

$$\text{want? } = \begin{vmatrix} \frac{\partial y^1 \circ f}{\partial u^1} & \dots & \frac{\partial y^k \circ f}{\partial u^k} \\ \vdots & & \vdots \\ \frac{\partial y^1 \circ f}{\partial u^{k+1}} & \dots & \frac{\partial y^k \circ f}{\partial u^{k+1}} \end{vmatrix}$$

The change of variable matrix is given by

$$\begin{pmatrix} \frac{\partial x^i}{\partial u^j}(p) \\ \frac{\partial y^i}{\partial u^j}(p) \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{\partial y^i \circ f \circ g}{\partial u^j}(p) \\ * \\ I \end{pmatrix} \quad \& \quad \frac{\partial x^i}{\partial u^j} = D_j(x^i \circ u^{-1})$$

trans. fn

↑ Jacobian of transition fn - it has full rank k by our choice of x^i .

Thus, by inverse fn thm, this $x^i \circ u^{-1}$ is a diffeomorphism (ie. C^∞ w/ C^∞ inv). So $x \in U$ are C^∞ -rel. \dot{x} is a coord sys \rightarrow the transition fn

are C^∞ -rel. \dot{x} is a coord sys b/c $x = x \circ u^{-1} \circ u$.

[General method - to show smth a coord system, find det of Jacobian] \rightarrow i.e. homeo.

In these coords, what does fn look like?

$$y \circ f \circ x^{-1}(a_1, \dots, a^k) = y \circ f \circ g \text{ of } x(g) = a, \text{ or } x^i(g) = a^i.$$

Thus $y^i \circ f \circ g = a^i$ for $i=1, \dots, k$, by def. of x^i ($= y^i \circ f$), \dot{x}

$$y \circ f \circ x^{-1}(a_1, \dots, a^k) = y \circ f \circ g = (a_1, \dots, a^k, \underbrace{*, \dots, *}_{k+1, \dots, m}).$$

(2) Choose $x \in U$ as in previous. can't say anything. Just smthk

case, s.t. $u \circ f \circ x^{-1}(a) = (a_1, \dots, a^k, \phi^{k+1}(a_1, \dots, \phi^m(a))$.

The rank of f is the rank of the matrix

$$\begin{pmatrix} I & 0 \\ * & \begin{pmatrix} \frac{\partial \phi^k}{\partial a^j} \end{pmatrix} \end{pmatrix} \text{ w/ } 1 \leq k+1, \dots, m, \quad 1 \leq j = k+1, \dots, m.$$

← This block must be zero, we know r.k. $f = k$.
 \hookrightarrow in a nbhd of p

So ϕ^i 's only depend on a^1, \dots, a^k .

So we change u . Choose

$$y^i = v^i, \quad i=1, \dots, k, \quad y^i = v^i - \phi^i \circ v, \quad i=k+1, \dots, m.$$

Check this is a coord sys: Find r.k. of Jacobian!

$$\begin{pmatrix} \frac{\partial y^i}{\partial v^j} \\ * \\ * \\ * \end{pmatrix} = \begin{pmatrix} I & 0 \\ * & I \end{pmatrix}. \text{ So full rank } \Rightarrow \text{ a coord sys, } C^\infty\text{-rel to } v.$$

↑ b/c $\phi^i \circ v$ depends only on v^1, \dots, v^k (as ϕ^i dep only on a^1, \dots, a^k)

In terms of these coords, the for u

$$y_0 \circ x^{-1}(a) = y_0 \circ v^{-1} \circ v \circ f_0 \circ x^{-1}(a) = y_0 \circ v^{-1}(a_1, \dots, a^k, \phi^{k+1}(a), \dots, \phi^m(a))$$

gives above

= q

Call $v(q) = (a_1, \dots, a^k, \phi^{k+1}(a), \dots, \phi^m(a))$

Then $y^i(q) \stackrel{\text{def}}{=} v^i(q) = a^i, i=1, \dots, k.$

$$y^i(q) = v^i(q) - \phi^i(v(q)) = \phi^i(a) - \phi^i(a) = 0, i=k+1, \dots, m$$

↑ $v(q) \neq a$, but same 1st k comp.

ϕ^i dep. only on 1st k comp, so

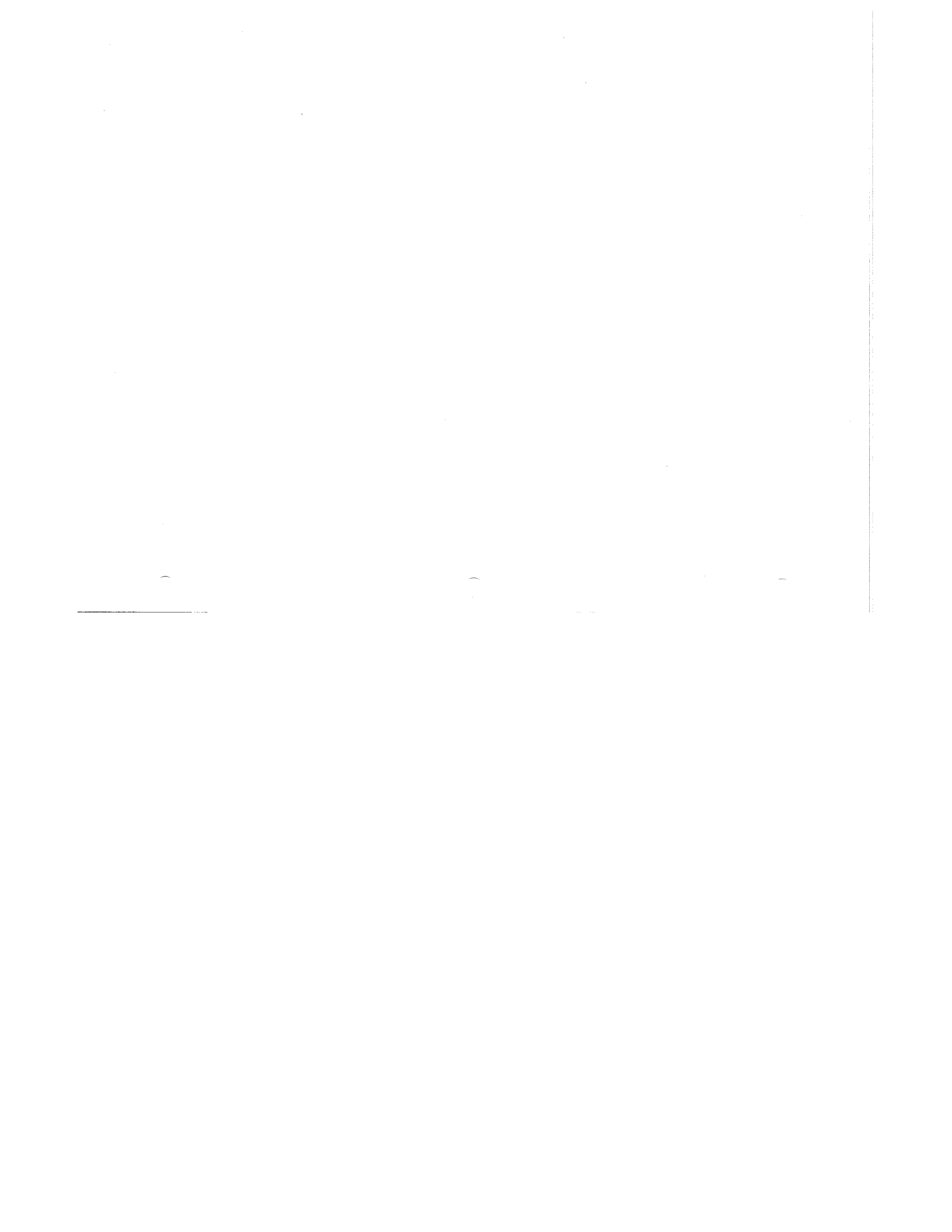
$$\phi^i(v(q)) = \phi^i(a)$$

□

So, $y_0 \circ x^{-1}(a) = (a_1, \dots, a^k, 0, \dots, 0).$

* If full rank, then N really a subset of N , in right coords.
($m > n$)

if $n > m$, then proj. in 1st m coords.



9/9 - Diff. Manifolds $\mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{N}^m$
 $P \rightarrow F(P)$

Def: 1. If $m \leq n$ & $r_k F = m$ at P , then for any coord around $F(P)$ \exists one around P s.t.

$$y \circ f \circ x^{-1}(a^1, \dots, a^m) = (a^1, \dots, a^m)$$

2. If $n = m$ & F has $r_k = n$ at P , then for any coord. around P , \exists one around $F(P)$ s.t.

$$y \circ f \circ x^{-1}(a^1, \dots, a^n) = (a^1, \dots, a^n, 0, \dots, 0)$$

i.e., only need to change one coord (around the one w/ higher r_k) to get this form. Note: This is for max r_k Pans.

Note: Can we assume these r_k 's in nbhd of pt? Yes. Can't go up w/ max. Can't go down ~ there's a mirror w/ $r_k \neq 0$, so \exists open nbhd where that mirror $\neq 0$.

In general, r_k can only increase in a nbhd (always have that $\neq 0$ mirror)

PF: (1) Immediate from their bc we do not need to reorganize coords at beginning (if observing max).

(2) The map has max r_k in nbhd (from note). So, can find $\mathcal{U} \ni P$ s.t. $\forall \phi \circ f \circ \phi^{-1}(a^1, \dots, a^n) = (a^1, \dots, a^n, 0, \dots, 0)$.

But we want any r_k , not specific ϕ .

Assume $\psi \circ f \circ \psi^{-1}(a^1, \dots, a^n) = (b^1, \dots, b^r, 0, \dots, 0)$, where

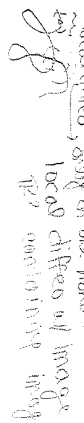
$$r \circ \phi^{-1}(b^1, \dots, b^r) = (a^1, \dots, a^n)$$

$$\text{Define } \lambda(b^1, \dots, b^r) = (r \circ \phi^{-1}(b^1, \dots, b^r), b^{r+1}, \dots, b^m).$$

$$\text{Then } \lambda \circ \psi \circ \psi^{-1} \circ \psi^{-1}(a^1, \dots, a^n) = \lambda \circ r \circ \phi \circ \phi^{-1}(b^1, \dots, b^r) = \lambda(b^1, \dots, b^r, 0, \dots, 0) = (a^1, \dots, a^n, 0, \dots, 0). \quad \square$$

Def: A diff. Pan $F: M \rightarrow N$ is an immersion if the r_k of F is n for any pt $P \in M$.

- locally, an immersion just a proj. in right coords. Locally $\neq 1$, & locally diffed (from inverse Pan than)

Ex: $\mathbb{R} \rightarrow \mathbb{R}^2$ immersion $\begin{matrix} \text{local diffed, orig. in } \\ \text{local diffed of image, but not by subset of } \\ \text{immersion} \end{matrix}$ 

ex A fibro or torus is an immersion, when γ flow becomes dense.



Def: A subset $M \subseteq N$ of a diff. structure (not nec. compatible) is called an immersed submfd of N if the inclusion $i: M \rightarrow N$ is an immersion.

- Not nec. nice - may have different top. & so diff. diff. structure both sides above are immersed submfd's

Def: We say $f: P \rightarrow M$ is an embedding if it is a 1-1 immersion that is homeo to its image (as a subset of M)

- both axes (gnd of dense flow) are not embeddings

Def: An immersed submfd is a C^∞ -submfd if the inclusion is an embedding.

The prev. thm tells us that an immersed submfd is locally the level sets of some coord.

Prop: Let $f: M \rightarrow N$ have constant rk k on a nbhd of a set $f^{-1}(p)$.

ex: $f(x,y,z) = (2x+3y-2z, y-x, 2y+z) = \begin{pmatrix} 2 & 3 & -2 \\ 1 & 1 & 0 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$

$f^{-1}(0,0,0) \leftarrow$ this map on rk of f $\xrightarrow{\text{rk of this}}$ $\begin{pmatrix} 2 & 3 & -2 \\ 1 & 1 & 0 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$

if $\text{rk} = 4, 2\text{-dim'l sp}$ $\xrightarrow{\text{rk + dim subsp = dim space}}$ $\begin{pmatrix} 2 & 3 & -2 \\ 1 & 1 & 0 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$

$= 2, 1\text{-dim'l sp}$

$= 3, \text{pt}$

Then $f^{-1}(p)$ is a closed submfd of M , w/ dim $n-k$. If p is a regular value, then $f^{-1}(p)$ is an $(n-m)$ -submfd.

HW 3 prove this prop. Eube the normal forms we came up w/]

Ex: Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be $f(x) = |x|^2$.

If $a \neq 0$, $f^{-1}(a) = \sqrt{a}$ (max 1) since $\nabla f(x) = 2x$, which is $\neq 0$ if $a \neq 0$.
 Thus, f^{-1} is a regular value & $S^2 = f^{-1}(1)$ is a submanifold of \mathbb{R}^3 .
 \rightarrow If $f(x)$ has max at pt, level sets of f are submanifolds.

Thm 19 Prove that $O(n) = \{A \in GL(n, \mathbb{R}) : A^T = -A\}$ is a submanifold of $GL(n, \mathbb{R})$.
 [$f(A) = A^T A$. Check f has full rank at $I \rightarrow$ computational - it's not a map between spaces]

Q: Is any manifold a submanifold of \mathbb{R}^n for some N ? Yes! But we need a lot of stuff to answer it, particularly partitions of unity.
Preliminaries:

Def: Given an open cover of M , \mathcal{O} , we say \mathcal{O}' is a refinement of \mathcal{O} if \mathcal{O}' is a cover of M & for any $A \in \mathcal{O}'$, $\exists A' \in \mathcal{O}$ w/ $A \subseteq A'$.



Def: The cover \mathcal{O} is locally finite if for any pt x \exists nbhd that intersects only finitely many members of \mathcal{O} .

Thm: Assume M is σ -cpt (i.e. seq of cpt sets s.t. $U = \bigcup U_i$) & we have a metric, it is σ -cpt & ctd. Then, for any open cover of M , we can find a locally finite refinement.

Pr: Let C_1, \dots, C_n, \dots be cpt sets covering M . C_i 's contained in an open set w/ cpt closure U_i (finite union of images of balls covering it - using coords).
 Define U_2 to be open in U_1 .



\rightarrow getting nested open sets w/ cpt closure & $C_i \subseteq U_i$, so they form a cover.

Assume \exists cover \mathcal{O} . Each cpt set $K_i = \overline{U_i} - U_{i-1}$ is covered by \mathcal{O} . Set of \mathcal{O} sets in \mathcal{O} . [Now have countable cover (fin # in each annulus, & countable # of annuli)] Take the intersection of these sets w/ $U_{i+1} - U_{i-3}$ [controlling size of open sets]. This is a refinement, & locally, the nbhd $U_{i+1} - U_{i-3}$ will intersect only fin. many, from construction

The Shrinking Lemma: Let \mathcal{D} be a locally fin. open cover of M .



Can I shrink the cover slightly? w/ open sets whose closures are inside one of \mathcal{D} in cover?

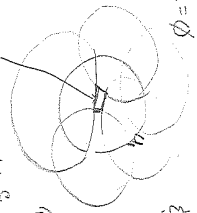
[HAB has countable basis, so \mathcal{D} a countable cover]

Then, for any $U \in \mathcal{D}$ we can choose U' w/ $\bar{U}' \subset U$ & st. $\mathcal{D}' = \{U'\}$ also forms an open cover.

PF: Let $C_1 = M - (U_1 \cup \dots)$ which is a closed set

By Urysohn's Lemma, we can separate C_1 & U_1^c w/ 2 open sets V_1 & V_2 s.t. $V_1 \cap V_2 = \emptyset$ & $U_1^c \subset V_1$, $C_1 \subset V_2$. Therefore,

$C_1 \subset V_2 \subset U_1$ since $V_2 \subset V_1^c \subset U_1$ & V_2^c is already $U_1 \cup U_2 \dots$ is an open cover of M .



Repeat: $C_2 = U_2 - (U_1' \cup U_3 \cup \dots)$.

Separate C_2 from U_2^c & find V_2' s.t. $C_2 \subset V_2' \subset U_2^c$ & substitute U_2 w/ U_2' to still form an open cover. For finite steps, still cover. But what about ∞ steps? Still cover - or do we miss

pt at end? If $p \in M$, \exists max k s.t. $p \in U_k$, b/c \mathcal{D} loc. finite, & $p \in U_1' \cup \dots \cup U_k' \cup U_{k+1} \cup U_{k+2} \dots$, which is a cover, b/c only fin.

many steps. Hence $p \in U_1' \cup \dots \cup U_k'$. \square

Lemma: Let $C \subset U$ be a cpt set contained in an open set. Then \exists a C^∞ fn $f: \mathbb{R} \rightarrow \mathbb{R}$ w/ $f|_C \equiv 1$ & $\text{supp}(f) \subseteq U$.

$$[\text{supp}(f) = \{p \mid f(p) \neq 0\}]$$

Pr: First we claim \exists $g: \mathbb{R}^n \rightarrow \mathbb{R}$ which is C^∞ , positive on $(-z, z)^n$, $g(-z, z) = 0$ & zero outside the cube of side z . For this, let $h: \mathbb{R} \rightarrow \mathbb{R}$ be

$$h(x) = \begin{cases} e^{-(x-1)^2} & x \in (-1, 1) \\ 0 & x \notin (-1, 1) \end{cases}$$



& define $g(x_1, \dots, x_n) = h(x_1/\varepsilon) \dots h(x_n/\varepsilon)$.

Next, for every $p \in C$, we choose coords (x, y) w/ $x \in V \subset \mathbb{R}^n$, $y \in W \subset \mathbb{R}^m$, $x(p) = 0$ and ε s.t. $(\frac{p-y}{\varepsilon}) \in (-1, 1)^n$. Consider $x^{-1}((-z, z)^n)$, for $z = \varepsilon$. Then the

fn $g \circ x^{-1}$ is C^∞ , positive on $x^{-1}((-z, z)^n)$ & zero outside.

We extend it by zeros elsewhere & call it $f_p: \mathbb{R}^n \rightarrow \mathbb{R}$. But C

is cpt, so can cover C w/ a finite # of V 's, $\forall p_i \in C, i=1, \dots, k$ &

consider $\hat{f} = f_{p_1} + \dots + f_{p_k}$. \hat{f} is positive on C , \rightarrow the $x^{-1}((-z, z)^n)$ &

$\text{supp}(f_{p_i}) \subseteq U \Rightarrow \text{supp}(\hat{f}) \subseteq U$. Now we need $\hat{f} = 1$ on C .

Let δ be such that $\hat{f} \geq \delta$ on C . (\exists lower bound $\neq 0$ b/c C cpt)

Let $k: \mathbb{R} \rightarrow \mathbb{R}$ be positive on $(0, \delta)$ & 0 outside:



$$k(x) = \frac{\int_0^x t dt}{\int_0^\delta t dt}$$

Define $f = \hat{f} \circ k \circ \hat{f}$. f is 1 on C & 0 outside U .

\hat{f} is C^∞ , zero for $x \leq 0$, 1 for $x \geq \delta$. We define $f = k \circ \hat{f}$ which is 1 on C (b/c $\hat{f} \geq \delta$ on C) & zero outside U (b/c $\hat{f} = 0$ outside U)

□

Thm: Let D be an open loc. fin. cover of M . Then for each $U \in D$, \exists fin $\phi_U: M \rightarrow [0,1]$ s.t.

(a) $\sum_U \phi_U(p) = 1 \quad \forall p \in M$ (fin. sum b/c D loc. fin.)

PF: ① Assume add $U \in D$ have cpt closure. Use the shrinking lemma to obtain $U' \subseteq \overline{U} \subseteq U$ & define $\psi_U: M \rightarrow [0,1]$ s.t. $\psi_U|_{U'} = 1$ & $\text{supp}(\psi_U) \subseteq U$. Then

$$\sum_U \psi_U > 0 \quad \text{everywhere (i.e. at any } p \in M). \text{ It suffices to define } \phi_U = \frac{\psi_U}{\sum_U \psi_U}.$$

② In general, we will first prove that if $E \subseteq U$ is closed, then there is $\psi_U: M \rightarrow [0,1]$ w/ $\psi_U|_E = 1$, $\text{supp}(\psi_U) \subseteq U$. For this, cover E & $M-E$ w/ open sets w/ cpt supp , w/ those covering E inside U . Call this cover of E \mathcal{C} . Case whole cover \mathcal{C} : Shrink \mathcal{C} (as in 1) to produce a cover \mathcal{D} & define ψ_U , w/ \mathcal{D} as in case 1. Then define

$$f = \sum_{V \in \mathcal{D}} \phi_V \quad \forall V \in \mathcal{C}$$

Then $f > 0$ on E , & $\text{supp}(f) \subseteq U$.

If $p \in E$, the only $V \in \mathcal{D}$ are those that cover E , not $M-E$, thus

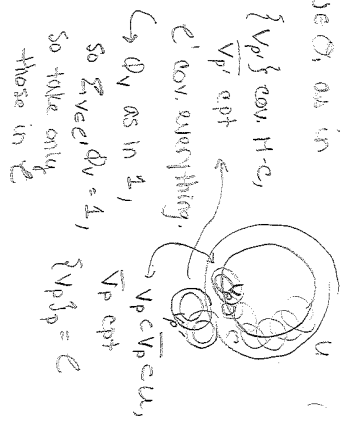
$$\text{for } p \in E, \sum_{V \in \mathcal{C}} \phi_V = \sum_{V \in \mathcal{D}} \phi_V = 1$$

(b/c add other $\phi_V = 0$, b/c $p \notin V$ if $V \in \mathcal{C}'$)

Thus, $f(p) = 1 \quad \forall p \in E$ & $\text{supp}(f) \subseteq U$. Then repeat pf for $M-E$ using f .

Cor (Existence of partitions of unity): Let D be an open cover of M . Then \exists a sequence of C^∞ fcn's $\phi_i: M \rightarrow [0,1]$ s.t.

- (1) $\sum_i \phi_i(x) = 1$ is loc. fin.
- (2) $\sum_i \phi_i(p) = 1 \quad \forall p \in M$
- (3) For each $i \exists U_i \in D$ w/ $\text{supp}(\phi_i) \subseteq U_i$.



The pf is simple: find a refinement of the cover by a loc. fin open cover & apply prev. thm.

The family \mathcal{F} is assumed a partition of unity subordinated to \mathcal{O} refers to (3).

Thm: If M is a cpl C^∞ mfd, then \exists an embedding $M \rightarrow \mathbb{R}^N$ for some N .

Pf: Cover M w/ coord. sys's $(x_i, U_i), \dots, (x_r, U_r)$, shrink the cover to U_i' & let ψ_i be the fns of $\text{supp}(\psi_i) \subset U_i'$ & $\psi_i|_{U_i'} = 1$. Define $f: M \rightarrow \mathbb{R}^{m+r}$

$$f = (\underbrace{\psi_1 x_1, \dots, \psi_r x_r}_{\text{pt in } \mathbb{R}^m}, \underbrace{\psi_1, \dots, \psi_r}_{\in \mathbb{R}}) \quad \text{so } f: M \rightarrow \mathbb{R}^{m+r}$$

1. f has full rk everywhere & it is an immersion.

b/c for each $p \in M$, $\exists \psi_i = 1$ b/c $p \in U_i'$ for some i .
 So that point is just x_i , & that has nontriv. Jacobian \rightarrow i.e. get block of dim n .

2. f is 1-1. Suppose $f(p) = f(q)$. Then $\psi_i(p) = \psi_i(q) \forall i$. If $p \neq q$, $\exists q \in U_i$, b/c $\psi_i(q) = 1 \neq \text{supp}(\psi_i) \subseteq U_i$. Then look at 1st r -coords: $x_i(p) = x_i(q)$, so $p = q$ (b/c x_i is 1-1).

HW 3. Prove f is a homeo w/ its image. Hint: Is this locally an embedding? (this is enough to say globally an emb w/ $\{e_1, \dots, e_n\}$)

HW 1. Let $g: S^n \rightarrow \mathbb{R}P^n$ be the map $p \rightarrow [p]$. Show that $f: \mathbb{R}P^n \rightarrow M$ is C^∞ $\Leftrightarrow f \circ g: S^n \rightarrow M$ is C^∞ . Compose df w/ $rk(df \circ g)$.
 Note: this means diff structure of $\mathbb{R}P^n$ comes from that of S^n

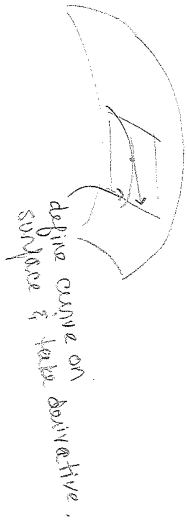
2. Let $f: \mathbb{R}P^2 \rightarrow \mathbb{R}^3$ be the map $g([x, y, z]) = (y^2, x^2, yz)$, whose image is the Steiner surface. Show that g is not an immersion at exactly 6 pts.

[cannot diff w/ (x, y, z) , b/c they are not coords. Need only 2 bc $\mathbb{R}P^2$ is 2-dim]

TANGENT BUNDLE

How does one define the tangent to a manifold? If the manifold is in \mathbb{R}^n it is clear how. Otherwise, it is not so clear.

Surfaces:

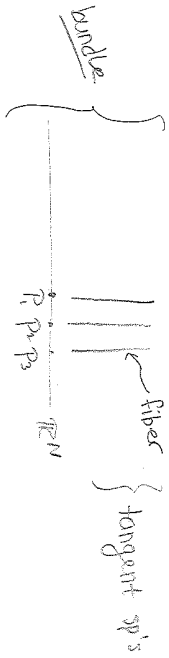


$M \hookrightarrow \mathbb{R}^n$ & then define a curve & take tangent, then $(\dot{p}(t))$ pull it back to M .

→ how do you do this, b/c M on left is not embedded anywhere.

Also, not unique - what if choose diff. N ?
And what is a tangent?

Start w/ \mathbb{R}^n , then move to manifolds. We want to define the tangent "space" that contains all tangent vectors.



On M , have $p \in M$ & curve $\alpha: (-\epsilon, \epsilon) \rightarrow M$ s.t. $\alpha(0) = p$. Then take $\alpha'(0)$ - but what does this mean? we can diff. fcn's $M \rightarrow \mathbb{R}$, but what about $\mathbb{R} \rightarrow M$? Also, many diff. α 's may have same $\alpha'(0)$. So we need to define some equivalence class of curves.

Def: A vector bundle is a quintuple $(E, B, \pi, +, \cdot)$, where E, B are manifolds, $\pi: E \rightarrow B$ is C^∞ & onto, & $\pi^{-1}(p)$ (called the fiber) has the structure of a vector sp of dim n . B is called the base sp, E the total sp. Also, we assume that for any pt $q \in E$, \exists open set $V \ni q$, $P = \pi(q) \in U \text{ s.t.}$

$\forall v \in U \times \mathbb{R}^n$ (local triviality condition)
 \hookrightarrow topologically & smoothly

We say a bundle is trivial if $E = B \times \mathbb{R}^n$.

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Def: A n -vector bundle is a family $(E, B, \pi, +, \cdot)$, where $\omega \in E, B$ are top sp's,

- $\pi: E \rightarrow B$ is cts
- (1) $\pi^{-1}(p)$ is a vect sp of dim n , w/ operations $+, \cdot$
- (2) \exists a cover $\{U_i\}$ of B & maps $f_i: \pi^{-1}(U_i) \rightarrow U_i \times \mathbb{R}^n$, called the trivializations of the vect bundle, s.t. f_i is a homeo &
- $f_i|_{\pi^{-1}(p)}: \pi^{-1}(p) \rightarrow \{p\} \times \mathbb{R}^n$ is an isomorphism ($1-1$ & linear)

Ex: Trivial bundle: $B \times \mathbb{R}^n$ for any top. sp B .

$$\begin{array}{c} \downarrow \pi \\ B \end{array}$$

Def: Two bundles over B, E_1, E_2 , are equivalent if \exists map (the equivalence) $f: E_1 \rightarrow E_2$ s.t. f a homeo & $f|_{\pi_1^{-1}(p)} \rightarrow \pi_2^{-1}(p)$ is an isomorphism. If a bundle is equivalent to $B \times \mathbb{R}^n$, we say it is trivial.

Ex: (1) $TS^1 = \bigcup_{s \in S^1} T_p S^1$, where $T_p S^1$ is unit vector \perp p , counterclockwise.

Then $T_p S^1 = \{ \lambda \vec{u}_p \mid \lambda \in \mathbb{R} \}$. Define

$$f: T S^1 \rightarrow S^1 \times \mathbb{R}$$

$$\vec{v}_p \mapsto (p, \lambda), \quad \vec{v}_p = \lambda \vec{u}_p$$

Let \vec{u}_p be the

$$\pi: \bigcup_p T_p S^1 \rightarrow S^1$$

(cts w/ this top)

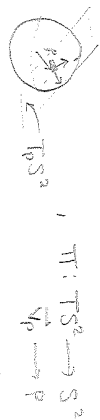
But what's the top on TS^1 ? Choose it s.t. f is cts, i.e. the open sets are the f^{-1} preimages of open sets in $S^1 \times \mathbb{R}$. With this top, f is $1-1$ & a homeomorphism. This makes π cts (b/c $\pi = (proj)_1 \circ f$, both cts).

$f: T_p(S^1) \rightarrow \{p\} \times \mathbb{R}$

$$\vec{v}_p + \vec{w}_p \mapsto \lambda + \lambda' \Rightarrow f \text{ linear on } \pi^{-1}(p). \text{ (}\lambda, \lambda' \in \mathbb{R}\text{)}$$

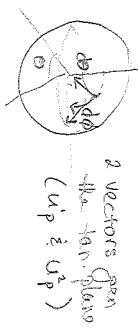
Thus, TS^1 is trivial.

(2) $TS^2 = \bigcup_p T_p S^2$, $T_p S^2$ is



This is locally trivial: take basis at p - can move this basis smoothly to pts nearby. (ie. choose smooth family) - 2 tan vectors: diff in direction of $\theta \in \text{dir. of } \phi$, from spherical coords, those 2 vectors are the basis.

Then $T_p S^2 = \{ \forall p = \lambda u_p + \mu v_p \mid \lambda, \mu \in \mathbb{R} \}$



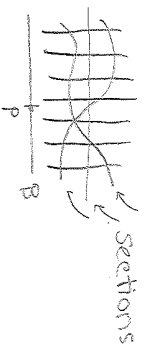
$\epsilon: \pi^{-1}(u) \rightarrow U \times \mathbb{R}^2$

$\forall p \mapsto (p, \lambda, \mu) \Rightarrow$ if have a smooth family of gens, we can always locally trivialize.

Thus TS^2 is a vector bundle.

Assume TS^2 is trivial: $TS^2 \xrightarrow{f} S^2 \times \mathbb{R}^2$. Then, $\forall v \neq 0$: $v \in \mathbb{R}^2$, consider $f^{-1}(S^2 \times \{v\})$ (ie. pulling back v to each pt of S^2) & $f^{-1}(f(v)) \neq \emptyset$. This gives a smooth vector field on S^2 , which contradicts the hairy ball thm. Thus f DNE.

Visualization of bundle:



Def A section of a vector bundle (E, B, π) is a continuous map $S: B \rightarrow E$ s.t. $\pi \circ S(p) = p$. [ie. $S(p) \in \pi^{-1}(p)$]

* For $B = S^2$, every section of the tangent needs to vanish somewhere, to not contradict hairy ball thm.

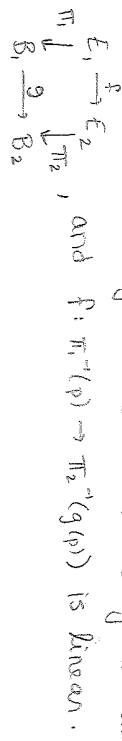
Ex: (3) $B = \mathbb{R}^n$, $\widehat{TP}^n = \bigcup_{p \in \mathbb{R}^n} T_p \mathbb{R}^n$, where $T_p \mathbb{R}^n = \{ \alpha^i(t) \mid \alpha^i: (-\epsilon, \epsilon) \rightarrow \mathbb{R}^n, \alpha^i(0) = p \}$.

$T_p \mathbb{R}^n$ is a vector sp (can add α^i 's, $(\alpha + \beta)^i(t) = \alpha^i(t) + \beta^i(t)$, $(\lambda \alpha)^i(t) = \lambda \alpha^i(t)$)

$\widehat{TP}^n = \mathbb{R}^n \times \mathbb{R}^n$ (ie. trivial), Top. of \widehat{TP}^n is top. of $\mathbb{R}^n \times \mathbb{R}^n$. $\forall p \mapsto (p, \text{coords of } v_p \text{ w.r.t. } \{e_i\})$ * If $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$, \exists an induced map $f_*: T_p \mathbb{R}^n \rightarrow T_p \mathbb{R}^n$ (ie. $f_*(\alpha^i(t)) = (f \circ \alpha)^i(t) \in T_{f(p)} \mathbb{R}^n$, (ie. mult. α^i by $J_{f(p)}$)

Thm: For every n -mfld M , \exists an n -vector bundle TM over M (called the tangent bundle) & a bundle map (π, f) for any map $f: M \rightarrow N$, M, N mflds.

Def: A bundle map (f, g) from (E_1, B_1, π_1) to (E_2, B_2, π_2) is a pair of maps $f: E_1 \rightarrow E_2$, $g: B_1 \rightarrow B_2$ s.t. the diagram commutes



$$V = \alpha^{-1}(0), \quad \alpha: (\cdot, \varepsilon, \varepsilon) \rightarrow M$$

$$(x, \alpha)'(0) = v \quad \left\{ \begin{array}{l} \text{vectors} \\ \text{in } \mathbb{R}^n \end{array} \right. \xrightarrow{g} \mathbb{R}^n$$

$$(y, \alpha)'(0) = \omega \quad \left\{ \begin{array}{l} \text{vectors} \\ \text{in } \mathbb{R}^n \end{array} \right. \xrightarrow{h} \mathbb{R}^n$$

$$\omega = D(y \circ \alpha^{-1})'(x(p))v \quad \text{b/c } (y \circ \alpha^{-1} \circ x \circ \alpha)'(0) = (y \circ \alpha)'(0)$$

Want this to be our equivariance relation. diff: & apply chain rule \rightarrow get eqn on left

Prf: (a) We say $(x, v) \sim_p (y, \omega)$ if $\omega = D(y \circ \alpha^{-1})(x(p))v$, w/ $x \neq y$ coordinates around $p \in V \subseteq \omega \in \mathbb{R}^n$. This is an equivalence rel.

Let $[(x, v)]_p$ be the class of (x, v) .

(b) Define $TM = \{ [(x, v)]_p \mid x \text{ a coord, } v \in \mathbb{R}^n \}$.

$$TM = \bigcup_{p \in M} T_p M.$$

$$(c) \quad \pi^{-1}(p) \rightarrow [(x, v)]_p + [(y, \omega)]_p$$

$$= [(x, v)]_p + [(x, D(x \circ \alpha^{-1})(y(p))\omega)]_p$$

} change so both are in same coord. Note: both coord. around p , so must be overlap of coords

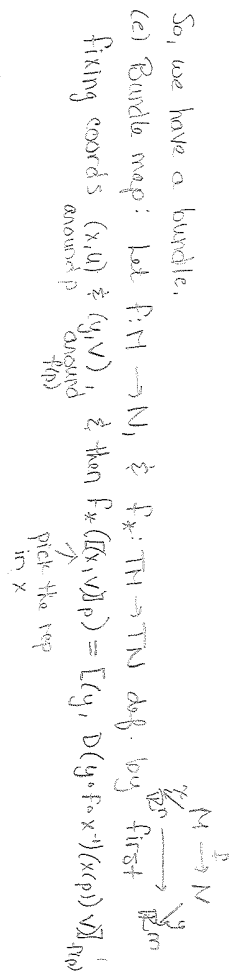
$$= [(x, v + D(x \circ \alpha^{-1})(y(p))\omega)]_p$$

$$\rightarrow \lambda [(x, v)]_p = [(x, \lambda v)]_p \Rightarrow \pi^{-1}(p) \text{ a vect. sp}$$

(d) Trivializations: Fix (x, u) & define $t_x: \pi^{-1}(u) \rightarrow U \times \mathbb{R}^n$
 $[(x, v)]_p \rightarrow (p, v)$

We want this to be cts, so let top on TM be the preimages of open sets in $U \times \mathbb{R}^n$. As before, this implies π is cts.

So, we have a bundle.



Need to check f_* is \mathbb{R} - \mathbb{R} linear. Assume we choose $(\hat{x}, \hat{v}), (g, \hat{v})$.

$$\begin{aligned} f_*([\mathbb{R}x, \mathbb{R}v]_p) &= f_*([(\hat{x}, D(\hat{x} \circ x^{-1})(x(p))v)]_p) \\ &= [g, D(g \circ f \circ \hat{x}^{-1})(\hat{x}(p))D(\hat{x} \circ x^{-1})(x(p))v]_{f(p)} \\ &= [g, D(\hat{g} \circ f \circ x^{-1})(x(p))v]_{f(p)} \\ &= [g, D(g \circ f \circ x^{-1})(x(p))v]_{f(p)} \\ &= [g, D(g \circ f \circ x^{-1})(x(p))v]_{f(p)} \end{aligned}$$

Then check the following properties of bundle maps: \square

Properties of Bundle Maps:

- (1) $(\mathbb{1}_M)_* = \mathbb{1}_{TM}$
- (2) If $f: M \rightarrow N$, $g: N \rightarrow \mathbb{R}$, then $(g \circ f)_* = g_* \circ f_*$.
- HW \rightarrow (3) \exists bundle equivalence between $TM \times \mathbb{R}^n$ & $\widehat{TM} \times \mathbb{R}^n$
- (4) If $U \subseteq M$, then $TM|_U \sim TM|_u$, U is open, $\hat{g}: TM \rightarrow N$, $(f|_U)_* = (f_*)|_{TM}$.

$$\bigcup_{p \in U} TM$$

\mathbb{R}^n maps $M \rightarrow \mathbb{R}^m$

Derivations of $P: D_p M = \{ \lambda_p: \mathbb{C}^\infty(M, \mathbb{R}) \rightarrow \mathbb{R} \mid \lambda_p \text{ linear and mult. by } f \}$

i.e. $\lambda_p(fg) = \lambda_p(f) + \lambda_p(g) \neq \lambda_p(fg) = \lambda_p(f) \cdot \lambda_p(g)$, \neq
 $\lambda_p(fg) = f(p)\lambda_p(g) + \lambda_p(f)g(p)$

$D_p M$ is a vector sp. What is $\dim D_p M$?

Note (1) $\lambda_p(f)$ depends only on the value of f on a nbhd of p . We will see that if $f \equiv g$ on a nbhd of p , then $\lambda_p(f) = \lambda_p(g)$. First, $f \equiv 0$ on a nbhd of p . Then, $f^{-1}(0)$ contains a nbhd U of p .

Let h be s.t. $\text{supp}(h) \subseteq U \neq h(p) = 1$. Then $(hf)(q) = 0 \forall q$.

$0 = \lambda_p(hf) = h(p)\lambda_p(f) + f(p)\lambda_p(h) = \lambda_p(f)$
 b/c linear maps take 0 to 0

If $f \equiv g$ on a nbhd of p , then $0 = \lambda_p(\underbrace{f-g}_{0 \text{ on nbhd of } p}) = \lambda_p(f) - \lambda_p(g) \checkmark$

(2) From here, we conclude that we can apply derivations of P to fns that are only locally defined, $f: U \rightarrow \mathbb{R}$, $p \in U$. (b/c we can extend it using h as above)

Thm: $\dim D_p M = n$. If (x_i, u_i) are local coords, then a basis for $D_p M$ is $\left\{ \frac{\partial}{\partial x_i} \Big|_p \right\}_{i=1, \dots, n}$ and $\lambda_p = \sum_{i=1}^n \lambda_p(x_i) \frac{\partial}{\partial x_i} \Big|_p$.

Pr: (1) $\lambda_p(1) = \lambda_p(1 \cdot 1) = \lambda_p(1) + \lambda_p(1) \Rightarrow \lambda_p(1) = 0$. Also,

$\lambda_p(0) = 0 \lambda_p(1) = 0$

(2) Assume $M = \mathbb{R}^n \ni p = 0$. We write $f^{(a)} = f(a) + \sum_{i=1}^n g_i^{(a)} e_i$, w/ $D_i g_i(a) = D_i f(a)$. [we can do $\int_{t=0}^1 D_i f(t a) dt$]

thus from analysis: $g_i^{(a)} = \int_0^1 D_i f(t a) dt$
 $\Rightarrow \lambda_p(f) = \sum_{i=1}^n \lambda_p(e_i) \cdot g_i(0)$, $\neq g_i(0) = \int_0^1 D_i f(a) dt = D_i f(a)$

So for $M = \mathbb{R}^n$, we have $\lambda_p(f) = \sum_{i=1}^n \lambda_p(e_i) \cdot \frac{\partial f}{\partial x_i} \Big|_0$

(3) Now consider a general mfd M , \neq let $\lambda_p \in D_p M$. Let $x_i: U \rightarrow \mathbb{R}^n$. Define $\lambda_{p \circ x_i} = \lambda_p(x_i)$. $\lambda_{p \circ x_i}$ is a derivation, \neq $\lambda_p = \sum_{i=1}^n \lambda_{p \circ x_i}$ we apply part (2).



Then $\mathcal{L}_p(g \circ x) = \sum \mathcal{L}_{p \circ (e_i)} \frac{\partial x_i}{\partial e_i} \Big|_{x(p)=0}$

$\mathcal{L}_{p \circ (e_i)} = \mathcal{L}_p(e_i \circ x) = \mathcal{L}_p(x_i)$

If $F = g \circ x$, then $\frac{\partial F}{\partial x_i} \Big|_{x(p)} = D_i(g)(x(p)) = D_i(g \circ x^{-1})(x(p)) = \frac{\partial F}{\partial x_i} \Big|_p$,

So $\mathcal{L}_p(F) = \sum \mathcal{L}_p(x_i) \frac{\partial F}{\partial x_i} \Big|_p$.

□

What is the relationship between $D_p M \hat{=} T_p M$?

• $D_p M$ forms a bundle:

$$DN = \bigcup_p D_p M \xrightarrow{\pi} M$$

$$\mathcal{L}_p \longrightarrow p$$

$$\bigcup_{p \in U} D_p(M) \longrightarrow U \times \mathbb{R}^n$$

$$\mathcal{L}_p = \sum_p \mathcal{L}_p(x_i) \frac{\partial}{\partial x_i} \Big|_p \longmapsto (p, (\mathcal{L}_p(x_i)))$$

linear in each fiber by construction.
Choose the topology that makes this cts, which then makes π cts.

Given $f: M \rightarrow N$, $f_*: DN \rightarrow DN$, $(g: N \rightarrow \mathbb{R})$.

$(f_*(\mathcal{L}_p))(g) = \mathcal{L}_p(g \circ f)$

• $DN \approx TM$.

Fix coordinates. $h(p_0) = [x_i, (\mathcal{L}_p(x_i))]$. Linear map

$TM = [T(x_i)]_p$
 $\uparrow h$
 $DN = \{ \mathcal{L}_p = \sum \mathcal{L}_p(x_i) \frac{\partial}{\partial x_i} \Big|_p \}$

the mapping coeffs in basis to coeffs in basis, so cts a bundle equivalence.

What is $\alpha'(0)$, $\gamma: \mathbb{R} \rightarrow M$? [w/ $\alpha(0)=p$]

On \mathbb{R} , $\frac{d}{dt}$ generates the tangent (at each fiber, it's just \mathbb{R}).

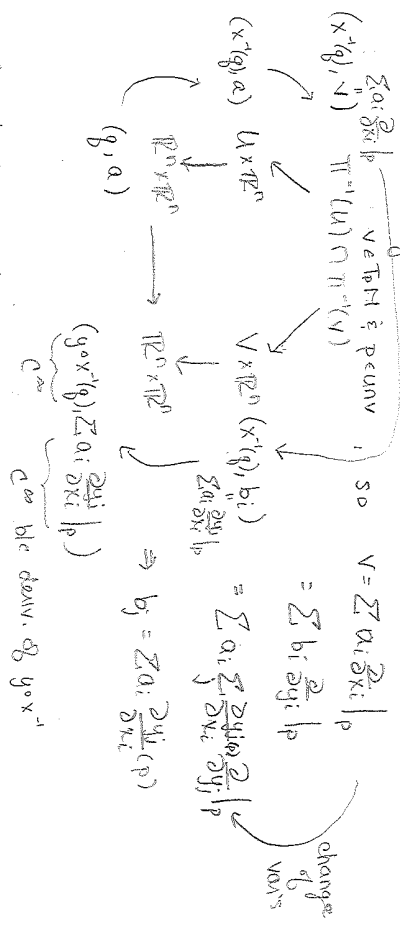
Define $\alpha'(0) \in T_p M$ st. $\alpha'(0) = \alpha_* \left(\frac{d}{dt} \Big|_0 \right)$.

vector at 0, so α_* gives vector at p .

TM has a C^∞ structure:

Choose coords for TM Given an atlas (x, U) on M , define coords for TM given by $(\pi^{-1}(U), (x \circ \pi) \circ t_x)$, where t_x is the n -trivialization, $t_x: \pi^{-1}(U) \rightarrow U \times \mathbb{R}^n$

These form an atlas of TM, & so $\dim TM = 2n$. (n for pt & n for vector)
 So TM is a mfd. We'll check that transition maps are C^∞ . Key one:



So, $(q, a) \mapsto (y \circ x^{-1}(q), \sum a_i D_i(y \circ x^{-1})(q))$ is C^∞ b/c each piece is.

Def: A section of TM is called a vector field. \bar{X}_p is a derivation on $C^\infty(M, \mathbb{R})$, b/c in coords, $\bar{X}_p = \sum \bar{X}_p(x^i) \frac{\partial}{\partial x^i} |_p$. So we represent a vector field locally as:

$$\bar{X} = \sum a^i \frac{\partial}{\partial x^i} \text{ where } a^i \text{ are fns on } U, a^i: U \rightarrow \mathbb{R}.$$

Since \bar{X}_p is a derivation, then $\bar{X}(f \cdot g) = f \bar{X}(g) + g \bar{X}(f)$ in the ring of fns.

$$\bar{X}: C^\infty(M, \mathbb{R}) \rightarrow \text{Hops}(M, \mathbb{R}), \bar{X}(f)(p) = \bar{X}_p(f).$$

Def: \bar{X} is C^∞ if $\bar{X}(f)$ is C^∞ for any f in C^∞ . This def. is equiv. to saying \bar{X} is C^∞ as a section, b/c \bar{X} is C^∞ mfd. Equiv. to \bar{X} is C^∞ as a section, b/c \bar{X} is C^∞ mfd.

ie, for any coordinates (x, y) , $\bar{x} = \sum a^i \frac{\partial}{\partial x_i}$ w/ $a^i \in \mathbb{C}^\infty$
in the above

$$\text{So, } \bar{x}: \mathcal{C}^\infty(M, \mathbb{R}) \rightarrow \mathcal{C}^\infty(M, \mathbb{R}).$$

Orientability

Given a vector sp. V :

• Start w/ \mathbb{R}^n basis $\{v_1, \dots, v_n\}$. $\det(v_1, \dots, v_n) > 0$, choose one to be < 0
positive orientation, other to be negative orientation. Then
for any vector, just take det.

If $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a linear map, $f(v) = Av$, & $\det A > 0$, we
say f preserves the orientation. Obs, it reverses it.

• Do same thing in general vect sp, after fix a basis.

On a mfd, can choose an orientation for each vect. sp (b/c there's
one at each pt). But how do we compare the or. for diff
vect. sp's?

Orientability

Def: A manifold M is orientable if there exists an atlas \mathcal{A} s.t. if $(x, U), (y, V) \in \mathcal{A}$, then $\left(\frac{\partial y_i}{\partial x_j} \right) (p)$ has positive det. $\forall p \in U \cap V$.

Note: $y \circ x^{-1}$ is a diffeomorph, so the det. never changes sign, so suffices to check one $p \in U \cap V$ in each comp.

$D_j(y_i \circ x^{-1})(x(p))$
= Jacobian of transition fn

* Like a continuity of orientations than charts. \hookrightarrow b/c matrix has full rank $\Rightarrow \det \neq 0$ $\forall p$.

The matrix $(D_j(y_i \circ x^{-1}))$ defines the change of coord. for the tan. bundle:

$$\begin{aligned} t_x : \pi^{-1}(U) &\rightarrow U \times \mathbb{R}^n \\ t_y : \pi^{-1}(V) &\rightarrow V \times \mathbb{R}^n \end{aligned} \quad \left. \begin{array}{l} \text{these give the coords on TM} \\ \text{after comparing w/ } x \times \mathbb{R}^n \text{ (} y \times \mathbb{R}^n \text{)} \end{array} \right\}$$

$$t_y \circ t_x^{-1}(q, a) = (y \circ x^{-1}(q), (D_j(y_i \circ x^{-1})(q))a)$$

When we fix a fiber, this is a linear map:

$$t_x : \underbrace{\pi^{-1}(p)}_{= \mathbb{R}^n} \rightarrow \mathbb{R}^3 \times \mathbb{R}^n. \quad \text{This relates or. in } \mathbb{R}^n \text{ to}$$

or in $\mathbb{R}^3 \times \mathbb{R}^n \xrightarrow{\text{then}}$ either preserved or reversed or t_x on its \mathbb{R}^n is so invertible. (after or's are fixed in each)

* At each fiber, b/c $D_j(y_i \circ x^{-1})(q)$ has pos. det, then t_y either pres. or rev. or, in same way as t_x :

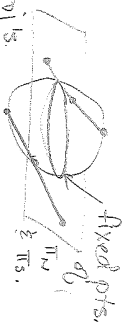
$t_y \circ t_x^{-1}$ pres or, $\&$ $t_y = t_y \circ t_x^{-1} \circ t_x$, so t_y does same thing to or as t_x

Ex: (a) \mathbb{R}^2 is or.

(1) S^n is or.:

Atlas from N proj. $\hat{=}$ S proj

Let $\pi_N \hat{=} \pi_S$ be the 2 stereographic proj's



For $p \in$ equator, $\pi_N \circ \pi_S^{-1}(p) = p$. [recall, we only need to choose one pt, so we choose a fixed pt] But, we need the Jacobian; so we need to do calculations. Yuck. So we use the other def.

Consider $S^2 \hookrightarrow \mathbb{R}^{m+1}$ $\hat{=}$ let's define an or. on $T_p S^n$.

If $\{v_1, \dots, v_n\}$ span $T_p S^n$, we say they are pos. or. if

$\{p, v_1, \dots, v_n\}$ are pos. or. in \mathbb{R}^{m+1} .



(2) Möbius band is non-or.

Assume we have an or. on Möbius band.

coordinates: $f: [0, 2\pi] \times (-1, 1) \rightarrow \mathbb{R}^3$

$$(\theta, t) \mapsto (2 \cos \theta + t \cos \frac{\theta}{2}, 2 \sin \theta + t \cos \frac{\theta}{2}, t \sin \frac{\theta}{2})$$

Choose $t=0$, which gives a loop. (choose $t=0$ w/c z -axis)

$$f_{\theta}^{(0,0)} = (-2 \sin \theta, 2 \cos \theta, 0)$$

$$f_{\theta}^{(0,0)} = (\cos \frac{\theta}{2}, \cos \frac{\theta}{2} \sin \theta, \sin \frac{\theta}{2})$$

$$f_{\theta}(2\pi, 0) = f_{\theta}(0, 0) = (0, 2, 0)$$

$$f_{\theta}(0, 0) = (1, 0, 0) \text{ but } f_{\theta}(2\pi, 0) = (-1, 0, 0)$$

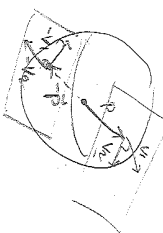
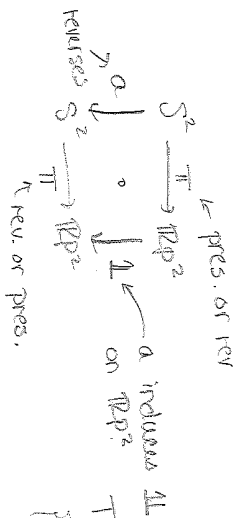
but one dot is +, other dot is - , so it is not possible to orient.

(3) $\mathbb{R}P^2$ is not or.

2/3

Consider $S^2 \xrightarrow{\alpha} S^2$. $T_p S^2 \xrightarrow{d\alpha_p} T_p S^2$ \neq $\mathbb{R}^3 \xrightarrow{\alpha} \mathbb{R}^3$
 $p \mapsto -p$ $v \mapsto -v$ (depend α to $\mathbb{R}P^2$)

So $\alpha_* (\{p, v_1, v_2\}) = \{-p, -v_1, -v_2\} \Rightarrow \alpha_*$ rev. or. of S^2
 gives or on S^2



Thus $\mathbb{1}$ $\mathbb{R}P^2$ or, either
 {pres = rev \circ pres. or
 rev = rev \circ rev } or
 $\mathbb{1}_{\mathbb{R}P^2}$ rev. or $\mathbb{1}$.

(4) $\mathbb{R}P^3$ is or.

Follows same argument, but now $\{p, v_1, v_2, v_3\}$, & α_* actually preserves or. It's or is inherited from S^3 .

Tensor Bundles

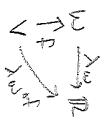
Def: V^* is the dual vector sp to V if

$$V^* = \{ \lambda: V \rightarrow \mathbb{R} \mid \lambda \text{ linear map} \}$$

with the usual operations +, ..

If $f: V \rightarrow W$ is linear, $f^*: W^* \rightarrow V^*$ is the dual map to f

$$f^*(\lambda \circ f)(v) = (\lambda \circ f)(f(v))$$



Properties:

- (1) $\mathbb{1}_V^* = \mathbb{1}_{V^*}$
- (2) f^* is linear
- (3) $(f \circ g)^* = g^* \circ f^*$

$\dim V = \dim V^*$ Given a basis $\{v_1, \dots, v_n\}$ for V , \exists a dual basis $\{v_1^*, \dots, v_n^*\}$ of V^* as the linear maps sat.

$$v_i^*(v_j) = \delta_{ij}$$

$\rightarrow V$ can be identified w/ V^* but not in a natural way, i.e. we need a basis to do it. V can be naturally identified with $(V^*)^*$.

If $v \in V$, then $f_v \in (V^*)^*$ is defined by $f_v(\lambda) = \lambda(v)$

Def: Let $S = (E, B, \pi)$ be a bundle. Then the dual bundle is $S^* = (E^*, B, \pi^*)$, where $E^* := \bigcup_{p \in B} (\pi^{-1}(p))^*$. [Since $E = \bigcup_{p \in B} \pi^{-1}(p)$ vector sp's]

$\xi: \pi^*: E^* \rightarrow B$
 $\lambda_p \rightarrow p$
 $(\pi^{-1}(p))^*$

Note: The fibers are maps on vector sp's.

Why is this a bundle?

- Assume we have local trivializations for S :

$$t: \pi^{-1}(U) \rightarrow U \times \mathbb{R}^n$$

At each fiber, $t: \pi^{-1}(p) \rightarrow \{p\} \times \mathbb{R}^n$ is linear ξ an isomorphism.

So $t^*: \{p\} \times (\mathbb{R}^n)^* \rightarrow (\pi^{-1}(p))^*$. Since this is an \cong , we can invert it:

by fixing a basis (the same one everywhere)

$$(t^*)^{-1}: (\pi^{-1}(p))^* \rightarrow \{p\} \times \mathbb{R}^n. \text{ Define } \hat{t}, \text{ the triv. for the dual}$$

$$\text{as } \hat{t}: (\pi^*)^{-1}(U) \rightarrow U \times \mathbb{R}^n \quad \hat{t}|_{(\pi^*)^{-1}(p)} = (t^*)^{-1}$$

- GWS bk t is.

Set the topology in E^* that makes \hat{t} continuous. Then π^* will also be ats (bc compose \hat{t} w/ projection)

In general, $S \neq S^*$ (not equiv. as bundles) — although usually so. But $S \cong (S^*)^*$, using the natl ident of $V \cong (V^*)^*$.

If $E = TM$, then $E^* = T^*M$ is called the cotangent bundle.

Cotangent bundle $T^*M = \cup_{p \in M} (T_p^*M)^*$

* Ex: Check T^*M is a C^∞ -mfd.

Identical to what we did for TM - use local trivializations:

for U $(\tau_U^*)^{-1}: T_U^*M \rightarrow U \times \mathbb{R}^n \xrightarrow{\text{identity}} \mathbb{R}^n \times \mathbb{R}^n$ gives coordinates.

Then check the transition fens.

For TM ; $(g, d) \xrightarrow{\text{coeffs of vectors}} (g \circ \tau_U^{-1} [D(\tau_U \circ \tau_V^{-1})] \alpha)$ is the transition fen. For T^*M , get inverse transpose of Jacobian.

→ Do this for any bundle, w/ \mathbb{R}^n replaced w/ V , a vect sp, which we identify w/ \mathbb{R}^n by choosing a basis.

Def: A section of T^*M is called a 1-form,

$\omega: M \rightarrow T^*M$.

Ex: $f: M \rightarrow \mathbb{R}$, then we define the 1-form $df(p) \in (T_p M)^*$ as

$df(p)(\vec{X}_p) = \vec{X}_p(f)(p)$
any of tang. vectors, so a vector field.
vec. field applied to fcn ω .
differentiation.

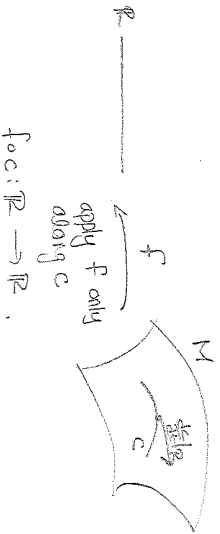
↳ fen from tan. vect. (i.e. vect. field) to \mathbb{R} .

Ex: let $c: (-\epsilon, \epsilon) \rightarrow M$ be a curve w/ $c(0) = p$. Recall

$\frac{dc}{dt}|_p = c_*(\frac{\partial}{\partial t}|_0)$.

So $df(p)(\frac{dc}{dt}|_p) = df(p)(c_*(\frac{\partial}{\partial t}|_0)) = c_*(\frac{\partial}{\partial t}|_0)(f) \circ c$

$= \frac{d}{dt}|_0(f \circ c)$
Shown before.



Let (x_i, U) be coordinates around $p \in M$.

$T_p M$ is gen. by $\{\frac{\partial}{\partial x_i}|_p\}$. Call $\{dx_i(p)\}$ the dual basis to $\{\frac{\partial}{\partial x_i}|_p\}$.

$$dx_i(p) \left(\frac{\partial}{\partial x_j} \Big|_p \right) = \delta_{ij}, \text{ the dual basis.}$$

Form dual form above δ_{ij}

So $dx_i(p)$ not just a name. They are the same differentials (1-forms) as in the exs above.

Since $\{dx_i(p)\}$ are a basis, given any section ω , we can write it as $\omega(p) = \sum \omega_i(p) dx_i(p)$.

On U we can write

$$\omega = \sum \omega_i dx_i, \text{ where } \omega_i \text{ are fns } \&$$

$\omega_i \& dx_i$ are sections.

Def: We say ω is C^0 if ω_i are C^0 for an atlas covering M .

Thm: Let (x_i, U) be coords, f a C^1 fn. Then

$$df = \sum_{i=1}^n \frac{\partial f}{\partial x_i} dx_i. \quad [\text{Recall, } \frac{\partial f}{\partial x_i} = D_i(f \circ x^{-1})]$$

Pf: Let \bar{x}_p be a vector $\bar{x}_p = \sum \bar{x}_p(x_i)(p) \frac{\partial}{\partial x_i} \Big|_p$. [Recall, for a derivation, we have $\rho = \sum \rho(x_i) \frac{\partial}{\partial x_i}$].

$$= \sum dx_i(p) \left(\bar{x}_p \right) \frac{\partial}{\partial x_i} \Big|_p, \text{ so}$$

$$df(p) = \sum_i dx_i(p) \left(\bar{x}_p \right) \frac{\partial f}{\partial x_i} \Big|_p = \left(\sum_i \frac{\partial f}{\partial x_i} \Big|_p dx_i(p) \right) (\bar{x}_p)$$

* differential applied to vector to get 1-form applied to form

Let $f: M \rightarrow N$. We know we have $f_*: TM \rightarrow TN$. But we do not have $f^*: \dots$:

$f_*: TM \rightarrow TN$ is a linear map, so we can dualize

$$f^*: (T^*_p N)^* \rightarrow (T^*_p M)^*$$

but f may not be inj or surj. Thus f^* does not exist if f is not 1-to-1. [If not surj, can define f^* restricted to $T^*(f(M))$].

But we can naturally pullback sections. Let $\omega: N \rightarrow T^*N$ be a section. Then we define $f^*\omega: M \rightarrow T^*M$ by

$$f^*\omega(p)(\bar{X}_p) = \underbrace{\omega(f(p))}_{\in T^*_p N} \left(\underbrace{f_* \bar{X}_p}_{\in T_p M} \right), \text{ which is a section on } M. \text{ If}$$

$\omega \in T^*N$ is C^k , $f^*\omega$ is C^k .

Ex: (1) $f^*(dg) = d(g \circ f)$ because:

$$f^*(dg)(\bar{X}_p) = dg(f_* \bar{X}_p) = (f_* \bar{X}_p)(g) = \bar{X}_p(g \circ f) = d(g \circ f)(\bar{X}_p)$$

Tensors

Def: A vector field is called a contravariant v.f. & a 1-form is called a covariant v.f.

1-form $\rightarrow dy_i = \sum_j \frac{\partial y_i}{\partial x_j} dx_j$ ← way to change a basis in \mathbb{R}^n , so called covariant

If $\omega = \sum_i \omega_i dx_i$, then $\omega_j = \sum_k \omega_k \frac{\partial x_k}{\partial y_j}$

Vect. field $\rightarrow \frac{\partial}{\partial y_i} = \sum_j \frac{\partial x_j}{\partial y_i} \frac{\partial}{\partial x_j}$ ← opp way to change a basis in \mathbb{R}^n , so called contravariant reciprocal than for dy_i

Def: Let $T: V_1 \otimes \dots \otimes V_k \rightarrow \mathbb{R}$ be a multilinear map (ie linear in each entry).

Define $T^k(V)$ to be the vector sp. of such maps,

so $T^k(V) = V^{\otimes k}$. Elts of $T^k(V)$ are called k-tensors.

Given $f: V \rightarrow W$ linear, we define $f^*: T^k(W) \rightarrow T^k(V)$

$$f^*(T) = T \circ (f \times \dots \times f)$$

Assume $T \in T^k(W) \neq 0 \in T^k(V)$. Then $T \otimes S \in T^{k+r}(V)$, $\neq 0$

$T \otimes S(V_1, \dots, V_k, V_{k+1}, \dots, V_{k+r}) = T(V_1, \dots, V_k) \cdot S(V_{k+1}, \dots, V_{k+r})$. (This product is a multilinear map, so

$$\otimes: T^k(V) \times T^r(V) \rightarrow T^{k+r}(V).$$

\otimes is non commutative

\otimes is associative

Basis for $T^k(V)$: Assume $\{v_1, \dots, v_n\}$ is a basis for V . Take

$\{v_1^{\otimes k}, \dots, v_n^{\otimes k}\}$, which are 1-tensors, so $v_1^{\otimes k} \otimes \dots \otimes v_k^{\otimes k}$ is a k-tensor.

But $v_1^{\otimes k} \otimes \dots \otimes v_k^{\otimes k}$ is also a k-tensor, which is not a multiple. So a basis would be $\{v_1^{\otimes k} \otimes \dots \otimes v_k^{\otimes k}\}$, where $i_j = 1, \dots, n$, $j = 1, \dots, k$.

So $\dim T^k(V) = n^k$

Given a manifold M , define the k-covariant tensor bundle to be

$$T^k(M) = \bigcup_{p \in M} T^k(T_p M).$$

$$\downarrow \pi \text{ (takes fiber to } p \text{)}$$

$$M$$

Trivializations: Let (x, U) be coords on M

$T^k_{\text{diff}} \cup T^k(T_p M)$. How do we get the following map?

$$T^k_x(M) \rightarrow U \times \mathbb{R}^{n^k}$$

We have from the tan. bundle!

$$t_x: T_x M \rightarrow U \times \mathbb{R}^n$$

$$t_p: T_p M \rightarrow \{p\} \times \mathbb{R}^n, \text{ linear}$$

$$t_p^*: T^k(\mathbb{R}^n) \rightarrow T^k(T_p M), \text{ the pullback}$$

Fix a basis \hat{e} on \mathbb{R}^n . } use some basis?
 isom. $T^k(\mathbb{R}^n) \rightarrow \mathbb{R}^{n^k}$ } use some isom. for all trivializations

$$(t_p^*)^{-1}: T^k(T_p M) \rightarrow \mathbb{R}^{n^k}$$

So bundle theory maps to form $T^k M \rightarrow U \times \mathbb{R}^{n^k}$, so that it's $(t_p^*)^{-1}$ at each fiber.

In coordinates, $dx_i \otimes \dots \otimes dx_i$ generate $T^k(T_p M)$.

A section $A: M \rightarrow T^k M$ is called a covariant k-tensor (k -v.f)

$$A = \sum_{i_1, \dots, i_k} a_{i_1, \dots, i_k} dx_{i_1} \otimes \dots \otimes dx_{i_k}, \quad A \text{ is a } C^\infty\text{-section of } A_I \text{ are}$$

$$= a_I \leftarrow I \text{ called a multindex. (has order)}$$

C^∞ for all I & an atlas covering M .

$$\text{If } A = \sum_I a_I dx_{i_1} \otimes \dots \otimes dx_{i_k} = \sum_j b_j dy_j \otimes \dots \otimes dy_{j_k}, \text{ then}$$

$$a_I = \sum_j b_j \frac{dy_{j_1}}{dx_{i_1}} \dots \frac{dy_{j_k}}{dx_{i_k}} \quad \left\{ \begin{array}{l} \text{y's on top} \\ \text{b/c covariant} \end{array} \right.$$

Given a covariant tensor A , we can define a linear map

$$(1) \quad \mathcal{A}: \mathcal{V}_x \times \dots \times \mathcal{V}_x \longrightarrow \mathcal{L}^k(M), \text{ where } \mathcal{V} \text{ is a vector field}$$

$$\leftarrow \text{sp. of } C^\infty \text{ fcn's on } M$$

$$(2) \quad \mathcal{A}(\overline{x}_1, \dots, \overline{x}_k)(p) = A(p)(\overline{x}_1|_p, \dots, \overline{x}_k|_p)$$

\mathcal{A} is applied to a vect. field (which exists $\forall p$), while A is applied to vectors.

Theorem: If μ is a μ -additive map on above, then there exists a k -
linear μ satisfying (2).

Thm: Let V be the space of C^k v.f. on M , $\xi: \mathcal{A} \times \mathcal{V} \times \dots \times \mathcal{V} \rightarrow C^k(M)$
 multilinear wrt mult. by $C^k(M)$. Then \exists a k , C^k tensor field
 \mathcal{A} s.t. $\mathcal{A}(V_1, \dots, V_k)(p) = \mathcal{A}(p)(V_1, \dots, V_k)$. covariant

key difference from this is identification of derivations, which are linear wrt mult. by scalars.

Pf: We need to define $\mathcal{A}(p)(V_1, \dots, V_k)$, $V_i \in T_p M$. Given V_i , choose coords at p , (x, u) , ξ and $V_i = \sum a_i^j \frac{\partial}{\partial x_j}$. Let $f: M \rightarrow \mathbb{R}$, $\mathcal{A}(p) = 1$, $\text{Supp}(f) \subset U$. Define $\bar{X}_i = \sum a_i^j \frac{\partial}{\partial x_j}$ on U [ie bump fcn] 0 outside

$\bar{X}_i(p) = f V_i(p) = V_i$, $\xi \bar{X}$ is C^k . We define

$$\mathcal{A}(p)(V_1, \dots, V_k) = \mathcal{A}(\bar{X}_1, \dots, \bar{X}_k)(p)$$

vectors \uparrow vector fields

This is well-def: ie. if $\bar{X}_i(p) = Y_i(p)$, $i=1, \dots, k$, then $\mathcal{A}(\bar{X}_1, \dots, \bar{X}_k)(p) = \mathcal{A}(Y_1, \dots, Y_k)(p)$, ie. \mathcal{A} depends only on value of \bar{X}_i at pt.

Assume $k=1$: (This will suffice, since we can apply this case to each entry) By linearity, we need show that if $\bar{X}(p) = 0$, then $\mathcal{A}(\bar{X})(p) = 0$. (b/c $\mathcal{A}(\bar{X})(p) = \mathcal{A}(V)(p) \Rightarrow \mathcal{A}(X-V)(p) = 0$)

Assume first that $\bar{X}(p) = 0$ in a nbhd of p , w : Let f be a fcn w/ $\text{Supp}(f) \subseteq w$, $\xi f(p) = 1$.

$$0 = f \bar{X}, \text{ so } \mathcal{A}(f \bar{X})(p) = 0 = f(p) \mathcal{A}(\bar{X})(p) \neq \mathcal{A}(\bar{X})(p) \Rightarrow \begin{cases} \text{if } \bar{X} = 1 \text{ in a} \\ \text{nbhd of } p, \text{ since} \\ \text{value of } \bar{X} \end{cases}$$

Assume now $\bar{X}(p) = 0$. Let (x, u) be coordinates around p w/ $\bar{X} = \sum a_i \frac{\partial}{\partial x_i}$, $a_i(p) = 0$, on U . [want to take out a_i , by linearity,

but can only do that if $\frac{\partial}{\partial x_i}$ are vector fields, not vectors - so we need to extend this restricted \bar{X}]

Let $f: M \rightarrow \mathbb{R}$, $f|_U = 1$, $\bar{V} \in U$, $\text{Supp}(f) \subseteq U$. Consider $f \bar{X}$ on U , $f \bar{X} = \sum f a_i \frac{\partial}{\partial x_i}$. So, $\mathcal{A}(f \bar{X})(p) = \sum f a_i \mathcal{A}(\frac{\partial}{\partial x_i})(p) = 0$. Since $f \bar{X} \neq \bar{X}$

$\frac{\partial}{\partial x_i}$: these are vector fields \uparrow coincide on a nbhd of p , by prop. coord , $\mathcal{A}(f \bar{X})(p) = \mathcal{A}(\bar{X})(p)$. \square

We can consider multilinear maps $T: V^k \times \dots \times V^k \rightarrow \mathbb{R}$. Then repeat the construction (w/ V^* a vect. sp). You get contravariant tensors, if $V = T_p M$, $T \in (T_p^* M)^{\otimes k} = T_p^* M^{\otimes k}$ ($k=1$).

We now take tensor products of these. Locally, a contravariant tensor looks like $\sum a_{i_1, \dots, i_k} \frac{\partial}{\partial x_{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x_{i_k}}$.

Note: we can calculate tensor products of sections by doing it phrase: $(A \otimes B)(p) = A(p) \otimes B(p)$.

We can also construct mixed tensors, in which some are V & others are V^* ← apply to forms?

Contraction: let $T: V^k \times \dots \times V^k \times \dots \times V^k \times V^k \rightarrow \mathbb{R}$ be multilinear, & ← apply to vect. sps

R an $(r-1, s-1)$ -tensor. Then R is the contraction of T if

$$T = \sum a_{i_1, \dots, i_r, j_1, \dots, j_s} \frac{\partial}{\partial x_{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x_{i_r}} \otimes \dots \otimes \frac{\partial}{\partial x_{j_1}} \otimes \dots \otimes \frac{\partial}{\partial x_{j_s}}$$

$$C_{i_1 j_1}^n T = \sum_{i_1 \neq i_2} \sum_{i_2 \neq i_3} \dots \sum_{i_{n-1} \neq i_n} a_{i_1, \dots, i_n, j_1, \dots, j_s} \frac{\partial}{\partial x_{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x_{i_n}} \otimes \dots \otimes \frac{\partial}{\partial x_{j_1}} \otimes \dots \otimes \frac{\partial}{\partial x_{j_s}}$$

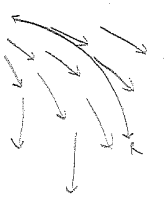
Then $C_{i_1 j_1}^n T$ is an $(r-1, s-1)$ -tensor.

Flw #1, 2, 3 from Ch. 4 (p.127) in Spivak.

Vector Fields & Integration

Goal problem: Given $\{X_1, \dots, X_k\}$, do I locally have a mfd this is tangent to? Generalizing no, but we'll look at when this case

Assume we have a vector field X . Can we find a curve $\alpha(t)$ s.t. $\dot{\alpha}(t) = X(\alpha(t))$ is tangent to α at t . That is, $\alpha'(t) = X(\alpha(t))$ (*)



In coordinates: $\dot{X}(t) = \sum a_i^j(t) \frac{\partial}{\partial x_i}$
 $\alpha'_*(\frac{d}{dt})(t) = \frac{d}{dt}(f \circ \alpha)$
 $= \sum \frac{\partial f}{\partial x_i}(\alpha(t)) \frac{dx_i}{dt}$, where $\alpha'_i = X_i \circ \alpha$.

$$\begin{bmatrix} (-\varepsilon, \varepsilon) \xrightarrow{M} \mathbb{R}^n \\ \alpha_i = x_i \circ \alpha \text{ (} x^i = i^{\text{th}} \text{ coord.)} \end{bmatrix}$$

From here, $\alpha'_*(\frac{d}{dt}) = \sum \frac{d\alpha_i}{dt} \frac{\partial}{\partial x_i} \Big|_{\alpha(t)}$. If we want (*) to be true,

$\sum \frac{d\alpha_i}{dt} \frac{\partial}{\partial x_i} \Big|_{\alpha(t)} = \sum a_i^j(\alpha(t)) \frac{\partial}{\partial x_i} \Big|_{\alpha(t)}$. Thus, locally, the property (*) holds whenever $\frac{d\alpha_i}{dt} = a_i^j(\alpha(t))$ (a 1st order diff. eqⁿ), which we can solve, uniquely if we give an initial condition, i.e. fix $\alpha_i(0) = p_i, i=1, \dots, n$.

Ex: $x' = x^2$

$\frac{x'}{x^2} = 1 \Rightarrow -\frac{1}{x} = t + c \Rightarrow \frac{1}{x} = t + c \Rightarrow x = \frac{1}{t+c}$, DNE $\forall t$. \Rightarrow Solutions will always be local, not global.

Review of ODE: not nec. of s

Thm: Let $f: U \rightarrow \mathbb{R}^n, U \subseteq \mathbb{R}^n, x_0 \in U, \tau > 0$ s.t. $\overline{B_r(x_0)} \subset U$. Assume f is bdd & Lipschitz on $\overline{B_{2r}(x_0)}$ [$|f(x) - f(y)| \leq L|x - y| \forall x, y \in \overline{B_{2r}(x_0)}$]. Then, \exists bdd s.t. for any $x \in B_r(x_0), \exists$ a ! sol'n $\alpha_{x, \cdot} : (-b, b) \rightarrow U$ s.t. $\alpha'_x = f(\alpha_x(t))$ & $\alpha_x(0) = x$.



\leftarrow where all α_x are in $B_r(x_0)$ for the same time, $(-b, b)$!

($\mathcal{C}^1 \Rightarrow$ loc. Lipschitz)

Thm: If $f: U \rightarrow \mathbb{R}^n$ is locally Lipschitz, then

$$\alpha: (-b, b) \times \mathbb{R} \rightarrow U$$

$$\alpha(t, y) = \alpha_x(t), \text{ as before}$$

is cts (in both t & y). If f is \mathcal{C}^k , then α is \mathcal{C}^k .

Since $d: \mathbb{R}^k \times \mathbb{R} \rightarrow \mathbb{R}^k$, we can find $\varepsilon > 0$ w/ $d: (-\varepsilon, \varepsilon) \times B_{\mathbb{R}^k}(x_0)$

$\rightarrow B_{\mathbb{R}^k}(x_0)$, bc d is cts. Equally, we can find $\delta > 0$ w/

$$\alpha: (-\delta, \delta) \times B_{\mathbb{R}^k}(x_0) \rightarrow B_{\mathbb{R}^k}(x_0), \text{ etc.}$$

Lie Derivatives

Def: (1) $L_{\bar{X}}(f) = \bar{X}(f)$, the Lie deriv. of a fcn

(2) For a covariant vector field, w/ $M \xrightarrow{\phi_h} M$, ϕ_h the flow.

$$(L_{\bar{X}} \omega)_p = \lim_{h \rightarrow 0} \frac{1}{h} ((\phi_h^* \omega)_p - \omega_p)$$

$$(\phi_h^* \omega)_p := \omega_{\phi_h(p)}$$

Note: $L_{\bar{X}}(f)$ coincides w/ the grad def:

$$\lim_{h \rightarrow 0} \frac{1}{h} ((\phi_h^* f)_p - f(p))$$

when they're equal, at same pt. $\omega_p \rightarrow \omega_{\phi_h(p)}$ then pullback so we can compare

$$= \lim_{h \rightarrow 0} \frac{1}{h} (f(\phi_h(p)) - f(p))$$

$= \frac{d}{dh} f(\phi_h) = \bar{X}(f)$, since \bar{X} is the tangent vector to the curve $h \rightarrow \phi_h(p)$ at $h=0$.

(3) For a vector field Y ,

$$(L_{\bar{X}}(Y))_p = \lim_{h \rightarrow 0} \frac{1}{h} ((\phi_h^* Y)_p - Y_p) = \lim_{h \rightarrow 0} \frac{1}{h} (((\phi_{-h})_* Y)_p - Y_p) =$$

$$\left[\begin{array}{c} M \xrightarrow{\phi_h} M \\ \text{diffs, so can pullback vector fields} \\ \phi_h^* \end{array} \right]$$

$$\begin{array}{l} \text{Define} \\ \phi_h^* Y = (\phi_h^{-1})_* Y \\ = (\phi_{-h})_* Y \end{array}$$

$$= \lim_{h \rightarrow 0} \frac{1}{h} ((\phi_{-h})_* Y_{\phi_h(p)} - Y_p)$$

$$M \xrightarrow{\phi_h} M \\ \phi_h(p)$$

$$\text{Let } \cdot = \lim_{h \rightarrow 0} \frac{1}{h} [Y_p - (\phi_h)_* Y_{\phi_h(p)}]$$



* go back in flow & push forward, unlike for forms, where you go forward in flow & pullback

(ω a 1-Form)

Prop: Assume $L_X(Y)$ & $L_X \omega_i$ exist for $i=1,2$. Then \exists one C^∞

(1) $L_X(Y_1 + Y_2) = L_X Y_1 + L_X Y_2$

(2) $L_X(\omega_1 + \omega_2) = L_X \omega_1 + L_X \omega_2$

(3) $L_X(fY) = X(f)Y + fL_X Y$

(4) $L_X(f\omega) = X(f)\omega + fL_X \omega$

HW (5) $L_X(\omega(Y)) = (L_X \omega)(Y) + \omega(L_X Y)$

PF (3): $[L_X(fY)]_p \stackrel{\text{vect field form}}{=} \lim_{h \rightarrow 0} \frac{1}{h} [f(\phi_h)Y_p - (f(\phi_h))_* Y_{\phi_h(p)}]$

$= \lim_{h \rightarrow 0} \frac{1}{h} [f(\phi)Y_p - f(\phi_h(p))Y_{\phi_h(p)}]$

$= \lim_{h \rightarrow 0} \frac{1}{h} [f(\phi)Y_p - f(\phi)(\phi_h)_* Y_{\phi_h(p)} + f(\phi)(\phi_h)_* Y_{\phi_h(p)} - f(\phi_h(p))Y_{\phi_h(p)}]$

$= f(\phi) \lim_{h \rightarrow 0} \frac{1}{h} [Y_p - (\phi_h)_* Y_{\phi_h(p)}] + \lim_{h \rightarrow 0} \frac{1}{h} [(f(\phi_h))_* Y_{\phi_h(p)} - f(\phi_h(p))Y_{\phi_h(p)}]$

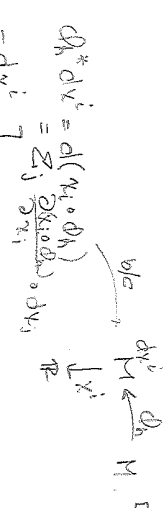
$= f(\phi)(L_X Y)_p + X(f)Y_p$

In coordinates:

(1) obvious

(2) $L_X(dx^i)_p = \lim_{h \rightarrow 0} \frac{1}{h} [(\phi_h^* dx^i)_p - dx^i_p]$

$= \lim_{h \rightarrow 0} \frac{1}{h} \left[\sum_j \frac{\partial(x^i \circ \phi_h)}{\partial x_j} dx_j - \sum_j \frac{\partial x^i}{\partial x_j} dx_j \right]$



linear map #1 so take out

same as dx^i

$$= \sum_i \frac{\partial}{\partial x_i} \left[\lim_{h \rightarrow 0} \frac{1}{h} (x_i + \theta h - x_i) \right] dx_i$$

$$= L_{\bar{x}}(x_i) = \bar{x}(x_i) = \frac{d}{dh} \Big|_{h=0} x_i(\theta_h)$$

Assume $\bar{x} = \sum a_i \frac{\partial}{\partial x_i}$, so $\bar{x}(x_i) = a_i$. Thus,

$$\begin{aligned} \omega &= \sum a_i dx_i \text{ form} \\ \gamma &= \sum b_i \frac{\partial}{\partial x_i} \text{ vec of field} \end{aligned}$$

$$L_{\bar{x}}(dx_i) = \sum_j \frac{\partial a_i}{\partial x_j} dy_j$$

So γ is a form, $\omega = \sum u_i dx_i$, so apply Leibnitz rule, \ddagger

$$L_{\bar{x}}(\omega) = \sum_i \bar{x}(u_i) dx_i + \sum_{i,j} u_i \frac{\partial a_i}{\partial x_j} dx_j$$

$$L_{\bar{x}}(\omega) = \sum_i \bar{x}(u_i) + \sum_j u_j \frac{\partial a_j}{\partial x_i} \Big] dx_i$$

C^0 , then $L_{\bar{x}}(\omega)$ exists \ddagger is C^0 . If \bar{x} & ω exist \ddagger are

$$(3) (L_{\bar{x}}(\gamma))_p = [\bar{x}, \gamma]_p := \bar{x} \gamma_p - \gamma \bar{x}_p$$

$$\ddagger (L_{\bar{x}}(\gamma))(p) = \bar{x} \gamma_p(p) - \gamma \bar{x}_p(p) :$$

$L_{\bar{x}} \frac{\partial}{\partial x_i}$: we'll use $\# 5$ \ddagger the fact that $dx_j(\frac{\partial}{\partial x_i})$ is a constant;

$$dx_j(\frac{\partial}{\partial x_i}) = \delta_{ij}, \text{ so } 0 = L_{\bar{x}}(dx_j(\frac{\partial}{\partial x_i})) = \overset{\text{by } (3)}{L_{\bar{x}} dx_j(\frac{\partial}{\partial x_i})} + dx_j(L_{\bar{x}} \frac{\partial}{\partial x_i})$$

$$\text{So } dx_j(L_{\bar{x}} \frac{\partial}{\partial x_i}) = -L_{\bar{x}} dx_j(\frac{\partial}{\partial x_i}) = \overset{\text{bc sub in (2), \ddagger terms in sum = 0 \forall i \neq j}}{-\frac{\partial a_j}{\partial x_i}}$$

Thus, $L_{\bar{x}} \frac{\partial}{\partial x_i} = -\sum_j \frac{\partial a_j}{\partial x_i} \cdot \frac{\partial}{\partial x_j}$ (bc of dx_j is applied to it we get)

Assume $\gamma = \sum b_i \frac{\partial}{\partial x_i}$. Then,

$$L_{\bar{x}} \gamma = \sum_i \bar{x}(b_i) \frac{\partial}{\partial x_i} + b_i L_{\bar{x}}(\frac{\partial}{\partial x_i}) \text{ by Leibnitz rule } [\bar{x} = \sum a_j \frac{\partial}{\partial x_j}]$$

$$= \sum_j a_j \frac{\partial b_i}{\partial x_j} \frac{\partial}{\partial x_i} - \sum_{i,j} b_i \frac{\partial a_j}{\partial x_i} \frac{\partial}{\partial x_j}$$

$$L_{\bar{x}} \gamma = \sum [a_j \frac{\partial b_i}{\partial x_j} - b_i \frac{\partial a_j}{\partial x_i}]$$

Lie brackets:

$$[\bar{X}, Y](f) = \bar{X} Y(f) - Y \bar{X}(f) = \sum_i a_i \frac{\partial}{\partial x_i} (b_j \frac{\partial f}{\partial x_j}) - b_j \frac{\partial}{\partial x_j} (a_i \frac{\partial f}{\partial x_i})$$

$\xrightarrow{0}$

* even though the 2 terms in the Lie bracket are not vect. fields, their difference is a vect. field.

Properties:

(1) $L_{\bar{X}}(Y) = -L_Y(\bar{X})$

(2) $L_{\bar{X}}(\bar{X}) = 0$

(3) $[\bar{X}, Y]Z + [Y, \bar{X}]Z + [Z, \bar{X}]Y = 0$ (Jacobi identity)
 $\Rightarrow \textcircled{0} [X, Y]Z = 0$
 \uparrow cyclic sum

In terms of Lie derivatives:

$$L_Z([\bar{X}, Y]) = L_Z(L_{\bar{X}}Y) = -L_{[\bar{X}, Y]}Z$$

$$L_{\bar{X}}[Y, Z] = L_{\bar{X}}L_Y Z$$

$$L_Y[Z, \bar{X}] = L_YL_Z \bar{X} = -L_YL_{\bar{X}}Z$$

$$\Rightarrow -L_{[\bar{X}, Y]}Z + L_{\bar{X}}L_Y Z - L_YL_{\bar{X}}Z = 0$$

$$\Rightarrow L_{[\bar{X}, Y]} = L_{\bar{X}}L_Y - L_YL_{\bar{X}} = [L_{\bar{X}}, L_Y], \text{ so Lie deriv}$$

of commutator is commutator of Lie deriv's.

Note: $[\bar{X}, Y]$ is not a tensor operation, i.e. cannot be written as a comb. of tensors.

$[,]$ takes $(\bar{X}, Y) \rightarrow Z$, input = 2 vect. fields, output = 1 vect. field

In theory, could be (2,1)-mixed tensor

$A = \sum a^i dx^i \otimes dy^j \otimes dz^k$. But tensors are linear over mult. by fens, while $[,]$ is not:

$$[\bar{X}, fY] = [X, Y]f + \bar{X}(f)Y$$

$$\bar{X}(fY) = fY\bar{X} - fY\bar{X} + \bar{X}(f)Y$$

(differentiation, so prod. rule.)

Also, tensors vanish when applied to a vector field that vanishes at p , since if $\bar{X} = \sum b^i \frac{\partial}{\partial x^i} |_p$, $b^i(p) = 0$, $\bar{X} A(X, Y)_p = \sum b^i a^i(p) \dots \Rightarrow A(X, Y)_p = 0$.

But if $\bar{X}_p = 0$, $[\bar{X}, Y]_p$ is not always 0. However, if $\bar{X}_p = Y_p = 0$, then $[\bar{X}, Y]_p = 0$:

Assume $\bar{X}_p = 0$. Then the flow satisfies $\frac{dc(t)}{dt} = \bar{X}(c(t))$ & $c(0) = p$. Thus $c(t) = p$ is a solution. Hence,

$$\Phi_t(p) = p \quad \forall t. \quad \text{So,}$$

$$[X, Y]_p = \lim_{h \rightarrow 0} \frac{1}{h} (Y_p - (\Phi_h^* Y)_p) = 0$$

not identity:
 $= (\Phi_h)_* Y_{\Phi_h(p)}$
 $\stackrel{p}{=} \text{the flow const at } p \text{ (use } t=h)$
 $= 0$

More Properties $\xrightarrow{f} \text{TM}$

Prop: Let $f: M \rightarrow N$ be a diffeomorphism. Let \bar{X} be a vect. field on M & $f_* \bar{X}$ be the v.f. on N . Then the flow of $f_* \bar{X}$ is $\Phi_t^{f_* \bar{X}} = f \circ \Phi_t^{\bar{X}} \circ f^{-1}$.

$g \in N$

Pf: $(f_* \bar{X})_g(g) = (f_* \bar{X}_{f^{-1}g_0})(g) = \overbrace{f_* \bar{X}_{f^{-1}g_0}}^{LX \text{ deriv}}(g \circ f)$

$= \lim_{h \rightarrow 0} \frac{1}{h} (g \circ f \circ \phi_h^{\bar{X}}(f^{-1}g_0) - g \circ f(f^{-1}g_0))$

$= \lim_{h \rightarrow 0} \frac{1}{h} (g \circ f \circ \phi_h^{\bar{X}} \circ f^{-1}(g) - g(g))$

$\Rightarrow \phi_{f_* \bar{X}}^h$

Cor: $f_* \bar{X} = \bar{X} \Leftrightarrow \phi_h^{\bar{X}} \circ f = f \circ \phi_h^{\bar{X}}$

Pf: $\phi_h^{f_* \bar{X}} = f \circ \phi_h^{\bar{X}} \circ f^{-1} \quad \& \quad f_* \bar{X} = \bar{X}$

So, leaving a vector field invariant is equivalent to commuting w/ the flow.

Prop: $[X, Y] = 0 \Leftrightarrow \phi_t^X \circ \phi_s^Y = \phi_s^Y \circ \phi_t^X$

Note: This says [,] measures the lack of commutativity in the flow.



this is closed. If [,] = 0.

Pf: (\Leftarrow): If $\phi_t^X \circ \phi_s^Y = \phi_s^Y \circ \phi_t^X$, then $(\phi_t^X)_* Y|_p = Y|_p \forall t$, by prev corollary. Then

$(LY^X)|_p = \lim_{h \rightarrow 0} \frac{1}{h} (Y|_p - (\phi_h^X)_* Y|_p) = 0 \checkmark$ and by cor, the flows commute

(\Rightarrow): If $[X, Y]|_p = 0$, w/TS $(\phi_t^X)_* Y = Y \forall t$. Consider the curve

$c(t) = ((\phi_t^X)_* Y)|_p$. We will show that $c'(t) = 0$, & so $c(t) = c(0) = Y|_p \forall t$.

$c'(t) = \lim_{h \rightarrow 0} \frac{((\phi_{t+h}^X)_* Y)|_p - ((\phi_t^X)_* Y)|_p}{h}$ [regular derivative]

$\begin{bmatrix} (\phi_{t+h}^X)_* \\ (\phi_t^X)_* \end{bmatrix}$

$= \lim_{h \rightarrow 0} \frac{1}{h} ((\phi_h^X)_* Y)|_{\phi_t^X(p)} - Y|_{\phi_t^X(p)}$

$= -LY^X|_{\phi_t^X(p)} = 0$ (by assum p.)

□

Prop: If α is a diffeomorphism, then $\alpha_* [X, Y] = [\alpha_* X, \alpha_* Y]$.

Prf: $(\alpha_* \bar{X})(f) = \bar{X}_{\alpha^{-1}(p)}(f \circ \alpha) \stackrel{\text{notation}}{=} \bar{X}(f \circ \alpha) \circ \alpha^{-1}(p)$

So, $[\alpha_* \bar{X}, \alpha_* \bar{Y}](f) = \alpha_* \bar{X}(\alpha_* \bar{Y}(f)) - \alpha_* \bar{Y}(\alpha_* \bar{X}(f))$

$$= \alpha_* \bar{X}(\alpha_* \bar{Y}(f \circ \alpha)) - \alpha_* \bar{Y}(\alpha_* \bar{X}(f \circ \alpha))$$

$$= \bar{X}(\alpha_* \bar{Y}(f \circ \alpha) \circ \alpha^{-1}) \circ \alpha^{-1} - \bar{Y}(\alpha_* \bar{X}(f \circ \alpha) \circ \alpha^{-1}) \circ \alpha^{-1}$$

$$= [\bar{X}, \bar{Y}](f \circ \alpha) \circ \alpha^{-1} = \alpha_* [\bar{X}, \bar{Y}]$$

D.

Question: If we have $\bar{X}_1, \dots, \bar{X}_k$ ind. vector fields on \hat{U} , can we find coordinates $x: U \rightarrow \mathbb{R}^n$ s.t. $\bar{X}_i = \frac{\partial}{\partial x_i}$? We did this for one, but can we do it for more?

Ans: No. B/c $[\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j}] = \frac{\partial^2}{\partial x_i \partial x_j} - \frac{\partial^2}{\partial x_j \partial x_i} = 0$, & so we see that $[\bar{X}_i, \bar{X}_j] = 0$ is a necessary condition. It turns out that this is also sufficient. [Essentially, we are straightening the flows]

Thm: If $\bar{X}_1, \dots, \bar{X}_k$ are ind. C^∞ -v.f.'s on a nbhd \hat{U} of $p \notin [\bar{X}_i, \bar{X}_j] = 0 \forall i, j$, then \exists coordinates (x, u) around p s.t. $\bar{X}_i = \frac{\partial}{\partial x_i}$ on $U, i=1, \dots, k$.

Prf: Similarly to $k=1$, assume $U = \mathbb{R}^n, p=0, \bar{X}_i|_0 = \frac{\partial}{\partial x_i}|_0$ for some coordinates t in \mathbb{R}^n

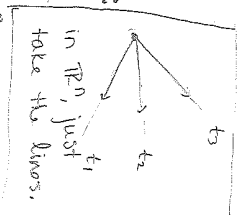
Define $g(a^1, \dots, a^n) = \phi_{a^1} \circ \phi_{a^2} \circ \dots \circ \phi_{a^k} (0, \dots, 0, a^{k+1}, \dots, a^n)$

where ϕ^i is the flow for \bar{X}_i . WTS g is a change of vars, i.e. g is a diffeom. If $t=k+1, \dots, n$:

$g_* (\frac{\partial}{\partial t_i}|_0) (f \circ g) = \frac{\partial}{\partial t_i} (f \circ g)(a)$ [can let $a_i = 0$ for $i=1, \dots, k$ b/c $\phi^i = 0$ for taking i th parthood]

$\stackrel{(i, j)}$ $= \frac{\partial}{\partial t_i} (f \circ g)|_0 (f(a, \dots, a_i, \dots, 0)) = \frac{\partial f}{\partial t_i}|_0$

So $g_* (\frac{\partial}{\partial t_i}|_0) = \frac{\partial}{\partial t_i}|_0$.



If $i=1, \dots, k$, then again, let $a_j = 0$ if $j \neq i$

$$y_* (\frac{\partial}{\partial t_i} |_0) (f) = \frac{\partial}{\partial t_i} |_0 (f(\phi_{a_i}^i(a_1, \dots, a_n)))$$

$= \bar{X}_0^i (f)$
 $= \frac{\partial}{\partial t_i} |_0 (f)$
 { deriv. of f along curve in
 tan. vector applied to f , &
 \bar{X}_0^i is the tan. vect. to ϕ_i^i at
 $h=0$

by assump.

Thus $y_* (\frac{\partial}{\partial t_i} |_0) = \frac{\partial}{\partial t_i} |_0$ for $i=1, \dots, k$. we showed the jacobian #?

Since $y_* |_0 = I$, we can invert y in a nbhd of 0 , so y is a diffeo. in a nbhd of 0 .

Choose $x = y^{-1}$ maps: $x_* \bar{X}^i = \frac{\partial}{\partial t_i}$ on a nbhd of 0 (not just at 0)

Then as $x_*^{-1} \frac{\partial}{\partial x_i} = \frac{\partial}{\partial t_i}$, we have $\bar{X}^i = \frac{\partial}{\partial x_i}$.
 by def; see diagram. $\frac{\partial}{\partial x_i} \in T\mathbb{R}^n$

Let's look at t_1 :

$$y_* (\frac{\partial}{\partial t_1} |_0) (f) = \frac{\partial}{\partial t_1} |_0 (f \circ y) = \frac{\partial}{\partial t_1} |_0 (f(\phi_{a_1}(g(a_1))), \text{ where}$$

$g^i = \phi_{a_2}^2 \circ \dots \circ \phi_{a_k}^k (0, \dots, 0, a_{k+1}, \dots, a_n)$. Recall $\phi_{a_1}^1$ is the flow of \bar{X}^1 , & differentiating along the flow gives $\bar{X}_1(f)$. So,

$$= \lim_{h \rightarrow 0} \frac{1}{h} (f(\phi_{h+a_1}^1(g(a_1))) - f(g(a_1)))$$

$$(*) = \lim_{h \rightarrow 0} \frac{1}{h} (f(\phi_h^1(\phi_{a_1}^1(\underbrace{\phi_{a_2}^2 \circ \dots \circ \phi_{a_k}^k(a_1, \dots, a_n)}_{y(a_1)})) - f(g(a_1))))$$

$$= \lim_{h \rightarrow 0} \frac{1}{h} (f(\phi_h^1(y(a_1))) - f(y(a_1))) = \bar{X}_1(f) \circ y(a_1)$$

To do for t_2 , need the fact that flows commute in order to pull $\phi_{a_2}^2$ to the front & repeat. Since $[\bar{X}^1, Y] = 0$, this is true. \square

HW: Ch. 5 (Vect Fields) # 7, 10, 11, 13, 14b (only for constant v.f.)

We have vector fields \vec{X}_p & are trying to find curves γ that to it. This exists locally, b/c essentially SDE's.

What if we have k vect fields, $\vec{X}_1, \vec{X}_2, \dots, \vec{X}_k$, I want a manifold to them (usually a k -manifold)

- when $k=1$, you have a flow;
 - when $k=2$, you have a plane;
 - when $k=3$, you have a volume.



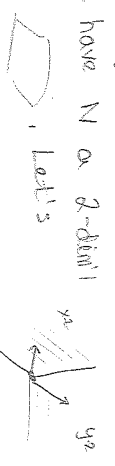
Filling everything

Doesn't always happen, b/c essentially PDE's.

Def: A k -dim distribution on M is a k -en $\mathcal{P} \rightarrow \Delta \mathcal{P} \subseteq T_{\mathcal{P}}M$, where $\Delta \mathcal{P}$ is a k -dim subsp of $T_{\mathcal{P}}M$. If for every $\mathcal{P} \in M$ \exists coordinates (x, u) st $\vec{X}_1, \dots, \vec{X}_k$ are \mathbb{R} -v.f.'s generating $\Delta \mathcal{P}$, $\mathcal{P} \in U$, then we say Δ is \mathbb{R} -gen. We say N is an integral submanifold if $N \subseteq M$ w/ $T_x N \subseteq \Delta_x$ the inclusion, & $C_x(T_x N) = \Delta_x$ for any $\mathcal{P} \in N$.

Let ω any pt of N , Δ_{ω} is the tangent sp. Δ is integrable k -submanifolds? No, in general.

Ex: Assume $M = \mathbb{R}^3$ & Δ is gen. by 2 v.f.'s, $\partial_x + f(x,y)\partial_z$ & $\partial_y + g(x,y)\partial_z$. Suppose we have N a 2-dim submanifold $\hookrightarrow \langle \partial_x, \partial_y \rangle$. Let's



write N as a graph, $z = s(x, y)$. (alog)

N is given by $(x, y, s(x, y))$. If $\mathcal{P} = (x, y, z)$,

$T_{\mathcal{P}}N = \langle (\partial_x + f\partial_z), (\partial_y + g\partial_z) \rangle$. If $(\partial_x + f\partial_z) \in \Delta_{\mathcal{P}}$, then $\partial_x + f\partial_z = f(x, y)\partial_z$ &

$\partial_y + g\partial_z = g(x, y)\partial_z$. This has a sol'n whenever $\partial_x^2 \partial_y = \partial_y^2 \partial_x \Rightarrow$

$\partial_x^2 \partial_y = \partial_y^2 \partial_x$. Pick 2 fns that don't sat. this condition, & there will be no such integral 2-submanifold N .

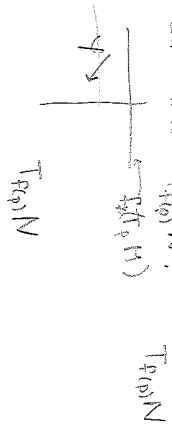
Ex: $\frac{\partial}{\partial x} + b \frac{\partial}{\partial z}$, $\frac{\partial}{\partial y}$. If b is not constant, this will not be integrable. If b is constant (or $\frac{\partial b}{\partial y} = 0$), then the plane generated by these 2 vectors at any pt is an integrable distribution. b is constant.

Local Theory of Integration

Def: Let $f: M \rightarrow N$ & let \bar{X} be a v.f. on M , \bar{Y} on N . We say $\bar{X} \in \bar{Y}$ are f-related if $f_* \bar{X}_p = \bar{Y}_{f(p)}$ for any $p \in M$.

I.e., $f_* \bar{X}_p (X_p)(g) = \bar{X}_p(g \circ f)$, so $\bar{X} \in \bar{Y}$ are f-rel. whenever $Y_{f(p)}(g) = Y(g) \circ f_p$ for any $g: N \rightarrow \mathbb{R}$.

Note! If \bar{Y} is a v.f. on N , it does not need to be f-related to a v.f. in M . It could be that $Y_{f(p)} \notin f_*(T_p M)$, as $f_*(T_p M)$ may have a smaller dim than $T_{f(p)} N$.



Also X may not be unique if not 1-1, i.e. some $g \in N$ may have 2 preimages.

Prop: Let $f: M \rightarrow N$ be a \mathcal{C}^∞ immersion. Then, if \bar{Y} is a \mathcal{C}^∞ v.f. on N w/ $Y_{f(p)} \in f_*(T_p M)$, Then $\exists!$ v.f. $X \in M$ f-rel. to \bar{Y} .

Pf: Since f is an immersion, f_{*p} is 1-1, & for $Y_{f(p)}$, we can find a unique X_p s.t. $f_{*p}(X_p) = Y_{f(p)}$. To see that X is \mathcal{C}^∞ , we choose coordinates: We know there are coordinates (x^i, y^j) on M s.t. $Y_{f(p)} = \sum a^i \frac{\partial}{\partial x^i} + \sum b^j \frac{\partial}{\partial y^j}$. In terms of $T_p M$, this means $f_* \frac{\partial}{\partial x^i} = \sum a^i \frac{\partial}{\partial x^i} + \sum b^j \frac{\partial}{\partial y^j}$ for $i=1, \dots, n$. On U , $X = \sum x^i \frac{\partial}{\partial x^i}$. Then $f_* X = \sum a^i \frac{\partial}{\partial x^i} + \sum b^j \frac{\partial}{\partial y^j}$. What are the b^j ?

$$N \xrightarrow{F^*} \mathbb{R}^n$$

$$\downarrow \alpha_i$$

$$\mathbb{R} \xrightarrow{\beta_i} \mathbb{R}^m$$

so $\alpha_i = \beta_i \circ f$

If $f_* X = Y \circ f = \sum \beta_i \partial y_i|_p$, then $\alpha_i = \beta_i \circ f$ and Y is \mathbb{R}^m then β_i are \mathbb{R}^m , \hat{z} thus so are α_i . □

Prop: If X_i is f -rel. $Y_i, i=1,2$, then $[X_1, X_2]$ is f -rel. to $[Y_1, Y_2]$.

(i.e. the push-forward preserves the Lie bracket).

Pr: $[Y_1, Y_2](g) \circ f = Y_1(Y_2(g)) \circ f - Y_2(Y_1(g)) \circ f$

but $f^* \circ f^* = \text{id}$ so $f \circ f^* = \text{id}$

$$= X_1(X_2(g \circ f)) - X_2(X_1(g \circ f))$$

$$= [X_1, X_2](g \circ f)$$

□

Def: We say a v.f. X belongs to a distribution Δ , if $X_p \in \Delta_p \forall p$.

Note: Assume N is a k -integrable submfd. Then $i: N \hookrightarrow M, w/ i_* T_p N = \Delta_p \forall p$. Let $X, Y \in \Delta$ around p . Then $\exists \mathcal{R}, \mathcal{Q}, v, \mathcal{R}$ on N that are i -rel. to $X \hat{z} Y$ (b/c i an immersion $\hat{z} X_{w_0}, Y_{w_0} \in i_* T_{w_0} N$. $[\mathcal{R}, \mathcal{Q}]_p \in T_p N$, \hat{z} it is i -rel. to $[X, Y]$, so.

$$i_* [\mathcal{R}, \mathcal{Q}]_p = [X, Y]_{i(p)} \in \Delta_p = i_* (T_p N).$$

Def: A distribution Δ is called involutive if for any $X_0, Y_0 \in \Delta_p$, $[X, Y]_p \in \Delta_p$. This is called integrable if for every p , \exists an integrable k -submfd through p . i.e. a vector field in Δ (locally).

Ex: $\partial_x + f \partial_z = X, \partial_y + g \partial_z = Y, [X, Y] = (-\partial_y^2 \partial_x + \partial_x^2 \partial_y) \partial_z$

If $\Delta = \langle X, Y \rangle$, then $[X, Y] \in \Delta \Leftrightarrow [X, Y] = 0$

need this int. $\partial_x \hat{z} \partial_y$ to be in Δ .

Frobenius Test (1st version): Let Δ be a \mathbb{C} -distribution, and assume it is involutive. Then for any p, \exists coordinates (x, y) , $x(y) = (-\xi, \xi)$, s.t. $\int_{p \in U} x^i(y) = a^i e^{\xi}$, $|a^i| < \epsilon$, $i = 1, \dots, n$? are all integrable submanifolds.

[i.e., locally looks like $\begin{matrix} \text{---} \\ \text{---} \\ \text{---} \end{matrix}$]

Furthermore, any integrable submanifolds contained in one of these, (locally)

i.e. Δ is span by $\partial_{x_i}, i = 1, \dots, k$, & these x_i are preimages of t_i on \mathbb{R}^n

Frobenius (vector field version): Let Δ be a C^∞ involutive k -dim'd distribution on M . Then, locally, Δ is integrable, that is, for each $p \in M$, we have (x, u) , $x(u) = (-x^i \partial_i)^n$ w/ $\{g^i u, x^i(g^j) = a^i, |a^i| < \epsilon, i = k+1, \dots, n\}$ an integrable submfd of Δ . Furthermore, a ctd integrable submfd is locally in one of these sets.

Pf: Assume $M = \mathbb{R}^n$ & $p = 0$. Assume x_i are coordinates s.t.

$\partial_{x_1}|_0, \dots, \partial_{x_k}|_0$ generate Δ_0 . [Reverse, Δ_p is locally gen by X_p, \mathcal{C}^∞ & we choose $\{u^i\}$ s.t. $X_0 = \sum \partial_{x_i}|_0$. Consider

$\pi: \mathbb{R}^n \rightarrow \mathbb{R}^k$ the projection onto the 1st k entries. $(x_1, \dots, x_k) \mapsto (x_1, \dots, x_k)$.

$\pi_*: T\mathbb{R}^n \rightarrow T\mathbb{R}^k$ has full rank ($r_k = k$) w/c π a proj. $\pi_*|_0: \Delta_0 \rightarrow T\mathbb{R}^k$ is (the "identity") an isomorphism. Δ involutive (*) requires

For $\forall p$ close to 0,

$\pi_*|_p: \Delta_p \rightarrow T\mathbb{R}^k$ is still an is, w/c π_* has full rk, it's smooth,

Then let X^i_p be the vector fields w/ $\pi_* X^i_p = \partial_{x_i}|_p$, p near 0.

X^i & ∂_{x_i} are π -related, so $[X^i, X^j] = 0$ w/c π_*

$[\partial_{x_i}, \partial_{x_j}] = 0$. If $[X^i, X^j] = 0$, then $\exists (x, u)$ w/ $X^i_p = \partial_{x_i}|_p, p \in u$,

& so $x_i(u) = a^i$ constant for $i = k+1, \dots, n$ are integrable submfd.

Note: (*) needs 2 things:

(1) need $\Delta_p \rightarrow T\pi(p) \mathbb{R}^n$ to be an is at each fiber, which comes from continuity

(2) need $\Delta u \rightarrow T\pi(u) \mathbb{R}^n$ to be smooth, & need gen's $\{X^i_p\}$ to map to $\{\partial_{x_i}|_p\}$, for which one needs involutive (w/c $T\mathbb{R}^n$ is closed under $[-, -]$, so Δu must be as well to define this map in a smooth way)

If N is an integral submfd, WTS that the old components of NU are contained in slices (each in one slice). Consider the inclusion

$i: NU \hookrightarrow U$, \exists let $x^i \in \Delta_u$.

$$\begin{aligned} d(x^{k+1}, \dots, x^k)(X_j) &= X_j(x^{k+1}, \dots, x^k) \\ &= i_* X_j(x^i) = 0 \end{aligned}$$

$G = 0$ on U , since $X_j = \frac{\partial}{\partial x^j} |_{g^i} \quad j=1, \dots, k, \quad [i = k+1, \dots, n]$

Since $d(x^{k+1}, \dots, x^k)(X_j) = 0 \quad \forall X \in \Delta_u$, an any integrable mfd, x^{k+1} is constant.

Details of step (*):

$\Pi_x^b: \Delta_0 \rightarrow T_0 \mathbb{R}^k$ is on \cong , so for p close to 0,

$\Pi_x^p: \Delta_p \rightarrow T_{\Pi_x(p)} \mathbb{R}^k$ is, on each fiber, an isomorphism.

(bc π doesn't change in a small nbhd, from continuity).

WTS $\Pi_x^*: \Delta_x \rightarrow T_{\Pi(x)} \mathbb{R}^k$ is smooth. Choose $X^i \in \mathcal{G}_x$ generating

Δ_x s.t. $\Pi_x(X^i) = \frac{\partial}{\partial x^i}$. [why can we choose these?]]

Then, if Δ is involutive, Π_x is smooth.

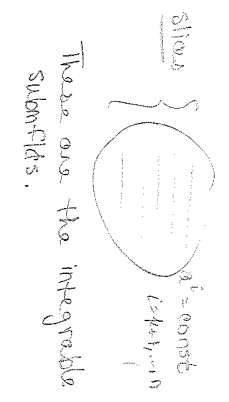
What is the global picture?

Def: Let M be a mfd. A k -diml smooth \mathfrak{z} regular foliation

of M is a set $\{N_x\}_{x \in M}$ of k -diml immersed submfd's

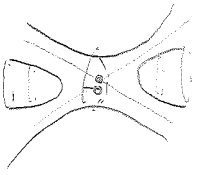
N_x s.t. $M = \cup_{x \in M} N_x$, \nexists s.t. for any $p \in M$, $\exists (x, U)$ with $N_x \cap U$ being contained in slices of the form

$$S_a(p) = \{g \in M \mid g^i = a^i, |a^i| < \varepsilon, i = k+1, \dots, n\}$$



Ex: The leaves of foliation are level sets of $x^2 + y^2 - z^2$:

This is a 2-dim foliation w/ singularities.



- Not regular, b/c looks like a sphere at every pt except at P , where you have a singularity & the dimension drops.


Note: 2 open areas are each a leaf, & the pt P is a leaf!

The N_x are called leaves of the foliation.

Ex: Foliation of \mathbb{R}^3 by action of S^1 is also singular: leaves are spheres except O , which is also a leaf.

Note: $N_x \cap N_y$ could be contained in multiple leaves, not just 1.

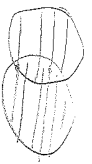
Thm: Let Δ be a C^∞ involutive distribution on M . Then M is foliated by integral ^{immersed} submanifolds. Each cld component is called a maximal integrable submanifold.

Ex: Torus  This flow is a leaf of a foliation, but is not embedded in any way.

Pf: Let $\{U_i\}_{i \in I}$ be a cover of M , sliced as in Frobenius thm.

Let's say $p, q \in U_i$, U_i, \dots, U_k and slices S_{x_1}, \dots, S_{x_r} w/ $S_{x_i} \cap U_i$ and $S_{x_i} \cap S_{x_{i+1}} \neq \emptyset$. Let $N_p = \int_{g \in H} g \cdot p$.

We can split H as the disjoint union of these classes $H = \bigcup_{x \in I} N_x$, $N_x = N_{p_x}$. Note: $N_p = N_q$ or $N_p \cap N_q = \emptyset$.



On N_x , define the top generated by that of S_i as an immersed submanifold of U_i . We need to show this is 2nd countable.

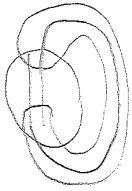
RE] $N_x \cup U_i$ could have countably many old components.

Think: -dense, so nbhd has countably many old comp's of \emptyset or leaf.

Can we have more than countably many old comp's of an N_x in one nbhd U_i ? If not, then have countably many slices covered by countably many open sets from rat 1 balls) in countably many nbhd's, so done.

First, if S_{x_i} is a slice in $U_i \cap U_j \neq \emptyset$, how many slices of U_j 's slices can S_{x_i} intersect?

- More than 1.



Note: If $p \in S_{x_i} \cap S_{y_j}$, by continuity, an entire nbhd of p is in the intersection. But we can cover an intersection by at most countably many such nbhd's. Thus, S_{x_i} can intersect at most countably many other slices.

Next, done. A pt on a leaf lies on a slice, & there are only countably many choices of where to go, in each of countably many open sets covering it. Thus the leaf containing p is covered by countably many slices.

Thus, N_x is an immersed submfld. □

From last time: $\pi: \mathbb{R}^n \rightarrow \mathbb{R}^k$ proj.

$\pi_*|_p: \Delta_p \rightarrow T_p \mathbb{R}^k$ an isomorphism b/c Δ_p is open, by assumption, by $\partial_{x_1}, \dots, \partial_{x_k}$

$\pi_*|_p: \Delta_p \rightarrow T_p \mathbb{R}^k$ an isomorphism for p close to O from continuity.

$\partial_{x_i} \pi|_p$ (which comes from Δ_p $\xrightarrow{\pi_*|_p} T_p \mathbb{R}^k$)

which implies it consists in $\partial_{x_i} \downarrow T_p \mathbb{R}^n / \text{etc}$

$$\frac{\partial}{\partial t} \Big|_p \in T_p \mathbb{R}^k$$

$\pi_*|_p \Big| \frac{\partial}{\partial t} \Big|_p = \frac{\partial}{\partial t} \Big|_p$, so $X^i \neq \partial_{x_i}$ are π -related, i.e.

$$\pi_* [X^i, X^j] = [\pi_* X^i, \pi_* X^j] = [\partial_{x_i}, \partial_{x_j}] = 0, \text{ but } \pi_* \text{ on } \Delta_p \text{ is } \neq 0 \text{ so}$$

$[X^i, X^j] = 0$, which only occurs when $[X^i, X^j] \in \Delta_p$, which it is, since Δ is involutive.

[i.e. if Δ_p involutive, then Δ is integrable]

Def: If $T \in T^k(V)$ is a k -tensor on a vect. sp V , we say T is

alternating if $T(v_1, \dots, v_i, \dots, v_j, \dots, v_n) = 0$ whenever $v_i = v_j, i \neq j$.

This is equivalent to saying T is skew-symm in any 2 entries, i.e. exchanging any 2 entries $v_i \neq v_j, i \neq j$, changes the sign of T :

$$T(v_1, \dots, v_i + v_j, \dots, v_i + v_j, \dots, v_n) = 0 \text{ (b/c alternating)}$$

$$\Rightarrow T(v_1, \dots, v_i, \dots, v_i + v_j, \dots, v_i + v_j, \dots, v_n) = 0 \text{ [b/c 2 terms w/ } v_i, v_j \text{ etc than } T=0]$$

$$\xi, \eta \text{ covars, skew-symm} \Rightarrow \text{alt b/c exchanging } v_i \neq v_j$$

Denote by $\Omega^k(V)$ the set of alternating tensors. $\Omega^k(V)$ is a

vector subsp of $T^k(V)$. If $f: V \rightarrow W$ is linear, $f^*: T^k(W) \rightarrow T^k(V)$ by

$$f^* T(v_1, \dots, v_k) = T(f(v_1), \dots, f(v_k)). \text{ If } T \in \Omega^k(W), \text{ then } f^* T \in \Omega^k(V),$$

since if $v_i = v_j, f(v_i) = f(v_j) \neq T$ alt. so $T=0$ $\stackrel{(f(v))}{\Rightarrow}$ then $f^* T=0$. So we have $f^*: \Omega^k(W) \rightarrow \Omega^k(V)$.

Recall, $\dim T^k(V) = n^k$ if $\dim V = n$. What is $\dim \Omega^k(V)$?

Def: Let S_k be the gp of permutations of $\{1, \dots, k\}$. For $\sigma \in S_k$, $\sigma: \{1, \dots, k\} \rightarrow \{\sigma(1), \dots, \sigma(k)\}$. $\text{sign } \sigma = (-1)^{\text{inv}}$ ($\text{inv} = \#$ of involutions to take for $(1, \dots, \sigma(k))$ to $\{1, \dots, k\}$).

S_k acts on k -vectors as $\sigma \cdot (v_1, \dots, v_k) = (v_{\sigma(1)}, \dots, v_{\sigma(k)})$.

If we compose 2 permutations, $p \neq \sigma$:

$$(p \circ \sigma)(v_1, \dots, v_k) = p(v_{\sigma(1)}, \dots, v_{\sigma(k)}) = (v_{\sigma(p(1)}, \dots, v_{\sigma(p(k))})$$

$$\stackrel{\text{inv}}{\text{inv}} \dots \stackrel{\text{inv}}{\text{inv}} \quad \text{b/c } \text{inv} \circ \text{inv} = \text{id}$$

Thus, $(p \circ \sigma)(v_1, \dots, v_k) = (v_{\sigma(p(1)}, \dots, v_{\sigma(p(k))})$ is a right action on k -vectors.

Def: Given a k -tensor T , we define its alternation, $\text{Alt}(T)$, as the tensor

$$\text{Alt}(T) = \frac{1}{k!} \sum_{\sigma \in S_k} (\text{sign } \sigma) \cdot T \circ \sigma$$

i.e., $\text{Alt}(T)(v_1, \dots, v_k) = \frac{1}{k!} \sum_{\sigma \in S_k} (\text{sign } \sigma) \cdot T(v_{\sigma(1)}, \dots, v_{\sigma(k)})$.

Ex: $k=2$: $\text{Alt}(T)(v_1, v_2) = \frac{1}{2!} [T(v_1, v_2) - T(v_2, v_1)]$

Note: If T is any tensor, $\text{Alt}(T)$ is skew-symm in every pair of entries.

Properties of Alt:

- ① If $T \in T^k(V)$, $\text{Alt}(T) \in \Omega^k(V)$.
- ② If $\omega \in \Omega^k(V)$, $\text{Alt}(\omega) = \omega$. [This is why $\frac{1}{k!}$ is necessary]
- ③ $\text{Alt}^2(T) = \text{Alt}(\text{Alt}(T)) = \text{Alt}(T)$. [Follows from 1 & 2]

PF: ① $\text{Alt}(T)(v_1, \dots, v_k) = \frac{1}{k!} \sum_{\sigma \in S_k} \text{sign}(\sigma) T(v_{\sigma(1)}, \dots, v_{\sigma(k)})$. Assume $v_i = v_j, i \neq j$.

For each $\sigma \in S_k$, consider $\sigma \circ \text{sig}$, where $\text{sig}(i) = i$, $\text{sig}(j) = j$, $\text{sig}(i) = j$, $\text{sig}(j) = i$, $\text{sign}(\sigma) = -\text{sign}(\sigma \circ \text{sig})$, but since $v_i = v_j$,

$T(v_{\sigma(1)}, \dots, v_{\sigma(k)}) = T(v_{\sigma \circ \text{sig}(1)}, \dots, v_{\sigma \circ \text{sig}(k)})$. Thus those 2 terms will vanish in the sum. But all permutations can be covered w/ this

type of pairing, so $\text{Alt}(T)(v_1, \dots, v_k) = 0$, so $\text{Alt}(T) \in \Omega^k(V)$.

② Assume $\omega \in \Omega^k(V)$.

2/2

$$\begin{aligned} \text{Alt}(\omega)(v_1, \dots, v_k) &= \frac{1}{k!} \sum_{\sigma \in S_k} \text{sign} \sigma \omega(v_{\sigma(1)}, \dots, v_{\sigma(k)}) \\ &= \frac{1}{k!} \sum_{\sigma \in S_k} \text{sign} \sigma \text{sign} \sigma \omega(v_1, \dots, v_k) \\ &= \frac{1}{k!} \cdot k! \omega(v_1, \dots, v_k) \\ &= \omega(v_1, \dots, v_k). \end{aligned}$$

) Use involutions to rearrange back to v_1, \dots, v_k , but ω is skew-symmetric, so each switch gives a minus.

③ Obvious.

Note: The tensor product of 2 alt. tensors is no longer alt.: \square

$$(\eta \otimes \omega)(v_1, \dots, v_k, v_{k+1}, \dots, v_{k+l})$$

if 2 are here, will vanish

if 2 are here, will vanish

But if $v_i = v_j$, $k \leq i < j \leq k+l$, $\eta \otimes \omega$ will not vanish.

Def: Let $\eta \in \Omega^k(V), \omega \in \Omega^l(V)$. Define the wedge product of $\eta \wedge \omega$ to be

$$\eta \wedge \omega = \frac{(k+l)!}{k!l!} \text{Alt}(\eta \otimes \omega).$$

Properties:

- (1) \wedge is bilinear. [b/c alternation is linear & \otimes is bilinear]
- (2) $f^*(\eta \wedge \omega) = (f^*\eta) \wedge (f^*\omega)$ [b/c f^* changes v_i to $f(v_i)$ but doesn't change the order]
- (3) $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$.

Pf: (3): $(\omega \wedge \eta)(v_1, \dots, v_k, v_{k+1}, \dots, v_{k+l})$

← rearrange these to be (v_{k+1}, \dots, v_k)

$$\begin{aligned} &= (-1)^k (\omega \wedge \eta)(v_{k+1}, v_1, \dots, v_k, v_{k+2}, \dots, v_{k+l}) \\ &= (-1)^{kl} (\omega \wedge \eta)(v_{k+1}, \dots, v_{k+l}, v_1, \dots, v_k) \\ &= (-1)^{kl} (\eta \wedge \omega)(v_1, \dots, v_k, v_{k+1}, \dots, v_{k+l}). \end{aligned}$$

If k is odd, then k^2 is odd, so $(-1)^{k^2} = -1$, thus $\omega \wedge \omega = -\omega \wedge \omega \Rightarrow \omega \wedge \omega = 0$. \square

Details of (2): Think of $\omega \wedge \eta$ as $\text{Alt}(\omega \otimes \eta)$ [up to constants]

$\left. \begin{array}{l} \text{Alt}(\omega \otimes \eta)(v_1, \dots, v_{k+l}, w_1, \dots, w_l) \\ \text{a sum of } \omega \otimes \eta \text{ applied to all } \\ \text{permutations of inputs} \end{array} \right\} \begin{array}{l} \text{vs. } \text{Alt}(\eta \otimes \omega)(v_1, \dots, v_k, w_1, \dots, w_l) \\ \text{so first apply } \sigma \in S_{k+l} \text{ that takes} \\ \text{1st input to 2nd input, then do sum} \\ \text{over all permutations. Thus they} \\ \text{differ only by } \text{sign}(\sigma). \end{array}$

Thm (Associativity):

(1) If $S \in T^k(V)$, $T \in T^l(V)$, with $\text{Alt}(S) = 0$, then $\text{Alt}(S \otimes T) = \text{Alt}(T \otimes S) = 0$.

(2) $\text{Alt}(\text{Alt}(S \otimes T) \otimes R) = \text{Alt}(S \otimes \text{Alt}(T \otimes R)) := \text{Alt}(S \otimes T \otimes R)$

(3) $\omega \wedge (\eta \wedge \nu) = (\omega \wedge \eta) \wedge \nu := \omega \wedge \eta \wedge \nu = \frac{\det}{k!l!} \cdot \text{Alt}(\omega \otimes \eta \otimes \nu)$

Pf:

(1) [For $\text{Alt}(T \otimes S)$] Let $H_0 \subseteq S_{k+l}$ be all perms that fix $1, \dots, l$.

$$\begin{aligned} \text{Alt}(T \otimes S)(v_1, \dots, v_k, v_{k+1}, \dots, v_{k+l}) &= \frac{1}{(k+l)!} \sum_{\sigma \in S_{k+l}} (-1)^{|\sigma|} (T \otimes S)(v_{\sigma(1)}, \dots, v_{\sigma(k+l)}) \\ \text{So, } \sum_{\sigma \in H_0} (-1)^{|\sigma|} (T \otimes S)(v_1, \dots, v_k, v_{\sigma(k+1)}, \dots, v_{\sigma(k+l)}) & \\ &= \sum_{\sigma \in H_0} (-1)^{|\sigma|} T(v_1, \dots, v_k) S(v_{\sigma(k+1)}, \dots, v_{\sigma(k+l)}) = T(v_1, \dots, v_k) \sum_{\sigma \in H_0} (-1)^{|\sigma|} S(\dots) = 0 \end{aligned}$$

Let $\sigma \notin H_0$, & let $H_1 := \sigma \cdot H_0$. (Note, $H_1 \cap H_0 = \emptyset$)

Then, similarly, we'll have $T(v_{\sigma(1)}, \dots, v_{\sigma(k)})$, constant, so can take out of \sum

$$\sum_{\sigma \in H_1} (-1)^{|\sigma|} T(v_{\sigma(1)}, \dots, v_{\sigma(k)}) \underbrace{S(v_{\sigma(k+1)}, \dots, v_{\sigma(k+l)})}_{\text{const}} = 0$$

Continue: let $\sigma_2 \notin H_0 \cup H_1$, then $\sigma_2 \cdot H_0 = H_2$, & $H_2 \cap (H_0 \cup H_1) = \emptyset$, & sum will vanish... Go on until $\cup \sigma_i H_0$ covers S_{k+l} .

Thm. (Associativity)

- (1) If $S \in T^k(V)$, $T \in T^l(V)$, \dagger $\text{Alt}(S) = 0$, then $\text{Alt}(T \otimes S) = \text{Alt}(S \otimes T) = 0$
- (2) $\text{Alt}(\text{Alt}(\omega \otimes \eta) \otimes \nu) = \text{Alt}(\omega \otimes \text{Alt}(\eta \otimes \nu)) = \text{Alt}(\omega \otimes \eta \otimes \nu)$
- (3) If $\omega \in \Omega^k(V)$, $\eta \in \Omega^l(V)$, $\nu \in \Omega^r(V)$, then

$$\omega \wedge (\eta \wedge \nu) = (\omega \wedge \eta) \wedge \nu = \omega \wedge \eta \wedge \nu = \frac{(k+l+r)!}{k!l!r!} \text{Alt}(\omega \otimes \eta \otimes \nu)$$

PF: Correction to (1): $\sigma_i \notin H$, $\sigma_j \notin \sigma_i H$, etc.

Goal: Write $S_{k+l} = H U \sigma_i H U \dots$,

Should have been $H \sigma_i$, $H \sigma_j, \dots$, etc

$$\begin{aligned} \text{(2): Let } \text{Alt}(\omega \otimes \eta) - \omega \otimes \eta &= S. \text{ Then } \text{Alt}(S) = \underbrace{\text{Alt}(\text{Alt}(\omega \otimes \eta))}_{\text{Alt}(\omega \otimes \eta)} - \text{Alt}(\omega \otimes \eta) \\ &= 0. \end{aligned}$$

From (1), we have $\text{Alt}(S \otimes \nu) = 0$. But then

$$\text{Alt}(\text{Alt}(\omega \otimes \eta) \otimes \nu) - (\omega \otimes \eta) \otimes \nu = 0, \text{ so}$$

$$\text{Alt}(\text{Alt}(\omega \otimes \eta) \otimes \nu) = \text{Alt}(\omega \otimes \eta \otimes \nu).$$

To get other equality, tensor on the left.

$$\text{(3): } \omega \wedge (\eta \wedge \nu) = \frac{(k+l+r)!}{(k!)!k!} \text{Alt}(\omega \otimes (\eta \wedge \nu))$$

$$\frac{(k+l)!}{k!l!} \text{Alt}(\eta \otimes \nu)$$

$$= \frac{(k+l+k)!}{k!l!k!} \text{Alt}(\omega \otimes \text{Alt}(\eta \otimes \nu)) \text{ (since Alt is linear)}$$

$$= \frac{(k+l+k)!}{k!l!k!} \text{Alt}(\omega \otimes \eta \otimes \nu) \text{ by (2).}$$

Similarly for $(\omega \wedge \eta) \wedge \nu$.

□

Assume $\{v_1, \dots, v_n\}$ is a basis for V . Then v_i^* goes $\Omega(V) = \tau(V) \circ V^*$

Then consider $(v_1^* \wedge \dots \wedge v_n^*)(v_1, \dots, v_n) = \frac{n!}{1!1! \dots 1!} \text{Alt}(v_1^* \otimes \dots \otimes v_n^*)(v_1, \dots, v_n)$

$$= n! \cdot \frac{1}{n!} \sum_{\sigma \in S_n} (v_1^* \otimes \dots \otimes v_n^*)(v_{\sigma(1)}, \dots, v_{\sigma(n)}) = \sum_{\sigma \in S_n} \text{Alt}(v_1^* \otimes \dots \otimes v_n^*)(v_1, \dots, v_n) = 1$$

Thus, $v_1^* \wedge \dots \wedge v_n^*$ is dual to (v_1, \dots, v_n) .

What is the dimension of $\Omega^k(V)$?

If $\dim V = n$,

Thm: Let $\{v_i\}$ be a basis for V & $\{v_i^*\}$ dual. Then

$\{v_{i_1}^* \wedge \dots \wedge v_{i_k}^*\} \mid 1 \leq i_1 < i_2 < \dots < i_k \leq n$ form a basis for $\Omega^k(V)$.

Hence $\dim \Omega^k(V) = \binom{n}{k}$.

Note: \langle b/c if any 2 are $=$, the wedge $= 0$.

ordered b/c if switch 2, just change sign so this just gets rid of repeats.

Pr: If $\omega \in \Omega^k(V) \subseteq \wedge^k(V)$, then

$$\omega = \sum_{i_1, \dots, i_k} a_{i_1, \dots, i_k} v_{i_1}^* \otimes \dots \otimes v_{i_k}^*$$

$$\omega \uparrow \text{Alt}(\omega) = \sum a_{i_1, \dots, i_k} \text{Alt}(v_{i_1}^* \otimes \dots \otimes v_{i_k}^*)$$

$$\text{b/c } \omega \in \Omega \Rightarrow \sum_{i_1, \dots, i_k} a_{i_1, \dots, i_k} \frac{1! \dots 1!}{k!} v_{i_1}^* \wedge \dots \wedge v_{i_k}^*$$

$$= \sum_{1 \leq i_1 < \dots < i_k \leq n} a_{i_1, \dots, i_k} v_{i_1}^* \wedge \dots \wedge v_{i_k}^*$$

reorganize, i.e. ignore 0's & add negatives to get v_i in increasing order

0

Notation: $(i_1, \dots, i_k) = I$ (multi-index)

$$V_i = v_{i_1} \otimes \dots \otimes v_{i_k} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{ambiguous.}$$

$$= v_{i_1} \wedge \dots \wedge v_{i_k}$$

In this class, we'll use I for wedge products only, i.e.
above = $\sum_I a_I v_I^*$ (note: understood for wedge have $1 \leq i_1 < \dots < i_k \leq n$)

Comment: $\Omega^n(\mathbb{R}^n) = n$ -forms = $v_1^* \wedge \dots \wedge v_n^*$ (if you have a basis)

note: $\dim \Omega^n(\mathbb{R}^n) = \binom{n}{n} = 1$ only

All properties of Ω^n are the props. of determinant.
if $e_1^* \wedge \dots \wedge e_n^* (e_1, \dots, e_n) = 1$, then this is exactly the determ. in terms of standard basis.

Thm: Let $\omega_1, \dots, \omega_k \in \Omega^k(V)$. Then $\omega_1, \dots, \omega_k$ are linearly independent iff $\omega_1 \wedge \dots \wedge \omega_k \neq 0$.

[In this sense, it's generalizing the determinant]

Pf: (\Leftarrow): If $\omega_1 \wedge \dots \wedge \omega_k \neq 0$, then $\{ \omega_i \}$ are independent, since otherwise $\omega_i = \sum_{j \in I} \omega_j \alpha_j$, $\nexists \omega_1 \wedge \dots \wedge \omega_k = 0$ (b/c will always have repeated index)

(\Rightarrow): If $\omega_1, \dots, \omega_k$ are lin. independent, consider their duals, $\omega_i^* \in V$, which are also independent. Then we can extend them to a basis $\{v_i\}_{i=1}^n$, $v_i = \omega_i^* \quad i=1, \dots, k$. Then $(\omega_1 \wedge \dots \wedge \omega_k)(v_1, \dots, v_k) = 1 \neq 0$, so $\omega_1 \wedge \dots \wedge \omega_k \neq 0$.

Note: To check $\{v_1, \dots, v_k\}$ are independent, calculate $v_1^* \wedge \dots \wedge v_k^*$.

Thm: (Change of basis) Let $\{v_i\}_{i=1}^n$ be a basis for V , $\omega \in \Omega^n(V)$, \nexists let $\{u_i\}$ be a different basis, $u_i = \sum_{j=1}^n \alpha_{ij} v_j$. Then $\omega(u_1, \dots, u_n) = \det(\alpha_{ij}) \omega(v_1, \dots, v_n)$.

Pf: Define $\eta \in \Omega^n(\mathbb{R}^n)$ as $\eta(\vec{e}_1, \dots, \vec{e}_n) = \eta \left(\begin{pmatrix} a_{11} \\ \vdots \\ a_{1n} \end{pmatrix}, \dots, \begin{pmatrix} a_{n1} \\ \vdots \\ a_{nn} \end{pmatrix} \right)$

$= \omega(a_{11}v_1 + a_{21}v_2 + \dots + a_{n1}v_n, \dots, a_{1n}v_1 + \dots + a_{nn}v_n)$

$\eta \in \Omega^n(\mathbb{R}^n) \Rightarrow \eta = c \det$, so $\eta(\vec{a}_1, \dots, \vec{a}_n) = c \det(\vec{a}_1, \dots, \vec{a}_n)$. To find c ,

$\eta(\vec{e}_1, \dots, \vec{e}_n) = c \cdot 1$

$\omega(v_1, \dots, v_n)$

$\Rightarrow \omega(u_1, \dots, u_n) = c \cdot \det(a_1, \dots, a_n) = \omega(v_1, \dots, v_n) \cdot \det(a_{ij})$. □

Ex: If we use $\Omega^n(V)$, $\omega \neq 0$, then we can orient V by stating $\{v_1, \dots, v_n\}$ is positively or $\Leftrightarrow \omega(v_1, \dots, v_n) > 0$.

Pf: ω preserves orientation, since 2 bases have same or. $\Leftrightarrow \det(a_{ij}) > 0$, so by formula above, ω keeps same sign on both bases. □

Homework Ch. 6 # 1, 3; Ch. 5 # 7, 10, 11, 13, 14(b) [conv. vect. field only]; 2 more Frobenius problems via email.

Due: Thurs. Nov. 6

(E, \mathbb{R}, π)
 Let ξ be a bundle. Define $\Omega^k(\xi)$ to be the bundle for which the fibers are $\Omega_p^k(\pi^{-1}(p))$. This construction is identical to that of $T^k(\xi)$ [the tensor bundle]. [where $\cup \Omega_p^k(\pi^{-1}(p)) = \Omega^k(\xi)$]
 A section of $\Omega^k(\xi)$ is a map $B \xrightarrow{\xi} \Omega^k(\xi)$. If we have 2 sections $\omega: B \rightarrow \Omega^k(\xi) \neq \eta: B \rightarrow \Omega^k(\xi)$, we can define the wedge product pointwise:
 $(\omega \wedge \eta)(p) = \omega(p) \wedge \eta(p)$.

Since $\omega(p) \in \Omega^k(\pi^{-1}(p))$, $\eta(p) \in \Omega^k(\pi^{-1}(p))$, so
 $\omega \wedge \eta: B \rightarrow \Omega^{2k}(\xi)$.

If $E = TM$, a section ω is called a k-form.

Vol $\pi^{-1}(DN)$

$$0 \Leftrightarrow v_i \text{ dup.}$$

$\dim V = n$, $v_i \in V$, $v_1^* \wedge \dots \wedge v_n^* \in \mathbb{R}^n$ are these the minors?

Fix a basis $\{e_i\}$ in \mathbb{R}^n . Then $\{e_{i_1}^* \wedge \dots \wedge e_{i_k}^*\}$ a basis.

Those match exactly the minors

(take the i_1, \dots, i_k rows)

$$\text{So } v_1^* \wedge \dots \wedge v_n^* = \sum_{\substack{\text{minors} \\ i_1, \dots, i_n}} c_{i_1, \dots, i_n} e_{i_1}^* \wedge \dots \wedge e_{i_n}^*$$

Let $V = \text{span}\{v_1, \dots, v_k\} \subseteq \mathbb{R}^n$, a k -dim subsp, so $\forall e \in \mathbb{R}^n$

$V \rightarrow [v_1^* \wedge \dots \wedge v_k^*]$, called Plucker coords.

(projection)

Last Time we defined $\Omega^k(TM)$.

Thm (Pullback Locality): Let $f: M \rightarrow N$, $(x, U), p \in U$, $(y, V), f(p) \in V$.

Then $f^*(g dy_1 \wedge \dots \wedge dy_n) = g \circ f \det \left(\frac{\partial y_i \circ f}{\partial x_j} \right) dx_1 \wedge \dots \wedge dx_n$.

Pf: $f^*(g dy_1 \wedge \dots \wedge dy_n) = g \circ f \det \left(\frac{\partial y_i}{\partial x_1}, \dots, \frac{\partial y_i}{\partial x_n} \right) = g \circ f dy_1 \wedge \dots \wedge dy_n (f_* \frac{\partial}{\partial x_1}, \dots, f_* \frac{\partial}{\partial x_n})$

$$= g \circ f dy_1 \wedge \dots \wedge dy_n \left(\sum_i \frac{\partial y_i \circ f}{\partial x_1} \frac{\partial}{\partial x_1}, \dots, \sum_i \frac{\partial y_i \circ f}{\partial x_n} \frac{\partial}{\partial x_n} \right)$$

$$= g \circ f \det \left(\frac{\partial y_i \circ f}{\partial x_j} \right) dy_1 \wedge \dots \wedge dy_n \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right) \text{ by change of basis formula.}$$

$$\text{So } f^*(g dy_1 \wedge \dots \wedge dy_n) = g \circ f \det \left(\frac{\partial y_i \circ f}{\partial x_j} \right) dx_1 \wedge \dots \wedge dx_n.$$

$$\text{(Recall, } \det \Omega^k(M) = \binom{n}{k} = 1) \quad \text{b/c this applied to } \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right) = 1.$$

(Change of variable - in n-forms)

Cor: If $(x, U), (y, V)$ are 2 coordinate systems around $p \in U$.

$f = \mathbb{1}$, then if

$$\omega = g dy_1 \wedge \dots \wedge dy_n = h dx_1 \wedge \dots \wedge dx_n, \text{ then}$$

$$h = g \det \left(\frac{\partial y_i}{\partial x_j} \right).$$

Pf: Follow $f = \mathbb{1}$ in thm.

□

Let ω be an n -form. It can be applied to n -vectors in tangent:

Say $\omega(p)(v_1, \dots, v_n) \neq 0$. It behaves like \det (if switch v_i, v_j , sign ^{switches})

$v_i \in T_p M$ ω usually use \det to orient vectors, so lets use $\omega(p)$ to orient vectors — need $\omega(p) \neq 0$ everywhere — \nexists make signs to match everywhere, so can patch it up. \hookrightarrow b/c $\omega(p)$ dts \nexists changes sign.

Thm: Let M be a C^∞ -mfd. M is orientable $\Leftrightarrow \exists$ a nonvanishing C^∞ n -form (i.e. $\omega(p) \neq 0 \forall p$)

\hookrightarrow i.e. $\neq 0$ when apply to basis. Well, of course, $= 0$ when applied to dependent vectors.

Pf: (\Leftarrow): HD: (in abld U)

(\Rightarrow): Locally, we know that we have ω_U w/ $\omega_U(p) \neq 0$. For $u \in U$, choose $\omega_U = dx_1 \wedge \dots \wedge dx_n$. ($\neq 0$ b/c applied to $(\partial/\partial x_1, \dots, \partial/\partial x_n)$ get 1.)

(The only way $\partial/\partial x_1, \dots, \partial/\partial x_n$ can vanish is if \nexists vanishes somewhere.)

Cover M w/ an oriented atlas. (i.e. the \det of change-of-coord is \pm)

Then all ω_U are going to give the same orientation, as $\det(\partial/\partial x_i) > 0$. Now we need to patch this together:

Let $\{U_\alpha\}$ be a partition of unity assoc. to the atlas. $\{x_\alpha\}$

Define $\omega = \sum_{\alpha} \chi_\alpha \omega_U$. Then

$$\omega(p) = \sum_{\alpha} \chi_\alpha(p) \omega_U(p) > 0 \text{ b/c } \chi_\alpha(p) > 0 \text{ } \forall p \in U. \text{ } p \in U \text{ for at}$$

least one U , so there's either one U ,

so $\neq 0$. Also $\chi_\alpha(p) \geq 0$ (whether or not $p \in U$). Thus, one term is > 0 & rest

are $\geq 0 \Rightarrow \omega(p) > 0$.

Alternatively, if $\{v_1, \dots, v_n\}$ is a basis for $T_p M$, $\nexists p \in U$, then

$\omega_U(p)(v_1, \dots, v_n) \neq 0$ since $\omega_U(p) \neq 0$. But $\chi_\alpha(p) \geq 0$ & $\chi_\alpha(p) \neq 0$ if

$p \in U$, so $\omega(p)(v_1, \dots, v_n) \neq 0$. $\hookrightarrow \nexists$ either > 0 or < 0 for all bases. \square

Def of Differential

By def, a 0-form is a fun $f: M \rightarrow \mathbb{R}$, i.e. $\Omega^0(M) = C^0(M)$.

Locally

Given a 0-form f , we define a 1-form $df = \sum \frac{\partial f}{\partial x_i} \cdot dx_i$, a local section of $\Omega^1(M) = T^*M$.

Q: Can we define $d: \Omega^k(M) \rightarrow \Omega^{k+1}(M) \forall k$?

Assume $\omega = \sum a_I dx_I$ is a C^∞ k-form, $p \in U$. Define

$$d\omega(p) = \sum_{I \in \mathcal{I}} \sum_{i=1}^n \frac{\partial a_i}{\partial x_i} dx_i \wedge dx_I = \sum_I da_I \wedge dx_I.$$

Properties:

- (1) $d(\omega_1 + \omega_2) = d\omega_1 + d\omega_2$
- (2) If ω_1 is a k-form, then $d(\omega_1 \wedge \omega_2) = d\omega_1 \wedge \omega_2 + (-1)^k \omega_1 \wedge d\omega_2$.
 we use def of exterior, & need to move it all the way back
- (3) $d^2 = 0$
- (4) $df = \text{classical } df$ (as above)
 $= \sum \frac{\partial f}{\partial x_i} dx_i$

PF: (1) Obvious.

(2) If $\omega_1 = \sum a_I dx_I$, then $\omega_2 = \sum b_J dx_J$

$$\omega_1 \wedge \omega_2 = \sum_{I,J} a_I b_J dx_I \wedge dx_J$$

$$\text{So } d(\omega_1 \wedge \omega_2) = \sum_{I,J} \left(\frac{\partial a_I}{\partial x_k} dx_k \wedge dx_I \wedge dx_J + \frac{\partial b_J}{\partial x_k} dx_k \wedge dx_I \wedge dx_J \right)$$

multiplication in terms, so around can move dx_k by around

need to move dx_k to get dx_{k2}

$$= d\omega_1 \wedge \omega_2 + (-1)^k \omega_1 \wedge d\omega_2$$

$$(3) d^2 \omega = d(\sum_I \sum_j \frac{\partial a_i}{\partial x_j} dx_i \wedge dx_j)$$

$$= \sum_I \sum_{i=1}^k \sum_{j=1}^k \frac{\partial^2 a_i}{\partial x_j \partial x_i} \underbrace{dx_j \wedge dx_i}_{\text{not ordered}} \wedge dx_I$$

These come in pairs given by

$$\frac{\partial^2 a_i}{\partial x_j \partial x_i} dx_j \wedge dx_i + \frac{\partial^2 a_i}{\partial x_i \partial x_j} dx_i \wedge dx_j = 0 \quad \& \quad dx_i \wedge dx_i = 0$$

So sum = 0.

Prop: Assume there is d' : $\Omega^k(U) \rightarrow \Omega^{k+1}(U)$ that satisfies properties (1) \rightarrow (4). Then $d' = d$ on $U \setminus M$. □

Pf: From (1) (linearity), we can assume $\omega = a_I dx_I$.

From (2) (product rule), $\omega = a_I \wedge dx_I$ $\&$ so

\uparrow
0-form

$$d\omega = d'a_I \wedge dx_I + (-1)^{|a_I|} a_I d'(dx_I).$$

From (4) $d'a_I = da_I$ (they are both the classical one), so we only need to check that $d'(dx_I) = 0$, $\&$ then $d'\omega = da_I \wedge dx_I = d\omega$.

$$d'(\underbrace{dx_1 \wedge dx_2 \wedge \dots \wedge dx_k}_{\text{rule}}) \stackrel{\text{prod.}}{=} (d')^k x_1 \wedge dx_2 \wedge \dots \wedge dx_k - dx_1 \wedge d'(dx_2 \wedge \dots \wedge dx_k)$$

\uparrow
We coincide on terms

$$= 0 - dx_1 \wedge d'((k-1)\text{-form}).$$

\uparrow
($k-1$)-form

By induction: $d'(d'f) = d'^2 f = 0$.

So if $d'(dx_1 \wedge \dots \wedge dx_k) = 0 \Rightarrow d'(d\omega^k) = 0$, from induction step above, for any $(k-1)$ -form $\&$ for any k -form.

Thus $d'\omega = d\omega$

□

Cor: \exists a 1 operator $d: \Omega^k(U) \rightarrow \Omega^{k+1}(U)$ w/ properties (1)-(3) = (4).

Pf: Choose an atlas $\{ (x, U) \}$, construct the unique local d_U on U , & define $(d\omega)(p) = d_U(\omega)|_p$. Well-def. b/c \mathcal{B} unique on $U \cap V$.

Coordinate free def of d : Given ω a k -form we define $d\omega$ as the

($k+1$)-form

$$d\omega(X_1, \dots, X_{k+1}) = \sum_{i=1}^{k+1} (-1)^{i+1} X_i(\omega(X_1, \dots, \hat{X}_i, \dots, X_{k+1}))$$

+ $\sum_{1 \leq i < j \leq k} (-1)^{i+j} \omega([X_i, X_j], X_1, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_{k+1})$.

k forms, globally, are multi-vert to mult. by forms \rightarrow must be \mathbb{R} fields, i.e. a form on k vect. fields so that it makes sense, since vect fields, X_i take forms as input.

Recall $ad_X(\partial_X) = \alpha$, a form \rightarrow gives a form

Thm: Both (local & global) definitions of d coincide.

Pr: we need to prove:

- (1) $d\omega$ is a form
- (a) $d\omega$ is multilinear w.r.t $C^\infty(M)$ multiplication (w.r.t to sum is obvious)
- (b) $d\omega$ is alternating (i.e. if $X_i = X_j$, $d\omega(X_1, \dots, X_{k+1}) = 0$)

(2) Both defs coincide locally.

Pr of (1):

(a) Consider fX_i in the def of $d\omega$.

$$d\omega(X_1, \dots, fX_r, \dots, X_{k+1}) = f \underbrace{[(-1)^{r+1} X_r(X_1, \dots, \hat{X}_r, \dots, X_{k+1})]}_{i.e. r, dr, b/c the f came out} + \dots$$

Look at $i \neq r$ in first sum: can pull f out of $d\omega$, so have $f\omega$, so we product rule.

$$\downarrow$$
 1st sum = $\sum_{i \neq r} X_i(f) \omega(X_1, \dots, \hat{X}_i, \dots, X_{k+1}) + \sum_{i=r} (-1)^{i+1} f X_i(\omega(X_1, \dots, \hat{X}_i, \dots, X_{k+1}))$

2nd sum = $\sum_{1 \leq i < j \leq n} (-1)^{i+j} f \omega([X_i, X_j], X_1, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_{k+1})$ [ok, f comes out of $d\omega$]

+ $\sum_{i < r} (-1)^{i+r} \omega([X_i, fX_r], X_1, \dots, \hat{X}_i, \dots, \hat{X}_r, \dots, X_{k+1})$ (*)

+ $\sum_{(i \neq r)} (-1)^{r+i} \omega([fX_r, X_i], X_1, \dots, \hat{X}_i, \dots, \hat{X}_r, \dots, X_{k+1})$ (**)

1st term of 2nd sum - from pulling out the commutators from rule before

$$= \sum_{1 \leq i < j \leq r} (-1)^{i+j} \omega(\delta_{X_i, X_j}) + \sum_{1 \leq i < r} (-1)^{i+r} \omega(X_i(f) X_r, X_{i+1}, \dots, \hat{X}_i, \dots, X_{r+1}) + \sum_{1 \leq j < r} (-1)^{r+j} \omega(-X_j(f) X_r, X_1, \dots, \hat{X}_j, \dots, X_{r+1})$$

* using $[gX, Y] = gXY - Y(gX) = g[X, Y] - Y(g)X \stackrel{\text{distributive}}{=} X(g)Y - gYX = X(g)Y + g[X, Y]$

Now just rearrange:

$$= f \sum_{1 \leq i < j \leq r} (-1)^{i+j} \omega([X_i, X_j], X_{i+1}, \hat{X}_i, \dots, \hat{X}_j, \dots, X_{r+1}) \{ (1) + \sum_{1 \leq i < r} (-1)^{i+r} X_i(f) (-1)^{r-i} \omega(X_{i+1}, \hat{X}_i, \dots, X_{r+1}) + \sum_{1 \leq j < r} (-1)^{r+j} X_j(f) (-1)^{r-j} \omega(X_1, \dots, \hat{X}_j, \dots, X_{r+1}) \}$$

$$= (1) + \sum_{1 \leq i < r} (-1)^i X_i(f) \omega(X_{i+1}, \hat{X}_i, \dots, X_{r+1}) + \sum_{1 \leq j < r} (-1)^j X_j(f) \omega(X_1, \dots, \hat{X}_j, \dots, X_{r+1})$$

$$= (1) + \sum_{i \neq r} (-1)^i X_i(f) \omega(X_1, \dots, \hat{X}_i, \dots, X_{r+1}) \quad \leftarrow \text{exactly the opposite of first term of 1st sum.}$$

TR_{2n}

$$\text{dw}(X_{k_1}, \dots, X_{k_n}) = 1^{\text{st}} \text{ sum} + 2^{\text{nd}} \text{ sum}$$

$$= 2^{\text{nd}} \text{ half of } 1^{\text{st}} \text{ sum} + (1) = f \text{ dw}(X_1, \dots, X_{k_n}) \checkmark$$

(b) Assume $X_r = X_s$, $r \neq s$, $r < s$.

If $i \neq r, s \neq j$, then the sum in def. will vanish, since ω is alternating. We need to check in the first sum:

$$(-1)^{r+1} X_r(\omega(X_1, \dots, \hat{X}_r, \dots, X_s, \dots, X_{k_n})) + (-1)^{s+1} X_s(\omega(X_1, \dots, \hat{X}_s, \dots, X_r, \dots, X_{k_n}))$$

so there are same, but $X_r = X_s$ is in diff. positions, so rearrange the 1st - have to move X_s to place r , move $s-r-1$ spots. So have $(-1)^{r+1} (-1)^{s-r-1} = (-1)^s \neq$ thus the 2 have opp signs, so = 0.

So 1st sum = 0.

In 2^n sum:

-if take out both $X_r \hat{=} X_s$, i.e. $i=r \hat{=} j=s$, then $[X_i, X_j] = 0$, so that term would be 0.

-if $i+r \neq s+j$, then those terms = 0 b/c ω alternating.

-if one is 0 or r : \leftarrow has X_s

$i=r$ $\sum_{1 \leq r < j \leq n} (-1)^{r+j} \omega([X_r, X_j], X_{i_1}, \dots, \hat{X}_r, \dots, X_{i_n})$ } Only terms that remain are those w/ $r < j \leq s$, since

$i=s$ $\sum_{1 \leq s < j \leq n} (-1)^{s+j} \omega([X_s, X_j], X_{i_1}, \dots, \hat{X}_s, \dots, X_{i_n})$ } for $j > s$ = same as above - have same X_s 's, but not in same place, so Σ 's cancel.

$j=r$ $\sum_{1 \leq i < r \leq n} (-1)^{i+r} \omega([X_r, X_i], X_{i_1}, \dots, \hat{X}_r, \dots, X_{i_n})$ } $i < r$, 2 sums = w opp signs, so cancel as above

$j=s$ $\sum_{1 \leq i < s \leq n} (-1)^{s+i} \omega([X_i, X_s], X_{i_1}, \dots, \hat{X}_i, \dots, X_{i_n})$ } So only terms left are for $r < i < s$.

$[n = k+1]$

$$= \sum_{1 \leq r < s \leq n} (-1)^{r+s} \omega([X_r, X_s], X_{i_1}, \dots, \hat{X}_r, \dots, \hat{X}_s, \dots, X_{i_n})$$

$$+ \sum_{1 \leq r < i < s \leq n} (-1)^{s+i} \omega([X_i, X_s], X_{i_1}, \dots, \hat{X}_i, \dots, \hat{X}_s, \dots, X_{i_n})$$

$[X_i, X_s] = -[X_s, X_i]$ } when we move X_s to r position, we have one more term than before b/c need to go over X_i which is missing

Thus, after reorganizing, we have opp. signs, so the whole sum = 0.

(2) Since d is linear, we can assume $\omega = a_1 dx_1 + \dots + a_n dx_n$. For simplicity, assume $dx_1 = a_1 dx_1 + \dots + a_n dx_n$, so $\omega = a_1 dx_1 + \dots + a_n dx_n$.

$$(d\omega)_{X_{i_1}, \dots, X_{i_n}} = \sum_{1 \leq i < j \leq n} (-1)^{i+j} \frac{\partial^2 \omega}{\partial X_i \partial X_j} (X_{i_1}, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_{i_n})$$

Note: $[\frac{\partial}{\partial X_i}, \frac{\partial}{\partial X_j}] = 0$, so bracket part of sum = 0

Then $\omega(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_r}, \dots, \frac{\partial}{\partial x_{k_1}})$ are all 0 unless $(i_1, \dots, i_{r-1}) = (1, \dots, k, s) \gg k$.
 $[i_1 < \dots < i_{k+1}]$

In order to not vanish, need to take out the s .

$$\text{If } s \gg k = (-1)^{\sum_{i=1}^{r-1} i} \left(\omega \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_k}, \frac{\partial}{\partial x_s} \right) \right)$$

the position of the one you remove + 1

$$= (-1)^k \frac{\partial \alpha_I}{\partial x_s}$$

$$\text{So } d\omega(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_k}, \frac{\partial}{\partial x_s}) = (-1)^k \frac{\partial \alpha_I}{\partial x_s}$$

$$\text{So } d\omega = \sum_{s \gg k} (-1)^k \frac{\partial \alpha_I}{\partial x_s} dx_1 \dots dx_k dx_s$$

$$= \sum_{s \gg k} (-1)^k \frac{\partial \alpha_I}{\partial x_s} dx_s dx_1 \dots dx_k$$

[but, all other values of s will vanish]

$$= \sum_{s=1}^n \frac{\partial \alpha_I}{\partial x_s} dx_s dx_1 \dots dx_k$$

$$= d\alpha_I \wedge dx_1 \wedge \dots \wedge dx_k \quad \checkmark$$

For $k=1$,

$$d\omega(x_1, x_2) = X_1(\omega(x_2)) - X_2(\omega(x_1)) - \omega([X_1, X_2])$$

□

Def: Let $\Omega(M)$ be the ring of all forms on M (with \wedge).

Let $\Delta^\circ \subseteq \Omega(M)$ be $\Delta^\circ = \{ \omega \in \Omega(M) \mid \text{if } \omega \text{ is an } r\text{-form,}$

$$\omega(x_1, \dots, x_r) = 0 \text{ whenever } x_i \in \Delta \forall i \}$$

Δ° is called the annihilator of Δ .

Δ° is an ideal, since if $\omega \in \Delta^\circ$, then $\eta \wedge \omega \in \Delta^\circ \forall \eta \in \Omega(M)$

Thm (Frobenius, 2nd version) Δ is integrable $\Leftrightarrow d\Delta^\circ \subseteq \Delta^\circ$

11/4 - DM (Arnold - Ch. 8 - Hrbf. Methods of Classical Mechanics - Symplectic)

Frobenius Thm (2nd version): Let Δ be a C^1 -distribution. Then Δ is integrable $\Leftrightarrow d\Delta^0 \subseteq \Delta^0$

1. integrable $\Leftrightarrow d\Delta^0 \subseteq \Delta^0$

Pr: Let $\{X_i\}_{i=1}^k$ be generators of Δ and extend them to a basis for $T_u M$, ($i=1, \dots, n$) & let $\{w_j\}$ be the basis dual to $\{X_j\}$, so w_1, \dots, w_n generate Δ^0 .

In coords: choose coords so that $\frac{\partial}{\partial x_i} |_{i=1, \dots, k}$ gen. Δ . We can always do this at u -pt - in a nbhd $\Leftrightarrow \Delta$ integrable. Then

$(dx_1 \wedge \dots \wedge dx_k)(p) \neq 0$ since $(dx_1 \wedge \dots \wedge dx_k) |_{p=1}$. By continuity, $(dx_1 \wedge \dots \wedge dx_k)(q) \neq 0$ on $U \subseteq \mathbb{R}^n$. Thus, $\{dx_i\}$ are independent on Δ . Therefore, $dx_j = \sum_{i=1}^k a_{ij} dx_i$, $j=k+1, \dots, n$, on Δ .
 $\Rightarrow dx_j - \sum_{i=1}^k a_{ij} dx_i = w_j$ generate Δ^0 . The annihilator of Δ , $j=k+1, \dots, n$.

Note: $\{dx_1, \dots, dx_k, w_{k+1}, \dots, w_n\}$ basis for $T_u^* M$.
 distribution annihilator

Reverse: $dw_j(X_r, X_s) = X_r(w_j(X_s)) - X_s(w_j(X_r)) = w_j([X_s, X_r])$, $i=r, s, n$

If $r, s < k$, so $\{X_i\}_{i=1}^k$ gen Δ , then
 $dw_i(X_r, X_s) = X_r(w_i(X_s)) - X_s(w_i(X_r)) = -w_i([X_s, X_r])$.

Then $dw_i(X_r, X_s) = 0 \Leftrightarrow w_i([X_s, X_r]) = 0$, since w_i gen the annihilator Δ^0 .
 w_i gen Δ^0 .
 \square

In coords, how can we tell if $d\Delta^0 \subseteq \Delta^0$? Note: Δ^0 a C^1 ing, not a v.s.

Assume $\{w_1, \dots, w_k, w_{k+1}, \dots, w_n\}$ is chosen as before. Then, for $i=k+1, \dots, n$,
 $dw_i = \sum_{j=1}^k a_{ij} w_j$, $a_{ij} = \sum_{q=1}^k \theta_j^q a_{iq} w_i$.

If $d\Delta^0 \subseteq \Delta^0$, then $dw_i(X_i, X_j) = 0$ when $i < j \leq k$. So,

$$dw_i(X_i, X_j) = \theta_j^i \sum_{s=1}^k a_{is} w_s(X_i, X_j) - w_i \wedge \theta_j^i(X_i, X_j)$$

But $\theta_j^i(X_j) = 0$ b/c $\theta_j^i(X_j) = \sum_{s < i} a_{is}^j w_s$, but $s < i < j$, so $w_s(X_j) = 0$. v.s

$$\text{then } dw_i(X_i, X_j) = \theta_j^i(X_j) = 0 \quad \forall i < j. \quad (\text{b/c } d\Delta^0 \subseteq \Delta^0)$$

But by def, $\theta_j^i = \sum_k a_k^i \omega_k$, so if $\theta_j^i(x_k) = 0$ for all $i < j$, then $a_k^i = 0 \forall i < j$ (w/c $\omega_j(x_k) = 1$). Thus, $\theta_j^i = 0, \forall i < j$.

Therefore, $\boxed{d\omega_j = \sum_{i=1}^n \theta_j^i \wedge \omega_i}$ ← this is what it means for $d\Delta^n \subseteq \Delta^n$.

Prop: $d(f^* \omega) = f^* d\omega$.

PF: For 0-forms, $d(f^* g) = f^* dg$:

$$d(f^* g) = d(g \circ f)$$

$$f^* dg(x) = dg(f_x(x)) = (f_x(x))(g) = X(g \circ f) = d(g \circ f)(x) \checkmark$$

It suffices to check $\omega = \alpha_I dx_I$.

$$d\omega = d\alpha_I \wedge dx_I$$

$$f^* d\omega = f^*(d\alpha_I) \wedge f^*(dx_I)$$

$$= d(f^* \alpha_I) \wedge f^*(dx_I)$$

$$= d(f^* \alpha_I \wedge dx_I) = d(f^* \omega)$$

Def: We say a form ω is closed if $d\omega = 0$. ω is exact if $\omega = d\theta, \theta \in \Omega^{k-1}$ -form.

Note: exact \Rightarrow closed (b/c $d^2 = 0$)

• in general, closed \neq exact:

Let $\omega = \frac{-y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$ (the differential of the \neq on the plane).

$$d\omega = \frac{\partial}{\partial y} \left(\frac{-y}{x^2+y^2} \right) dy \wedge dx + \frac{\partial}{\partial x} \left(\frac{x}{x^2+y^2} \right) dx \wedge dy$$

$$= \left[\frac{-1}{x^2+y^2} + \frac{2y^2}{(x^2+y^2)^2} \right] dy \wedge dx + \left[\frac{1}{x^2+y^2} - \frac{2x^2}{(x^2+y^2)^2} \right] dx \wedge dy$$

$$\frac{-x^2+y^2}{(x^2+y^2)^2}$$

but θ is not cons. (c/o for any θ)

$= 0 \Rightarrow \omega$ closed.

$$\text{If } \omega = d\theta = \frac{\partial \theta}{\partial x} dx + \frac{\partial \theta}{\partial y} dy \Rightarrow \frac{\partial \theta}{\partial x} = \frac{-y}{x^2+y^2} \Rightarrow \theta(x,y) = \tan^{-1}\left(\frac{y}{x}\right) + C(y)$$

$$\frac{-y}{x^2+y^2} \quad \frac{x}{x^2+y^2} \quad \text{But } \frac{\partial \theta}{\partial y} = \frac{x}{x^2+y^2} + C'(y) \Rightarrow C(y) = C.$$

The problem is that the domain of ω does not include $(0,0)$.

Def: M is smoothly contractible to \mathbb{R}^n if $\exists \gamma: \mathbb{R}^n \xrightarrow{c_0} M$ $H: M \times \mathbb{D}_r \times \mathbb{D}_r \rightarrow M$
 with $H(p,0) = p_0$ & $H(p,1) = p$. $(p,t) \mapsto H(p,t)$

Ex: Star-shaped region: A region in \mathbb{R}^n is called star-shaped if $\exists p_0 \in M$ s.t. $\forall p \in M$:

- Clearly, a star-shaped region is contractible since we can define $H: M \times \mathbb{D}_1 \times \mathbb{D}_1 \rightarrow M$



$$(p,t) \mapsto \text{Path}(p,p_0)$$

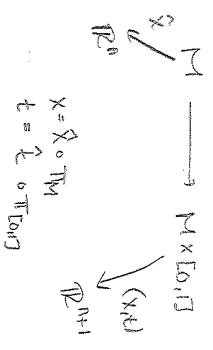
Define: $i_s: M \rightarrow M \times \mathbb{D}_1 \times \mathbb{D}_1$, $p \mapsto (p,s)$

Lemma: If ω is a closed 1-form on $M \times \mathbb{D}_1 \times \mathbb{D}_1$, then $i_1^* \omega - i_0^* \omega$ is exact

Pr: Idea: find a transformation $I(\omega)$ s.t.

$$i_1^* \omega - i_0^* \omega = d(I(\omega)) - I(d\omega), \text{ Then if } \omega \text{ is closed, get } i_1^* \omega - i_0^* \omega = d(I(\omega)), \text{ so exact.}$$

Assume ω is a 1-form. In coordinates:



It suffices to assume $\omega = \sum \omega_i dx_i + f dt$.

$$i_s^* \omega = \sum i_s^* (\omega_i) i_s^* dx_i + i_s^* f dt$$

\Rightarrow by time is constant when pull back:

$$i_s^* (f dt) = f dt (i_s^* X) = 0 \text{ (depends only on } X \text{)}$$

$$\Rightarrow i_s^* \omega(p) = \sum i_s^* \omega_i (i_s^* dx_i) = \sum \omega_i(p,s) i_s^* dx_i = \sum dx_i \left(\frac{\partial \omega_i}{\partial x_i} \Big|_p \right)$$

$$(i_s^* \frac{\partial}{\partial \tilde{x}_i} |_{p_i}) (F(q, t)) = \frac{\partial}{\partial \tilde{x}_i} |_{p_i} (F(q, s)) = \frac{\partial}{\partial x_i} |_{p_i} (F(q, s)), \quad \text{so}$$

$$i_s^* (\frac{\partial}{\partial \tilde{x}_i} |_{p_i}) = \frac{\partial}{\partial x_i} |_{p_i}, \quad \Rightarrow (i_s^* dx_i) (\frac{\partial}{\partial \tilde{x}_i}) = dx_i (\frac{\partial}{\partial x_i}) = 1, \quad \text{so } i_s^* dx_i = d\tilde{x}_i.$$

$$\text{Thus, } (i_s^* \omega)(p_i) = \sum w_i(p_i) d\tilde{x}_i.$$

From here,

$$i_s^* \omega - i_s^* \omega = \sum [w_i(p_i) - w_i(p_i)] d\tilde{x}_i.$$

If ω is closed, $dw = 0$, and then:

$$dw = \sum_{i=1}^n w_i \wedge dx_i + dF \wedge dt$$

$$= \sum_{i=1}^n \frac{\partial w_i}{\partial t} dt \wedge x_i + \sum_{i=1}^n \frac{\partial F}{\partial x_i} dx_i \wedge dt + \text{terms w/ no } dt.$$

Lemma: If ω is a closed 1-form on $M \times \mathbb{R}$, then $i^* \omega - i_0^* \omega$ is exact, where $i_0: M \rightarrow M \times \mathbb{R}$, $p \mapsto (p, 0)$.

Pf: Coordinates

$$M \rightarrow M \times \mathbb{R} \times \mathbb{R} \\ \downarrow \pi \quad \downarrow \text{pr}_1 \\ \mathbb{R}^n \quad \mathbb{R}^{n+1} \\ \begin{matrix} x = \hat{x} \circ \pi \\ t = t \circ \text{pr}_1 \end{matrix}$$

Assume $\omega = \sum_{i=1}^n \omega_i dx_i + f dt$, then $i_0^* \omega = \sum_{i=1}^n \omega_i \Big|_{t=0}$

$i^* \omega = \sum_{i=1}^n \omega_i(x, t) dx_i + f(x, t) dt$. (recall, dt disappears b/c $i_0^* dt = 0$)

So $i_0^* \omega - i^* \omega = \sum_{i=1}^n (\omega_i(p, 0) - \omega_i(x, t)) dx_i$.

ω is closed \forall $d\omega = 0$, ∇

$$d\omega = \sum_{i=1}^n \frac{\partial \omega_i}{\partial x_j} dx_j \wedge dx_i + \sum_{i=1}^n \frac{\partial f}{\partial x_i} dx_i \wedge dt + \sum_{i=1}^n \frac{\partial \omega_i}{\partial t} dt \wedge dx_i$$

If $d\omega = 0$, then $\frac{\partial \omega_i}{\partial t} = 0$, from the last 2 terms above, $\forall i$.

So since $i_0^* \omega - i^* \omega = \sum_{i=1}^n \int_0^t \frac{\partial \omega_i}{\partial t}(p, s) ds dx_i = \sum_{i=1}^n \int_0^t \frac{\partial f}{\partial x_i}(p, s) ds dx_i$.

If $\omega = \sum_{i=1}^n \frac{\partial g}{\partial x_i} dx_i$, then $i_0^* \omega - i^* \omega = dg$. To show this, let

$$g = \int_0^1 f(p, s) ds, \text{ we write } \frac{\partial g}{\partial x_i} = \int_0^1 \frac{\partial f}{\partial x_i}(p, s) ds, \text{ so, then done.}$$

$$\frac{\partial f}{\partial x_i}(p) = D_i (g \circ \hat{x}^{-1}) = D_i \left(\int_0^1 f(\hat{x}^{-1}(p, s)) ds \right) = \int_0^1 D_i f(\hat{x}^{-1}(p, s)) ds$$

← since x just projection then \hat{x} .

So $(x, t)(a, s) = (x, a, s)$

The form f , & hence g , does not depend on the coordinate, since

$$T(M \times \mathbb{R}) = \ker(\pi_*) \oplus \ker(\pi_{\mathbb{R}})_*, \text{ so } \omega: M \times \mathbb{R} \rightarrow T(M \times \mathbb{R})$$

$$\omega = \omega_M \oplus \omega_{\mathbb{R}}, \text{ as } \omega(V) = \omega(V_M + V_{\mathbb{R}}) = \omega(V_M) + \omega(V_{\mathbb{R}})$$

$$\omega_{\mathbb{R}} = f dt \text{ for some global } f, \text{ since}$$

$\omega_{\mathbb{R}} \simeq \mathbb{R}$ is trivial.
 not forms on M or \mathbb{R} , as ω_M depends on \mathbb{R} & vice versa.
 \square

If we have a k -form on $M \times \mathbb{R}$, then $\omega = \omega_M + dt \wedge \eta$, w/ η a $(k-1)$ -form. [Homework]. Now, η will play the role of F , as for 1-forms, we integrated a 0-form, so now for k -forms, we need to integrate a $(k-1)$ -form.

Define $I(\omega)(v_1, \dots, v_{k-1}) = \int_0^1 \eta(p, s)(i_{s^*} v_1, \dots, i_{s^*} v_{k-1}) ds$, a $(k-1)$ -form on M , or, succinctly, $I\omega = \int_0^1 i_s^* \eta ds$. Note! I is a linear operator.

Thm: For any k -form ω on $M \times \mathbb{R}$, $i_t^* \omega - i_0^* \omega = d(I\omega) + I(d\omega)$.

* In particular, if ω closed, LHS is exact b/c $d(I\omega)$.

Pf: It suffices to prove this in coordinates, since the split

$\omega = \omega_M + dt \wedge \eta$ is independent of coords,

(a) Assume $\omega = a_I dx_I + b dt \wedge dx_I$, b/c I, d are linear wrt sum.

$$d\omega = \frac{\partial a_I}{\partial t} dt \wedge dx_I + (\text{terms w/o } dt) \Rightarrow \eta = \frac{\partial a_I}{\partial t} dx_I$$

$$\Rightarrow I(d\omega) = \int_0^1 i_s^* \left(\frac{\partial a_I}{\partial t} dx_I \right) ds.$$

$$\text{Since } i_s^* \frac{\partial}{\partial t} \Big|_{(p,s)} = \frac{\partial}{\partial t} \Big|_{(p,s)}, \quad i_s^* dx_I(p,s) = dx_I(p). \quad (\text{as } \langle \frac{\partial}{\partial t}, v \rangle = \langle \omega, \frac{\partial}{\partial t} \rangle)$$

$$\text{So } I(d\omega) = \int_0^1 \left(\frac{\partial a_I}{\partial t}(p,s) \right) dx_I = (a_I(p,1) - a_I(p,0)) dx_I$$

Also, $I\omega = 0$, as $\eta = 0$ in this case [$\omega = a_I dx_I$].

$$I(d\omega) = (a_I(p,1) - a_I(p,0)) dx_I = i_1^*(a_I dx_I) - i_0^*(a_I dx_I) = i_1^* \omega - i_0^* \omega.$$

(b) Assume $\omega = f dt \wedge dx_I$ (w/ this I one dimensional than prev. I)

$\eta = f dx_I$, $i_s^* dt$ can only applied to $\partial/\partial t_i$ (as no t in M),

$$\text{then } i_s^* dt \left(\frac{\partial}{\partial t_i} \right) = dt \left(\frac{\partial}{\partial t_i} \right) = 0 \quad \frac{\partial f}{\partial t} i_s^* dt = d(t \circ i_s) = 0, \text{ as } t \circ i_s = s, \text{ Const.}$$

$$d\omega = \sum_{j=1}^n \frac{\partial f}{\partial x_j} dx_j \wedge dt \wedge dx_I \quad (\text{note, don't need } \frac{\partial f}{\partial t} dt \wedge dt \wedge dx_I \text{ b/c } dt \wedge dt = 0)$$

$$I(d\omega) = - \int_0^1 \left(\sum_{j=1}^n \frac{\partial f}{\partial x_j} dx_j \wedge dx_I \right) ds = - \sum_{j=1}^n \left(\int_0^1 \frac{\partial f}{\partial x_j}(p,s) ds \right) dx_j \wedge dx_I.$$

$$I\omega = \int_0^1 i_s^* (f dx_I) ds = \int_0^1 f(p,s) ds dx_I$$

$$d(I\omega) = \sum_{j=1}^n \frac{\partial}{\partial x_j} \left(\int_0^1 f(p,s) ds \right) dx_j \wedge dx_I$$

Use NTS: $\int_0^1 \frac{\partial^2}{\partial x_j^2} f(s) ds = \frac{\partial}{\partial x_j} \int_0^1 f'(s) ds$, then done.

$$\begin{aligned} \frac{\partial}{\partial x_j} \int_0^1 \int_0^1 f(x_1 x_2) ds &= \frac{\partial}{\partial x_j} \int_0^1 \int_0^1 x_1^* f ds = \int_0^1 \frac{\partial}{\partial x_j} (x_1^* f) ds = \int_0^1 d(x_1^* f) \frac{\partial}{\partial x_j} ds \\ &= \int_0^1 (x_1^* d f) \frac{\partial}{\partial x_j} ds = \int_0^1 d f x_1^* \frac{\partial}{\partial x_j} ds = \int_0^1 d f \frac{\partial}{\partial x_j} ds = \int_0^1 \frac{\partial f}{\partial x_j} ds \end{aligned}$$

From here, $d(I\omega) = \sum_{j=1}^n \int_0^1 \frac{\partial f}{\partial x_j} ds dx_j = \sum_{j=1}^n \int_0^1 d f dx_j$, so $I(d\omega) + d(I\omega) = 0$.

Poincaré's Lemma: If H is C^∞ -contractible to $p_0 \in H$, then $d\omega = 0 \iff \omega = d\eta$ for some η . □

PF: Since ω is contractible, we have a C^∞ map $H: M \times [0,1] \rightarrow M$ w/ $H(p,0) = p_0$, $H(p,1) = p$.

Let $H^* \omega$ be a form on $M \times [0,1]$. By the prev. thm,

$$i_1^*(H^* \omega) - \underbrace{i_0^*(H^* \omega)}_{(H \circ i_0)^*} = I(d(H^* \omega)) + d(I(H^* \omega)).$$

$$H \circ i_0(p) = p_0, \text{ so } (H \circ i_0)^* \omega = 0$$

$$H \circ i_1(p) = p \Rightarrow H \circ i_1^* = \mathbb{1}_M, \text{ so } (H \circ i_1)^* \omega = \mathbb{1}_M^* \omega = \omega.$$

$$\text{If } d\omega = 0, \text{ then } d(H^* \omega) = H^*(d\omega) = 0.$$

$$\text{Then } \omega = I(d(H^* \omega)) + d(I(H^* \omega)), \text{ so } \omega$$

$$\omega \text{ is closed, } \omega = d(I(H^* \omega)).$$

Homework: Do 2 Frobenius Problems for forms; Ch. 7/6.17, 21, 27, 28. □
 28. Given problem from today $\omega = u_1 u_2 + dx_1 u_2$.

Symplectic Structures on Manifolds

Let M^{2n} be a $2n$ -dim manifold. A symplectic structure on M is a nondegenerate closed 2-form ω on M^{2n} , i.e., $d\omega=0$ and for any $p \in M$ & $v \in T_p M$, $\exists u \in T_p M$ w/ $\omega(v,u) \neq 0$.

Ex: Cotangent bundle T^*M has a natl symp. structure (which is exact) defined as:

Let θ be a 1-form in T^*M , $\exists \alpha \in T_x(T_x^*M)$, α a form on M ,
we have $\pi^*: T^*M \rightarrow M$,
 $\mathcal{F} \rightarrow \pi^*\mathcal{F}$
(i.e. a pt in T^*M)

So let $\theta(\mathcal{F}) = \alpha(\pi^*\mathcal{F})$.

q coords in M , (p,q) coords in T^*M .

Assume $\alpha = \sum p_i dq_i$ in coords.

$$\mathcal{F} = \sum \alpha_i \frac{\partial}{\partial q_i} + \sum \beta_i \frac{\partial}{\partial p_i}$$

$$\pi^*\mathcal{F} = \sum \alpha_i \frac{\partial}{\partial q_i}$$

$$\theta(\frac{\partial}{\partial q_i}) = \alpha(\pi^*\frac{\partial}{\partial q_i}) = p_i \quad \alpha = \sum p_i dq_i$$

$$\text{Then } \theta = \sum p_i dq_i$$

$$\text{Then } \omega = d\theta = \sum dp_i \wedge dq_i$$

Symplectic Manifold: (M^{2n}, ω) , $d\omega = 0$, ω a 2 -form, nondegenerate. → symplectic structure

Ex: T^*M is a $(2n)$ -dim'd. Locally, $\omega = \sum_i dq_i \wedge dp_i = dq \wedge dp$.

Hamiltonian vector fields:

Given a vector field $X \in \mathcal{X}(M) =$ set of all vect. fields, i.e. maps to tangent we can define a 1-form ds

$$\omega_X(Y) = \omega(Y, X).$$

This relation defines a map.

$$\mathcal{X}(M) \rightarrow \Omega^1(M)$$

The map is linear & since ω is nondegenerate, there is no v.f. in kernel

Reverse: For any $P \in M$ & any $V \in T_P M$, $\exists U$ s.t. $\omega(P)(V, U) \neq 0$.

Thus map is invertible: $\Omega^1(M) \xrightarrow{\cong} \mathcal{X}(M)$.

In particular, given a fun $H: M \rightarrow \mathbb{R}$, dH is a 1-form, and so \exists v.f. X_H with the property that

$$dH(X_H) = \omega(X_H, X_H) \text{ for any v.f. } X.$$

X_H is called the Hamiltonian vector field associated to H .

Ex: on T^*M of symplectic form $\omega = dp \wedge dq = \sum_i dp_i \wedge dq_i$.

If $X = \sum_i a_i \frac{\partial}{\partial q_i} + b_i \frac{\partial}{\partial p_i}$ is a vector field, then

$$\omega(X, X) = -\sum_i (b_i dq_i - a_i dp_i) \text{ [a 1-form]}$$

locally consider the basis $\{\frac{\partial}{\partial q_i}, \frac{\partial}{\partial p_i}\}$ of $\mathcal{X}(M)$ & $\{dq_i, dp_i\}$ of $\Omega^1(M)$

X in the basis is (a_i, b_i) & the image is $(-b_i)$. Thus, the map

$$\mathcal{X}(M) \rightarrow \Omega^1(M) \text{ is } (a_i, b_i) \mapsto \begin{pmatrix} 0 & -I \\ I & 0 \end{pmatrix} \begin{pmatrix} a_i \\ b_i \end{pmatrix}.$$

Then the inverse $I: \Omega^1(M) \rightarrow \mathcal{X}(M)$ locally looks like

$$\begin{pmatrix} a \\ b \end{pmatrix} \mapsto \begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix}.$$

Locally, $dH = \sum_i \frac{\partial H}{\partial q_i} dq_i + \frac{\partial H}{\partial p_i} dp_i$, so $X_H = \sum_i \frac{\partial H}{\partial p_i} \frac{\partial}{\partial q_i} - \frac{\partial H}{\partial q_i} \frac{\partial}{\partial p_i}$

The signs for the flows are

$$\frac{dq_i}{dt} = \dot{q}_i = \frac{\partial H}{\partial p_i} \quad \& \quad \dot{p}_i = -\frac{\partial H}{\partial q_i}$$

Property: $H(\varphi_{\Sigma_H}^t(x)) = H(x)$ if $\varphi_{\Sigma_H}^t$ is the flow of Σ_H , i.e. the flow preserves H . [Energy is preserved]

$$\begin{aligned} \mathbb{E}: \Sigma_H(H) &= \frac{d}{dt}(H(\varphi_{\Sigma_H}^t(x))) \\ &= dH(\Sigma_H) \quad (\text{Differential applied to vect. field is v.f.}) \\ &= \omega(\Sigma_H, \Sigma_H) \quad (\text{applied to form}) \\ &= 0 \end{aligned}$$

Def: Let $F, H: M \rightarrow \mathbb{R}$ be 2 Hamiltonians. Define $\{F, H\}: M \rightarrow \mathbb{R}$ as the form given by $\{F, H\} = \omega(\Sigma_H, \Sigma_F)$. $\{F, H\}$ is called the Poisson bracket associated to ω . Note: $\omega(\Sigma_H, \Sigma_F) = dF(\Sigma_H) = \Sigma_H(F)$

Properties:

- (1) $\{F, H\} = -\{H, F\}$, i.e. $\Sigma_H(F) = -\Sigma_F(H)$
- (2) $\{, \}$ is bilinear over \mathbb{R} .
- (3) $\{F_G, H\} = F\{G, H\} + G\{F, H\}$ (Leibniz property):
 $d(FG)(\Sigma_H) = FdG(\Sigma_H) + GdF(\Sigma_H)$
- (4) $\{\{F, G\}, H\} + \{\{G, H\}, F\} + \{\{H, F\}, G\} = 0$ (Jacobi identity):
 $0 = d\omega(\Sigma_H, \Sigma_F, \Sigma_G) \stackrel{\text{by def}}{=} \Sigma_G(\omega(\Sigma_H, \Sigma_F)) - \Sigma_F(\omega(\Sigma_H, \Sigma_G)) + \Sigma_H(\omega(\Sigma_F, \Sigma_G))$
 $\Sigma_G(\{F, H\}) - \Sigma_F(\{G, H\}) - \Sigma_H(\{G, F\})$
 $= -\omega(\{\Sigma_H, \Sigma_F\}, \Sigma_H) + \omega(\{\Sigma_H, \Sigma_G\}, \Sigma_F) - \omega(\{\Sigma_F, \Sigma_G\}, \Sigma_H) (*)$
 $= \{\{F, H\}, G\} - \{\{G, H\}, F\} + \{\{G, F\}, H\} + (**)$
 $= \{\{F, H\}, G\} + \{\{H, G\}, F\} + \{\{G, F\}, H\} + (**)$

$$\begin{aligned} \omega(\xi_H, \xi_F, \xi_G) &= [\xi_H, \xi_F](\xi_G) \\ &= \xi_H(\xi_F(\xi_G)) - \xi_F(\xi_H(\xi_G)) \\ &\quad - \xi_G(\xi_F) \\ &= \xi_G(\xi_F, \xi_H) - \xi_G(\xi_H, \xi_F) \end{aligned}$$

In (*), this term is negative, so get: $\xi_G(\xi_H, \xi_F) - \xi_G(\xi_F, \xi_H)$.

When we add all 3 terms in (*), we get:

$$2[\xi_G, \xi_H, \xi_F] - 2[\xi_G, \xi_F, \xi_H] + 2[\xi_H, \xi_F, \xi_G]$$

Thus the whole sum yields $0 = \xi(\xi_H, \xi_G) + \xi_H(\xi_G, \xi_F) + \xi(\xi_G, \xi_F, \xi_H)$. ✓

Closest look at Jacobi identity

$$\begin{aligned} 0 &= -\xi(\xi_H, \xi_G) - \xi(\xi_H, \xi_F) - \xi(\xi_G, \xi_F, \xi_H) \\ &= \xi_{\xi_H}(\xi_G) + \xi_F(\xi_H, \xi_G) - \xi_H(\xi_F, \xi_G) \\ &\Rightarrow \xi(\xi_H, \xi_H) = [\xi_H, \xi_F] \end{aligned}$$

Cor: The Hamiltonian vector fields form a subalgebra of the vector fields, i.e. Lie bracket of 2 H.v.f.'s is an H.v.f.

Cor: If $G \notin F$ are preserved by ξ_H , then ξ_G, ξ_F is also preserved. Such quantities are called first integrals.

Pf: Notice that if G is preserved by ξ_H , then $\xi_H(\xi_G) = 0 = \xi_G(\xi_H)$. i.e. if flow keeps G constant, then the deriv. along flow = 0.

If $\xi_G(\xi_H) = \xi_F(\xi_H) = 0$, then by Jacobi identity, $\xi(\xi_G, \xi_F), \xi_H = 0$.

Cor: The Hamiltonian flows for $\xi_H \notin \xi_G$ commute $\Leftrightarrow [\xi_H, \xi_G]$ is constant.

Pf: Flows commute \Leftrightarrow Lie bracket = 0, but $[\xi_H, \xi_G] = \xi(\xi_H, \xi_G)$.

But $\xi_F = 0$ only if F is locally constant, b/c $0 = \xi_F(R) = -dF(\xi_R)$

$\xi_H = 0 \Leftrightarrow \omega(\xi_H) = 0$, but \exists H corresp. w/ forms, so $dF = 0$, ξ_F is locally constant.

Problems:

① Find f, g locally on T^*M .

② Show that on \mathbb{R}^{2n} of form $\sum_{i=1}^n p_i dq_i$, every 1-parameter gp of diffeomorphisms preserving ω ($(\mathbb{R}^+)^*$ $\omega = \omega$) is a Hamiltonian flow.

Hint: in \mathbb{R}^{2n} , any closed 1-form is exact.

Thm (Darboux's thm) Let ω be a closed, nondegenerate 2-form on a nbhd of $p \in \mathbb{R}^{2n}$. Then, \exists coordinates (p, q) s.t. $\omega = \sum_{i=1}^n p_i dq_i$.

Thm (Liouville's Thm): Assume M^{2n} is a symplectic mfd & we have n independent fns F_1, \dots, F_n in involution (i.e. $[F_i, F_j] = 0$).

Let $M_a = \{x \mid F_i(x) = a_i, i=1, \dots, n\}$. Then M_a is a smooth mfd invariant under the flow ξ_{F_i} .

(a) If M_a is opt & ctd, then it is diffeomorphic to the brvs T^n .

(c) The flow of ξ_{F_i} can be written in coordinates (ω, θ) w/ $\frac{d\omega}{dt} = 0$ & $\frac{d\theta}{dt} = \omega$.

Called action-angle variables



flows.

Integration

Recall: Line integrals: $\gamma: [a,b] \rightarrow \mathbb{R}^2$, $\gamma(t) = (x(t), y(t))$

$$\int_a^b f(x) + g(y) = \int_a^b [f(x(t))x'(t) + g(y(t))y'(t)] dt$$

a singular 1-cube ↳ subpace of the form $f(x) + g(y)$

Def: We call $I^k: [0,1]^k \rightarrow \mathbb{R}^k$ given by the inclusion the standard k-cube. We say $c: [0,1]^k \rightarrow M$ is a singular k-cube. We can write $c \circ I^k$ instead of c . By definition, $[0,1]^0 = \{0\}$, & a 0-cube is $c: \{0\} \rightarrow M$, a pt in M .

Ex: $c: [0,1] \times [0,1] \rightarrow \mathbb{R}^3$ (can reparametrize to be $[0,1]^2$)
 $(\theta, \theta) \rightarrow$ spherical coords.

Note, $\text{Im}(c) = S^2$, so S^2 is a singular cube. The torus is also a cube.

Def: If ω is a k-form on $[0,1]^k$, $\omega = f dx_1 \wedge \dots \wedge dx_k$ w/ $\{x_i\}$ coords on $[0,1]^k$ (w \mathbb{R}^k), then

$$\int_{[0,1]^k} \omega := \int_{[0,1]^k} f dx_1 \wedge \dots \wedge dx_k$$

Riemann integral.

If c is a singular cube & ω is a k-form on M ($c: [0,1]^k \rightarrow M$), then $\int_c \omega := \int_{[0,1]^k} c^* \omega$.

If $k=0$, & ω is a zero-form, $\omega = f$, then $\int_{[0,1]^0} \omega = f(0)$

Note: we can only integrate a k-form over a k-cube.

Lemma: Let c be a 1-1 singular n-cube, $c: [0,1]^n \rightarrow \mathbb{R}^n$ w/ $\det c' \geq 0$ on $[0,1]^n$. Let $\omega = f dx_1 \wedge \dots \wedge dx_n$. Then $\int_c \omega = \int_{c([0,1]^n)} f dx_1 \wedge \dots \wedge dx_n$

PF: $\int_c \omega := \int_{[0,1]^n} c^* \omega = \int_{[0,1]^n} f \circ c \det c' dx_1 \wedge \dots \wedge dx_n$. Since $\det c' > 0$,

$$= \int_{[0,1]^n} f \circ c |\det c'| dx_1 \wedge \dots \wedge dx_n \stackrel{\text{Riemann change of var.}}{=} \int_{c([0,1]^n)} f dx_1 \wedge \dots \wedge dx_n$$

□

Prop (Independence from reparametrization): Let $p: [a, b] \rightarrow [a, b]$ be 1-1 & onto. Assume $\det p' \geq 0$. Let ω be a k -cube & ω a k -form in M . Then,

$$\int_c \omega = \int_{\text{comp}} \omega$$

PF: $\int_{\text{comp}} \omega = \int_{[a, b]^k} (\text{comp})^* \omega = \int_{[a, b]^k} p^*(c^* \omega) \stackrel{\text{lemma}}{=} \int_{[a, b]^k} c^* \omega$

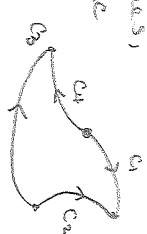
$$\int_{\text{ortho.}} \int_{[a, b]^k} c^* \omega = \int_c \omega$$

Def: If $\det p' \neq 0$ everywhere, then p is orientation preserving if $\det p' > 0$, reversing if $\det p' < 0$.

Note: If p preserves orientation, $\int_c \omega = \int_{\text{comp}} \omega$. If p reverses orientation, then $\int_c \omega = -\int_{\text{comp}} \omega$.

Def: A formal sum of singular k -cubes w/ integer coefficients is called a k -chain. $c = \sum a_i c_i$

ex: If c_i are singular 1-cubes, there may be a geometric meaning:



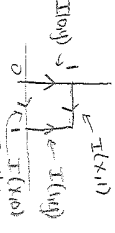
$c_1 - c_2 + c_3 - c_4$ means, geometrically, follow c_1 in this order w/ this orientation.

Def: If ω is a k -form, $\int_c \omega := \sum a_i \int_{c_i} \omega$.

Note: $-c_i$ represents c_i w/ opp. orientation; since,

$\int_{-c_i} \omega = -\int_{c_i} \omega$, $k c_i$ represents c_i traveled k times in same direction (for a curve).

Boundary

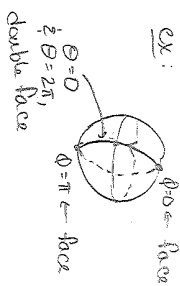


Think of this as the image of 1-cubes.

$$\partial I^2 = I(x_2, y_2) + I(x_1, y_2) - I(x_1, y_1) - I(x_2, y_1)$$

(add the number you plug in (coord) to the position where you put it. (1 or 2) For ∂ , plug in 0 or 1, but the positions are 1, 2, or 3.

Def: Given a k -cube, we define the (i, α) -face to be a $(k-1)$ -cube $I_{(i, \alpha)}^k: [0, 1]^{k-1} \rightarrow M$, $I_{(i, \alpha)}^k(x_1, \dots, x_{k-1}) = I^k(x_1, \dots, x_{k-1}, x_{k-1})$. If c is a singular k -cube, we define the (i, α) -face to be $c_{i, \alpha} = c \circ I_{(i, \alpha)}^k$.



ex: So 4 faces, 2 are pts, & the other 2 are the same arc at $\theta=0, \theta=2\pi$.

Def: The boundary of I^k is $\partial I^k = \sum_{(\alpha=1, \dots, k)} (-1)^\alpha I_{(i, \alpha)}^k$. Similarly,

$$\partial x: \partial S^2 = -(0, \theta) + (\theta, \alpha) + (\pi, \theta) - (0, 2\pi) \\ \text{if } (\theta, \alpha) = -N + \uparrow + S - \downarrow$$

When you integrate, $\uparrow - \downarrow$ disappears, so just integrate over 2 pts, so the integral of $\uparrow - \downarrow$ form is just 0 (the one won't always be constant), i.e. $\int_{S^2} \omega = 0$.

$$\partial [0, 1] = -\{0\} + \{1\}, \text{ i.e. } \int_0^1 f dx = f(1) - f(0).$$



$$\partial(\partial I^2) = I_{(1,1)}^2 - I_{(1,0)}^2 + I_{(0,1)} - I_{(0,0)} - I_{(0,1)} + I_{(0,0)} + I_{(1,0)} = 0.$$

Thm: $\partial^2 c = 0$, for c a k -chain.

Pr: Assume c a singular k -cube.

$$\partial(\partial c) = \partial \left[\sum_{(\alpha=0, \dots, k)} (-1)^\alpha c_{i, \alpha} \right] \\ = \sum_{j=1}^{k-1} \sum_{(\alpha, \beta=0, 1)} (-1)^{(\alpha+\beta)} (c_{i, \alpha})_{j, \beta}$$

$$(I_{i,d})_{j,d} (x_{i-1}, x_{k-2}) = I_{i,d} (x_{i-1}, x_{i-1}, x_{i-1}, \dots, x_{i-1}, x_{i-1}, x_{i-1}, \dots, x_{k-2}) \quad \text{Assume } i < j.$$

$$= I (x_{i-1}, x_{i-1}, x_{i-1}, \dots, x_{i-1}, x_{i-1}, x_{i-1}, \dots, x_{k-2})$$

$$= (I_{j+1,d})_{i,d}$$

But in the sum, these will have opp. signs b/c first is $(-1)^{i+j+2+3}$, 2nd is $(-1)^{i+j+1+2+3}$ so these cancel.

$$i: 1, 2, 3, \dots, k \quad \left\{ \begin{array}{l} (i,j) \\ (i,i) \end{array} \right. \rightarrow \left\{ \begin{array}{l} (1,1), (1,2), \dots, (1, k-1) \\ (2,1), (2,2), \dots, (2, k-1) \\ \vdots \\ (k-1, 1), (k-1, 2), \dots, (k-1, k-1) \end{array} \right\} \quad (i,j) \leftrightarrow (j+1, i)$$

some of opp signs just by counting. $i < j$ remaining is diagonal & subdiag.

So, $\partial^2 e = 0$.

□

11/18 - DM

Thm: $\partial^2 c = 0$.

Pf: Done on I^k .

$$\partial c = \sum_{i=1}^k \partial I^k = \sum_{i=1}^k (-1)^{i+k} c_{i,k}$$

Then the proof of $\partial^2 c = 0$ is identical to $\partial^2 I^k = 0$. (Substitute $c_{i,k}$ for $I^k_{i,k}$). And if c is a chain, $c = \sum a_i c_i$, then linearity answers $\partial^2 c = 0$.

Note: $\partial^2 c = 0$ parallel to $d^2 \omega = 0$

c is closed parallel to ω closed if $dc = 0$

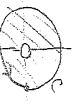
chain in 0 when $\int_{\text{over chain}} = 0$.

Remark: sphere is a closed chain.

$du = 0 \Rightarrow \omega = df$. we have the example $\omega = \frac{-y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$ on $\mathbb{R}^2 \setminus \{0,0\}$.

parallel to

In general, $\partial c = 0 \neq c = \partial \tilde{c}$



ex: $\partial c = 0$, but $c \neq \partial \tilde{c}$, bc there's a hole, \tilde{c} would have to be the image of Loop .

Stokes Thm (for chains): Let ω be a $(k-1)$ -form on M & a k -chain. Then

$$\int_{\partial c} \omega = \int_c d\omega$$

Pf: Case I: $c = I^k$, $\tilde{c} = M = \mathbb{R}^k$. For simplicity assume $\omega = f dx_1 \wedge \dots \wedge dx_k$.

Let's pull back ω to one of the faces: (recall, $\partial c = \sum_{i=1}^k (-1)^{i+k} I^k_{i,k}$)

$$(I^k_{j,k})^* \omega = (I^k_{j,k})^* (f dx_1 \wedge \dots \wedge dx_k)$$

(if $j \neq i$, then $I^k_{j,k} dx_j = 0 = d\tilde{x}$ so $\int \neq 0$ only when $j=i$)

$$= \sum_i f(x_1, \dots, \tilde{x}_i, \dots, x_k) dx_1 \wedge \dots \wedge dx_k$$

$\int f(x_1, \dots, \tilde{x}_i, \dots, x_k) dx_1 \wedge \dots \wedge dx_k$
so the $\mathbb{1}$ on all but j 'th spot

$$S_{\alpha, j} \int_{I_j^k} \omega = \sum_{i=1}^n \sum_{\alpha=1}^n (-1)^{i+j} \int_{I_j^k} \omega$$

$$\int_{I_j^k} \omega = \int_{[0,1]^{k-1}} \underbrace{\left(\int_{I_j^k} \omega \right)^*}_{=0 \text{ if } j \neq i} \omega$$

$$= (-1)^{i+j} \int_{[0,1]^{k-1}} F(x_{1,1}, \dots, x_{i,1}, x_{i,2}) dx_1 \wedge \dots \wedge dx_{i-1} \wedge dx_{i+1} \wedge \dots \wedge dx_k$$

$$- \int_{[0,1]^{k-1}} F(x_{1,1}, \dots, x_{i,1}, x_{i,2}) dx_1 \wedge \dots \wedge dx_{i-1} \wedge dx_{i+1} \wedge \dots \wedge dx_k \quad \left. \begin{array}{l} \alpha=0 \\ \alpha=1 \end{array} \right\}$$

$$\int_{I_j^k} d\omega = \sum_j D_j F dx_j \wedge dx_1 \wedge \dots \wedge dx_k \quad (\text{all } = 0 \text{ if } i \neq j)$$

$$= D_i F dx_i \wedge dx_1 \wedge \dots \wedge dx_k \quad (-1)^{i-1}$$

So $\int_{[0,1]^{k-1}} d\omega = \int_{[0,1]^{k-1}} (-1)^{i-1} D_i F dx_1 \wedge \dots \wedge dx_k$
 The def of \int is correct, but need the dx_i in correct order

$$d\omega = \int_{[0,1]^{k-1}} (-1)^{i-1} D_i F dx_1 \wedge \dots \wedge dx_k$$

$$\int_{[0,1]^{k-1}} (-1)^{i-1} \int_{[0,1]^{k-1}} [F(x_{1,1}, \dots, x_{i,1}, x_{i,2}) - F(x_{1,1}, \dots, 0, \dots, x_{i,2})] dx_1 \wedge \dots \wedge dx_{i-1} \wedge dx_{i+1} \wedge \dots \wedge dx_k$$

= $\int_{I_j^k} \omega$ ✓

Case II: C is a singular cube on $[0,1]^k$, then

$$\int_{\partial C} \omega = \sum_{\alpha=1}^n \int_{I_j^k} c^* \omega \stackrel{\text{Case I}}{=} \int_{I_j^k} d(c^* \omega) \stackrel{d \circ c^* \text{ commute}}{=} \int_{I_j^k} c^* d\omega = \int_C d\omega \quad \checkmark$$

(bc $c^* \omega$ is on \mathbb{R}^k)

Case III: $c = \sum a_i c_i$

Linearity proves this case. ✓

□

Applications of Stokes's Theorem

① Assume a form ω , $\int_C \omega \neq 0$ for some closed C . Then ω is not exact: Evidently use this for closed forms which we suspect are exact.

If $\omega = dy$, then $\int_C \omega = \int_C dt = \int_{\partial C} t = 0$, and $\partial C = 0$ b/c closed.

* Thus can check exactness of forms by integrating.

Ex: $\omega = \frac{y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$



$C: [0, 2\pi] \rightarrow \mathbb{R}^2$

$$\int_C \omega = \int_0^{2\pi} (\sin^2 2\pi t \cdot 2\pi + \cos^2 2\pi t \cdot -2\pi) dt = 2\pi \int_0^{2\pi} (\cos^2 2\pi t - \sin^2 2\pi t) dt$$

= $2\pi \neq 0$.

Thus $\omega \neq d\theta$.

② If $0 \neq \int_C \omega \neq \int_{C^*} \omega$ closed, then $C \neq \partial C^*$.

$$\int_C \omega = \int_{\partial C^*} \omega = \int_{C^*} d\omega = 0$$

Goal: Stoke's Theorem on manifolds. We want to parametrize the manifold.

We need to know: (1) What does $\int_M \omega$ mean? (2) Is $\int_C \omega = \int_{C^*} \omega$ on the intersection? (3) How do you orient ∂M ? (4) What is \mathbb{R}^n , $p \in \partial M$?

Thm: Let M be an orientable n -manifold, \mathbb{R}^n let c_1, c_2 be 2 chains $c_i: [0, 1]^n \rightarrow M$ s.t. c_i are diffeomorphisms on a nbhd of $[0, 1]^n$.

They both preserve (or reverse) orientation. Let $C = C_1([0, 1]^n) \cup C_2([0, 1]^n) \cap M$ and assume ω is an n -form w/ $\text{supp } \omega \subseteq C$. Then

$$\int_{C_1} \omega = \int_{C_2} \omega.$$

$$\text{Thm: } \int_{C_1} \omega = \int_{C_2} \omega = \int_{C_2^* \circ c_1} \omega = \int_{C_2^*} \omega. \text{ Call } C_2^* \circ c_1 = C.$$

C_2^* is an n -form in $[0, 1]^n$, so $C_2^* \omega = f dx_1 \wedge \dots \wedge dx_n$, so

$$C^* \omega = f \circ c \det c^i dx_1 \wedge \dots \wedge dx_n = f \circ c |\det c^i| dx_1 \wedge \dots \wedge dx_n$$

* both props of rev or.

$$\int_{\mathbb{R}^n} c^T \omega = \int_{c_1(\mathbb{R}^n)} c^T c^* \omega = \int_{c_1(\mathbb{R}^n)} f \circ c |det c| dx_1 \dots dx_n$$

$$\stackrel{\text{Riemann sum}}{\approx} \int_{c_2(\mathbb{R}^n)} f dx_1 \dots dx_n$$

$$= \int_{c_2(\mathbb{R}^n)} f dx_1 \dots dx_n$$

$$= \int_{c_2(\mathbb{R}^n)} c_2^* \omega$$

$$\stackrel{\text{supp } \omega \subseteq c_2(\mathbb{R}^n)}{=} \int_{c_2(\mathbb{R}^n)} c_2^* \omega$$

$$\stackrel{\text{supp } c_2^* \omega \subseteq \mathbb{R}^n}{=} \int_{\mathbb{R}^n} c_2^* \omega$$

$$= \int_{c_2} \omega$$

Def: Assume c is an n -chain, ω let ω be an n -form in M
 ω $\text{supp } \omega \subseteq c(\text{Int } \mathbb{J}^n)$. Then $\int_M \omega := \int_c \omega$.

Note: By the previous thm, this is well-def

If $\text{supp } \omega \notin c(\text{Int } \mathbb{J}^n)$ for any c , we cover M with open sets $\{\theta_j\}$ a partition of unity associated to $\{\theta_j\}$, $\omega|_{\theta_j}$ each $\theta_j \subseteq c_0(\text{Int } \mathbb{J}^n)$ for some chain c_0 . We can always do this by covering M w/ coord charts; then pick a box around 0 in \mathbb{R}^n , $[-z_1, z_1]^n$ & an ω $[-z_1, z_1]^n \rightarrow \text{Int } \mathbb{J}^n$. Then $c = \gamma \circ f$. Then, by def, ω has cpt supp, $\int_M \omega := \sum_{\theta} \int_{\theta} \omega$ [cpt supp ensures sum is finite].

But does this def depend on the partition of unity? If both have same cover

$$\sum_{\theta} \int_{c_0} \psi_{\theta} \cdot \omega = \sum_{\theta} \int_{c_0} \left(\sum_{\theta'} \psi_{\theta'} \right) \omega = \sum_{\theta} \int_{c_0} \sum_{\theta'} \psi_{\theta'} \omega = \sum_{\theta} \int_{c_0} \omega$$

$$\sum_{\theta} \psi_{\theta} = 1$$

If both don't have same cover - next time.

Wlo-DH

* If $\text{supp } \omega \subseteq C(\text{co}, \mathbb{R}^k)$, ω a k -form, $\int_M \omega := \int_C \omega$.

HW: Prove \int_M is a linear map.

If this is true, then $\int_M \omega = \sum \int_M \omega_i$, $\{\omega_i\}$ a partition of unity does not depend on \mathbb{R}^n , since

$$\int_M \omega = \int_M \sum \omega_i = \sum \int_M \omega_i = \sum \int_M \omega_i$$

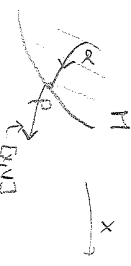
b/c $\sum \omega_i = 1$.

Manifolds w/ Boundary

A mfd M , $\neq \emptyset$ for any $p \in M \exists \alpha: U \rightarrow \mathbb{R}^n$ or $U \rightarrow \mathbb{H}^n = \{(x_1, \dots, x_n) \mid x_n \geq 0\}$. If \mathbb{H}^n , we say $p \in \partial M$.

To define $T_p M$, $p \in \partial M$, we have to allow curves that start / end at P , giving outward-pointing / inward-pointing vectors.

Define $T_p^{\text{out}} M = \{\alpha'(0) \mid \alpha: (-\epsilon, 0], \alpha(0) = p\}$, where α' is $[v, w]$ is the class of all vectors which are = in diff. coords.



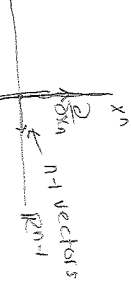
$$T_p^{\text{in}} M = \{\alpha'(0) \mid \alpha: [0, \epsilon) \rightarrow M, \alpha(0) = p\}$$

Then, $T_p \partial M = T_p^{\text{out}} M \cap T_p^{\text{in}} M$, so vectors you can get from both curves that end \hat{z} that start at P . So the tan. plane, for ∂M , is the whole plane, not just half.

Def: Assume M is an oriented mfd. ∂M is positively oriented with the induced orientation if $\{v_1, \dots, v_{n-1}\}$ are positively or whenever $\{v_1, v_2, \dots, v_{n-1}\}$ is positively oriented in M for any v pointing outwards.

Ex: How is $\partial \mathbb{H}^n$ or w/ this def?

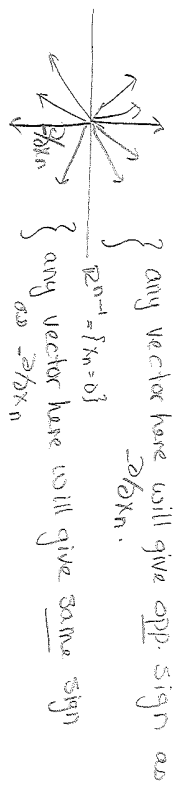
If (x_1, \dots, x_n) are usual coords, then $\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_{n-1}}$ gen ∂M . What is sign? $\det(-e_1, \dots, e_{n-1}) = (-1)^0 = 1$ or $\Leftrightarrow n$ even.



* so how induced or $\Leftrightarrow n$ even.

So if θ_n or in $\partial H^{n-1} = \mathbb{R}^{n-1}$ is pos if $\{e_1, \dots, e_{n-1}\}$ is pos (the standard or. of \mathbb{R}^{n-1}), then it is the induced or. of n is even, & the opp. one if n is odd.

Note:



Note: ∂H as a submfld of M has an atlas given by intersections of the atlas of M w/ the boundary. The image is the $\partial H^n = \mathbb{R}^{n-1}$, thus $\dim \partial H = n-1$. If the atlas is or. in M , then the atlas in ∂H will be oriented.

What is the integrand of a mfd w/ ∂ ?

Case I: Assume $M \subseteq \mathbb{R}^m$, $\partial M \neq \emptyset$. If F has cpt supp, we define

$$\int_M \underbrace{f dx_1 \wedge \dots \wedge dx_n}_{\text{on } n\text{-form}} = \int_H f dx_1 \wedge \dots \wedge dx_n, \text{ the Riemann integral}$$

(if $M(\partial H) = 0$, so doesn't change the R. integrand)

Case II: $\text{supp } \omega \subseteq c(\text{Int } M^n)$, $\int_H \omega = \int_c \omega = \int_{[0,1]^n} \omega^*$, & back to case I.

Case III: Use partition of unity to patch up $\int_H \omega$ as before.

Prop: If $f: H^n \rightarrow N^n$ is a diffeomorphism and ω is an n -form in N w/ cpt supp, then $\int_M f^* \omega = \int_N \omega$ if f preserves or. or $-\int_M \omega$ if f reverses or.

Pf: Follows the proof of the change of variables. \square


Thm (Stokes): Let M be oriented, n -dim manifold w/ $\partial M \neq \emptyset$ & assume ∂M has the induced orientation. Let ω be an $(n-1)$ -form w/ opt supp. Then $\int_M d\omega = \int_{\partial M} \omega$.

Pf:

Case I: Assume $\text{supp } \omega \subseteq \mathcal{C}(\text{Loc } \mathbb{R}^n) = \text{int}(\mathcal{C}(e, \mathbb{R}^n))$, and $\text{supp } \omega \subseteq \mathcal{C}(\text{Loc } \mathbb{R}^n) \subseteq M \setminus \partial M$.

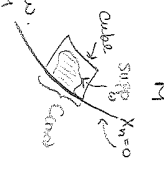
Then $\int_{\partial M} \omega = \int_{\partial \mathcal{C}} \omega = \int_{\mathcal{C}} d\omega = \int_M d\omega$ [- 0]

Stokes for choices



Case II: Assume $\partial M \cap \mathcal{C}(\text{Loc } \mathbb{R}^n) = \mathcal{C}_{(m)}$ (Loc \mathbb{R}^{n-1}) & $\text{supp } \omega \subseteq \mathcal{C}(\text{Loc } \mathbb{R}^n)$, which includes $\mathcal{C}_{(m)}$ (Loc \mathbb{R}^{n-1}).

Then $\int_M d\omega = \int_{\mathcal{C}} d\omega = \int_{\partial \mathcal{C}} \omega = \int_{(-1)^i \mathcal{C}_{(m)}} \omega = (-1)^n (-1)^n \int_{\partial M} \omega$



b/c $\text{supp } \omega \subseteq \mathcal{C}(\text{Loc } \mathbb{R}^{n-1})$, so on $\partial \mathcal{C}$, $\omega \neq 0$ only on $\mathcal{C}_{(m)}$, & the sign of $\mathcal{C}_{(m)}$ (in the sum for $\partial \mathcal{C}$) is $(-1)^n$.
But the or of $\text{Loc } \mathbb{R}^{n-1}$ as ∂M^n is $(-1)^n$ the induced one that M has.

Case III: Cover M w/ coordinate systems for & a partition of unity $\{\phi_i\}$ s.t. $d\omega$ is of type I or II. Then by case I/II

$$\int_M d\omega = \sum_i \int_M \phi_i d\omega = \sum_i \int_M d\phi_i \omega + \phi_i d\omega = \sum_i \int_M d(\phi_i \omega) = \sum_i \int_{\partial M} \phi_i \omega = \int_{\partial M} \omega$$

b/c $d\phi_i \omega = 0$, since

Recall: $C_{(m)}(x_1, \dots, x_{n-1}) = (x_1, \dots, x_{n-1}, 0) \in \mathcal{C}_{(m)}$

$$\sum_i d\phi_i \omega = \int_M d(\sum_i \phi_i \omega) = \int_M d(1) \omega = 0$$

b/c $d(1) = 0$

identifies \mathbb{R}^{n-1} w/ $\mathcal{C}_{(m)}$.

□

Applications

① Assume (M, μ) [i.e. M w/ an or.] is cpt & $\partial M = \emptyset$. Then

$$\int_M d\omega = \int_{\partial M} \omega = 0 \text{ for any form } \omega. \quad \left(\begin{array}{l} \text{not can integrate} \\ \text{any form by } M \\ \text{cpt} \end{array} \right)$$

Hence, if $\int_M \omega \neq 0$, then ω is not exact, even if it's closed.

Cor: A cpt n -fld w/ $\partial M = \emptyset$ cannot be contracted to a pt.

Pf: If M is or, there is always an n -form ω s.t.

$\int_M \omega \neq 0$: Let ω be the form giving an orientation,

so that $\omega(p) \neq 0$ & $\omega(p)(v_1, \dots, v_n) > 0 \forall (v_1, \dots, v_n)$ is positively or. So, locally, in or charts, $\omega = f dx_1 \wedge \dots \wedge dx_n$

w/ $f > 0$ for $\int_M \omega$ you just patch up w/ partition of unity

$$\int_M \omega = \sum_{\sigma} \int_{\sigma} \omega > 0 \quad (\text{b/c } f > 0 \text{ around a pt}).$$

But $\text{diss} = 0$, b/c ω is already top dim 2 . \square

de Rham Cohomology

(1) In $\mathbb{R}^2 \setminus \{0\}$, we say the closed, non-exact form $\frac{-y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$

(2) On S^{n-1} we have ω , an $(n-1)$ -form, giving the orientation, w/

$$\int_{S^{n-1}} \omega > 0. \quad \text{If } \omega = d\eta, \quad \int_{S^{n-1}} \omega = \int_{S^{n-1}} d\eta = \int_{\partial S^{n-1}} \eta = \int_{S^{n-1}} d\omega \Rightarrow \omega \neq d\eta$$

for any smooth η . $d\omega = 0$, since $\dim_{\mathbb{R}} S^{n-1} = n-1 = \text{order of } \omega$, so $d\omega$ an n -form on an $(n-1)$ -dim manifold, so $= 0$.

$\omega + d\eta$ also closed but not exact also.

$$0 \rightarrow \Omega^0(M) \rightarrow \dots \rightarrow \Omega^{k-1}(M) \xrightarrow{d_{k-1}} \Omega^k(M) \xrightarrow{d_k} \Omega^{k+1}(M) \rightarrow \dots, \quad d^2 = 0$$

Let $Z^k(M) = \text{the vect. sp. gen by closed } k\text{-forms} \subseteq \Omega^k(M)$
 $= \ker d_k$

$B^k(M) = \text{the vect. sp. gen by exact forms} \subseteq \Omega^k(M)$
 $= \text{Im } d_{k-1}$

Since $d^2 = 0$, $B^k(M) \subseteq Z^k(M)$.

Define $H^k(M) := Z^k(M) / B^k(M)$, called the k -de Rham cohomology vector sp.

The zero class is formed by closed, exact forms.

$[\omega] = [\omega] \Leftrightarrow \omega = \tilde{\omega} + d\eta$, where $d\eta \in B^k(M)$.

Note: de Rham proved this coincides w/ the simplicial cohom. of a mfd.

① Poincaré's Lemma says that if M is contractible, then $H^k(M) = 0$, $k > 0$.

② $H^0(M) = Z^0(M) = \text{zero forms (fns)} \text{ w/ } dF = 0$, i.e. const. on cld comps.


$$B^0(M) = 0$$

$\Rightarrow \dim H^0(M) = \#$ of cld components of M . (take $F = 1$ in cld comp

$\tilde{x} = 1$ in diff cld comp $\tilde{x} = 0$ else. So all fns will be lin. comb. of these, so have same # of gens as cld comps.

$$\Rightarrow H^0(M) = \mathbb{R}^k$$

③ If M is or $\partial M = 0$, then $\int_M \omega$ is an n -form st. $\int_M \omega > 0$.

Let ω be the orienting form; let $P = \text{int } M$. Then $\int_M \omega = \int_P \omega + \int_{\partial M} \omega$.  Then $\int_M \omega = \int_P \omega + \int_{\partial M} \omega$.

Then $\int_M \omega = \int_P \omega + \int_{\partial M} \omega$.

$d\omega = 0$ b/c ω is an n -form on an n -dim manifold. By Stokes' theorem, $\int_M d\omega = \int_{\partial M} \omega = 0$, so $\int_P \omega = 0$. (i.e. $H^{n-1}(S^{n-1}) \neq \mathbb{R}$)

④ $H^1(\mathbb{R}^2 \setminus \{0\}) \neq 0$, b/c of own 1-form $\frac{-y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$, closed but not exact.

Def: Let $H \subset X$ be a subset. We say $r: X \rightarrow H$ is a retraction if $r|_H = \text{id}_H$. A is a retraction of X .

Note: S^{n-1} is a retraction of $\mathbb{R}^n \setminus \{0\}$.

$$r: \mathbb{R}^n \setminus \{0\} \rightarrow S^{n-1}$$

Let ω be the orienting $(n-1)$ -form on S^{n-1} ; consider $r^*\omega$.

Then $d(r^*\omega) = r^*(d\omega) = 0$, so $r^*\omega$ is exact. Assume $r^*\omega = d\eta$.

Then $\int_{S^{n-1}} r^*\omega = \int_{S^{n-1}} d\eta = \int_{\partial S^{n-1}} \eta = 0$. But $\int_{S^{n-1}} \omega \neq 0$, so neither is $r^*\omega$.

Note: $\frac{-y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$ is $r^*\omega$.

Define ω on S^{n-1} as $\omega(p) = \det \begin{pmatrix} v_1 & \dots & v_{n-1} \end{pmatrix}$. Note: ω is the restriction to S^{n-1} of $\sigma = \sum_{i=1}^n (-1)^{i-1} x_i dx_1 \wedge \dots \wedge dx_{i-1} \wedge dx_{i+1} \wedge \dots \wedge dx_n$, an $(n-1)$ -form in \mathbb{R}^n .

If (v_1, \dots, v_{n-1}) are tangent to S^{n-1} at $p \in S^{n-1}$; we calculate $\sigma(p)(v_1, \dots, v_{n-1})$, then if $V_i = \sum_{j=1}^n a_{ij} dx_j$, then $\sigma(p)(v_1, \dots, v_{n-1})$ is the expansion by minors of $\det \begin{pmatrix} v_1 & \dots & v_{n-1} \end{pmatrix}$, b/c the x_i will give the i th comp. of p , i.e. the wedge is defined as a det, but never have the i th comp. of v_i , so det of a minor.

Lemma: Let $\sigma \neq \emptyset$ be as before. $(r^* \omega)(p) = \frac{\sigma(p)}{|p|^n}$, that is,

$$(r^* \omega) = \sum_{i=1}^n (-1)^{i-1} \frac{x_i}{|p|^n} dx_1 \wedge \dots \wedge dx_n, \text{ where } \nu(p) = |p|^n$$

Note: This is our usual form for $n=2$.

Pf: For $\vec{p} \in \mathbb{T}_p(\mathbb{R}^{2n} \setminus \{0\})$, $r_x \vec{p} = \frac{d}{dt} (\gamma(t)) = \frac{d}{dt} \left(\frac{\gamma(t)}{|\gamma(t)|} \right) = \frac{d}{dt} \left(\frac{\vec{p}}{|p|} \right) = 0$



For $\vec{v} \in \mathbb{T}_p(S^{n-1}(|p|))$, $r_x \vec{v} = \frac{d}{dt} \left(\frac{\gamma(t)}{|\gamma(t)|} \right) = \frac{d}{dt} \left(\frac{\gamma(t)}{|\gamma(t)|} \right) = \frac{\gamma'(t)}{|\gamma(t)|} - \frac{\gamma(t)}{|\gamma(t)|^2} \langle \gamma(t), \gamma'(t) \rangle$

$(n-1)$ -sphere w/ radius for $\gamma(t) = p$
 $|p|$ $\gamma'(t) = \vec{v}$

Notice $\mathbb{T}_p(\mathbb{R}^{2n} \setminus \{0\}) = \langle \vec{p} \rangle \oplus \mathbb{T}_p(S^{n-1}(|p|))$
 radius \neq $\left\{ \begin{array}{l} = \frac{\vec{v}}{|p|} \\ \frac{\gamma(t) \cdot \gamma'(t)}{|\gamma(t)|^2} = \frac{\vec{p} \cdot \vec{v}}{|p|^2} = 0 \end{array} \right.$

So $r_x p = 0 \neq r_x \vec{v} = \frac{\vec{v}}{|p|}$.

ω is an $(n-1)$ -form on $\mathbb{R}^n \setminus \{0\}$.

Case I: $r^* \omega(p) (\vec{p}, v_1, \dots, v_{n-2}) = \omega(r(p)) (r_x \vec{p}, r_x v_1, \dots, r_x v_{n-2}) = 0$.

$$\sigma(p) (\vec{p}, v_1, \dots, v_{n-2}) = \det \begin{pmatrix} \vec{p} \\ v_1 \\ \vdots \\ v_{n-2} \end{pmatrix} = 0.$$

Case II: $r^* \omega(p) (v_1, \dots, v_{n-1}) = \omega(r(p)) (r_x v_1, \dots, r_x v_{n-1}) = \omega \left(\frac{v_i}{|p|}, \dots, \frac{v_{n-1}}{|p|} \right)$

$$\forall i \in \mathbb{T}_p S^{n-1}(|p|) = \frac{1}{|p|^n} \det \begin{pmatrix} v_i \\ \vdots \\ v_{n-1} \end{pmatrix}$$

$$\sigma(p) (v_1, \dots, v_{n-1}) = \det \begin{pmatrix} v_1 \\ \vdots \\ v_{n-1} \end{pmatrix}.$$

So $r^* \omega = \frac{\sigma(p)}{|p|^n}$

Lemma: Let $f: B_1(0) \rightarrow \mathbb{R}$, $\int_B f$ define $g = \int_0^1 u^{n-1} f(uy) du$. Then $\int_B f = \int_B f dx_1 \wedge \dots \wedge dx_n = \int_{S^{n-1}} g \omega$. [convert from int whole ball to just sphere]

Pf: Strategy, More $\int_{S^{n-1}} \rightarrow \int_{S^{n-1} \times [0,1]}$ radius

Let $S^{n-1} \times [0,1] \xrightarrow{\pi_2} [0,1]$ & define ωdt on $S^{n-1} \times [0,1]$ as $\omega dt = (\pi_1^* \omega) \wedge (\pi_2^* dt)$, by abuse of notation.

Let $h: \mathbb{R}^n \rightarrow \mathbb{R}^{n+1}$, $h: S^{n-1} \times [0,1] \rightarrow \mathbb{R}^n$, $g = \int_0^1 h(u,p) du$
 $\int_{S^{n-1}} g \omega = \int_{S^{n-1} \times [0,1]} h(u,p) \omega dt$

Now let $\phi: B \setminus \{0\} \rightarrow S^{n-1} \times [0,1]$ (polar decomp, x_i radius)
 $p \mapsto (r(p), \nu(p))$
 $\frac{r(p)}{|p|} \searrow$

$$\begin{aligned} \phi^*(\omega dt) &= \phi^*(\pi_1^* \omega \wedge \pi_2^* dt) = (\pi_1 \circ \phi)^* \omega \wedge (\pi_2 \circ \phi)^* dt = r^* \omega \wedge \underbrace{\nu^* dt}_{= d|p|} \\ &= r^* \omega \wedge \sum_i \frac{x_i}{|p|} dx_i = \sum_i \frac{x_i}{|p|^{n+1}} dx_1 \wedge \dots \wedge dx_n \quad \uparrow \frac{1}{|p|^n} dx_1 \wedge \dots \wedge dx_n \\ &\quad \text{from def } r^* \omega \quad \sum x_i^2 = |p|^2 \end{aligned}$$

$$\begin{aligned} \phi^*(h \omega dt) &= (h \circ \phi)^*(\omega dt) = h(|p|, \frac{p}{|p|}) \frac{1}{|p|^n} dx_1 \wedge \dots \wedge dx_n \\ &= |p|^{p-n} f(|p|, \frac{p}{|p|}) \frac{1}{|p|^n} dx_1 \wedge \dots \wedge dx_n \\ &= f(p) dx_1 \wedge \dots \wedge dx_n \end{aligned}$$

So, $\int_B f dx_1 \wedge \dots \wedge dx_n = \int_{B \setminus \{0\}} f dx_1 \wedge \dots \wedge dx_n = \int_{B \setminus \{0\}} \phi^*(h \omega dt) = \int_{S^{n-1} \times [0,1]} h \omega dt = \int_{S^{n-1}} g \omega$

Thm: Let M be a non-ori. odd n -mfd. Then $H_0^2(M) = 0$

PF: Let ω be an n -form w/ opt supp. Let $\{U_i\}$ be a partition of unity: $\omega = \sum_{i=1}^k \phi_i \omega$ (finite w/ supp opt, $\text{Supp}(\phi_i \omega) \subseteq V_i \cap \mathbb{R}^{2n}$). wlog,

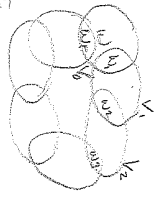
we can assume $\text{supp } \omega \subseteq V \subseteq \mathbb{R}^{2n}$.

Assume (X, θ) is a coord. system. We claim that we can construct a sequence (V_i, α_i)

w/ $V_0 = V, V_i \subset V, \exists$ s.t. $V_i \cap V_{i+1} = \emptyset$ &

$X_{i+1} \circ X_i^{-1}$ is local. or-preserving, & $X_{i+1} \circ X_i^{-1}$ is local or-reversing. If such a chain DNE,

then M is or (\neq). Choose one such chain



Assume $\int_{V_0} \omega > 0$. Note that since $V_i \subset \mathbb{R}^{2n}$ w/ $\int_{V_i} \omega = 0$, then $\omega = d\eta$ for

some η w/ opt. support (b/c \mathbb{R}^{2n} or, so we proved this already). \mathbb{R}^{2n} contractible, so $\omega = d\eta$ for some η , but not nec. w/ opt supp.

We define ω_i on $V_i \cap V_{i-1}$ w/ $\int_{V_i} \omega_i > 0$, for $i=1, \dots, r$, $\text{supp } \omega_i \subseteq V_i$.

Since $H_0^2(\mathbb{R}^{2n}) = \mathbb{R}$, $\omega_i = c_i \omega_i + d\eta_i$, & recall $c_i = \frac{\int_{V_i} \omega_i}{\int_{V_i} \omega_i} > 0$.

On the other hand, ω , as related to ω_r , will have opposite orientation, so if $\omega = c_r \omega_r + d\eta_r$, $c_r < 0$

(In other words, if we want to compare ω_r w/ a form $N = V_r$ s.t. c_r is positive, it will need to be $-\omega$).

$$\omega_1 = c_0 \omega + d\eta_0$$

$$\omega_2 = c_1 \omega_1 + d\eta_1$$

$$\omega = c_r \omega_r + d\eta_r$$

$$\Rightarrow \omega = c_0 c_1 \dots c_r \omega + d\eta$$

□

Let $f: M \rightarrow N$. If $\omega \in \Omega^k(N)$, $f^* \omega \in \Omega^k(M)$. Can we define a map

$$f^*: H^k(N) \rightarrow H^k(M) \quad ? \text{ Is it well-def. ? Yes: If } \omega = \hat{\omega} + d\eta,$$

$$[f^* \omega] \mapsto [f^* \hat{\omega}] \quad f^* \omega = f^* \hat{\omega} + d(f^* \eta) \quad \text{[pullback \& differentials commute].}$$

What about $f^*: H_c^k(N) \rightarrow H_c^k(M)$? We would need to know $f^* \omega$ has opt supp behavior as does.

$[u] \mapsto [f^* \omega]$ has opt supp behavior as does. i.e. that f is proper.

Assume f is proper if M, N are or, ctd n -mflds, then $H_0^c(M) \cong \mathbb{R} \cong H_0^c(N)$, so $f^*: \mathbb{R} \rightarrow \mathbb{R}$, & is linear $\Rightarrow \exists$ a number α s.t. $\int_M f^* \omega = \alpha \int_N \omega$, & independent of ω . \hookrightarrow is mult. by $\#$.

$f^*(\text{Vol})$ & Vol

Def: α is the degree of f .

Def: Let $p \in M$. We define $\text{sign}_p f = \begin{cases} 1 & \text{if } f_*: T_p M \rightarrow T_p N \text{ preserves or.} \\ -1 & \text{if } \dots \text{ reverses } \dots \end{cases}$

Thm: Let $f: M \rightarrow N$ be a proper map of ctd oriented n -mflds. Let $q \in N$ be a regular value. (i.e. Jacobian has full rk at all the preimages) Then $\deg f = \sum_{p \in f^{-1}(q)} \text{sign}_p f$, or $= 0$ if $f^{-1}(q) = \emptyset$.

Note: This implies $\deg f \in \mathbb{Z}$.

Pr: Since f is a regular value, $f^{-1}(q)$ must be discrete, as an accumulation pt would give a vanishing directional derivative, contradicting that they are regular pts. $\{q\}$ is cpt, so $f^{-1}(q)$ is cpt as well, since f proper, so $f^{-1}(q) = \{p_1, \dots, p_k\}$ is finite.

If we have $f u_i \in V$, & $f u_i \rightarrow V$ an iso. $\forall u, q \in V = \mathbb{R}^n$ all open, then construct ω w/ $\text{supp} \omega \subseteq V$ cpt $\text{supp} \omega \ni \int_V \omega > 0$.

$$\text{If } \int_M f^* \omega = \sum_i \int_{u_i} f^* \omega = \sum_i \text{sign}_p f \int_V \omega, \text{ then } \sum_i \text{sign}_p f = \deg f.$$

$\text{supp } f^* \omega \subseteq f^{-1}(\text{supp } \omega)$

So it remains only to show we can construct such V :
 Let U_i be s.t. $p_i \in U_i$ & $U_i \cap U_j = \emptyset$, & each U_i having only locally a diffeo.
 Let ω be a cpt nbhd of q . Let $\tilde{\omega} = f^{-1}(\omega) \cap \bigcup_i U_i$. $\tilde{\omega}$ is cpt, & so $f(\tilde{\omega}) \subseteq \omega$ is cpt. Thm 8.9. There fore $\tilde{\omega} \cap f^{-1}(\omega)$ is a nbhd of q . Let $q \in V = (\omega \setminus f(M))$ be an open set. Define $\hat{U}_i = U_i \cap f^{-1}(V)$.

Def: Two maps $f, g: M \rightarrow N$ are C^0 homotopic if $\exists H: [0, 1] \times M \rightarrow N$, s.t. $H(0, p) = f(p) \neq H(1, p) = g(p)$.

Thm: If $f \sim g$, then $f^*: H^k(N) \rightarrow H^k(M)$, $f^* = g^*$.

Pf: $f \sim g$ by $i_0: M \rightarrow [0, 1] \times M$ such that $H \circ i_0 = f$
 $i_1: M \rightarrow [0, 1] \times M$ such that $H \circ i_1 = g$

Then $g^* \omega - f^* \omega = i_1^* (H^* \omega) - i_0^* (H^* \omega) \stackrel{\text{Poincaré Lemma}}{=} \int_{\partial U} d(H^* \omega) + d(I(H^* \omega))$
 ω closed

So $g^* \omega - f^* \omega = d\eta \Rightarrow [g^* \omega] = [f^* \omega]$.

Cor: (1) If M, N are orientable, $\neq f \sim g$, $\deg f = \deg g$.

Recall: $f \sim g \Rightarrow f^* = g^* \Rightarrow \deg f = \deg g$

Cor: If n is even, there is no nonvanishing vector field on S^n .

Pr: Assume there is. Let $A: S^n \rightarrow S^n$, $A(p) = -p$. Construct a

hopy from $A(p)$ to $\mathbb{1}(p)$:

Let $\gamma_x^p(t)$ be the large circle st

$$\gamma_x^p(0) = p \quad \& \quad \gamma_x^p(1) = -p$$

$(\gamma_x^p)'(0) = \vec{X}(p)$ Since X is C^∞ , one can prove that

$$H: [0,1] \times S^n \rightarrow S^n \quad \text{is } C^\infty.$$

$$(t, p) \mapsto \gamma_x^p(t)$$

But $H(0,p) = \mathbb{1}(p) \neq H(1,p) = A(p)$, so $A \sim \mathbb{1}_{S^n}$, so $\deg A = \deg \mathbb{1}_{S^n} = 1$.

But $\deg A = \sum_{p \in \mathbb{R}^n} \text{sign}(A) = -1$, since $A^{-1}(q) = -q \quad \& \quad \text{sign } A = -1$ since ψ

n is even, A reverses the orientation.

□

Note: If n is odd, such a v.f. always exists: If $p = (a_1, a_2, \dots, a_{n+1}) \in \mathbb{R}^{n+1}$,

define $X(p) = (a_2, a_1, \dots, a_{n+1}, -a_n) \in TS^n$.



Cor: $H^k(S^{n-1}) \cong H^k(\mathbb{R}P^n \setminus \{0\}) \quad \forall k$.

Pr: Recall the retraction $r: \mathbb{R}^n \setminus \{0\} \rightarrow S^{n-1}$. Then $\mathbb{1}_{S^0}: \text{Tot}: S^{n-1} \rightarrow S^{n-1}$

So $(\text{Tot})^* = \mathbb{1}_{S^{n-1}} = \mathbb{1}_{H^k(S^{n-1})}$. LOTS: $(\text{Tot})^* = \mathbb{1}_{H^k(\mathbb{R}P^n \setminus \{0\})}$ so that $r^* \text{ on } \cong$, $\&$ we're done

We'll show $\text{Tot} \sim \mathbb{1}_{\mathbb{R}P^n \setminus \{0\}}$:

$$H(t,p) = tp + (1-t) \frac{p}{\|p\|} \quad (\text{straight-line hopy})$$

□

Lie Groups

Def: G is a Lie gp if G is a gp and a manifold st. the maps

$$(a,b) \rightarrow ab \quad ; \quad a \rightarrow a^{-1} \text{ are smooth. This is equivalent to } (a,b) \rightarrow a^{-1}b \in \mathcal{L}^0.$$

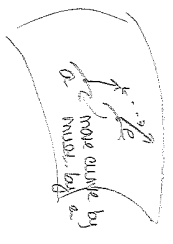
Ex: $(\mathbb{R} \setminus \{0\}, \cdot)$

$O(n), U(n), SL(n), Spin, \dots$: also matrix gps.

* If G is a Lie gp, define homeos $L_a: G \rightarrow G$ and $R_a: G \rightarrow G$

$$R_a: G \rightarrow G \quad ; \quad \text{homeos since } L_a^{-1} = L_{a^{-1}} \quad ; \quad R_a^{-1} = R_{a^{-1}}.$$

Def: A v.f. X on G is left-invariant if $L_a X = X$. Similarly for right-invariant.



If $\gamma(t) \in G$ w/ $\gamma(0) = e$, then $a\gamma(t) \in G$ w/ $a\gamma(0) = a$. Since $\gamma'(0) \in T_e G$, $L_a X'(0) \in T_a G$, so this def makes sense.

Note: Saying $L_a X = X$ is equivalent to saying X is L_a -related to X , so the space of L -inv. v.f.'s is closed under the Lie bracket

Def: $T_e G = \mathfrak{g}$, the Lie algebra (a v.sp.) with Lie bracket

$$[v,w] = [X_v, X_w](e), \text{ where } X_v \text{ is the left v.f. corresp. to } v. \text{ (use our assumption } X_v \text{ is } L\text{-inv. v.f.'s from } v \in \mathfrak{g} \text{, proven below)}$$

Thm: The tangent bundle of G is trivial. (i.e. X_v is C^∞)

Pf: We only need to find n ($= \dim G$) global independent v.f.'s. If we have them, then the map $TG \rightarrow G \times \mathbb{R}^n$ is a triv. of the bundle.

Let $X(a) = L_a X(v)$, $v \in T_e G$. Consider coords (x_1, \dots, x_n) around $a \in G$. $v \in T_e G \mapsto (p, v_1, \dots, v_n)$, $v = \sum v_i X_i(p)$. Let $X(a) = \sum X_i(x_i) \partial x_i$ vsu st. $\langle a, b \rangle \in V$, $ab \in U$. $X(a)(x_j)$ is C^∞ (since $X = \sum X_i(x_i) \partial x_i$)

$$X(\omega)(x_j) = (L_{x_j^{-1}})_* V(x_j) = V(L_{x_j}(\omega)).$$

$L_{a_j}(x_j)(b) = x_j(a \cdot b)$, $\dot{x}_j(a \cdot b)$ is C^∞ , so $x_j(a \cdot b)$ is C^∞ , so

$V(L_{x_j}(\omega))$ is C^∞ . (b/e takes C^∞ to C^∞).

Recall: \exists conjugation map $G \times G \xrightarrow{A} G$. Fixing g , this maps $e \rightarrow e$. $(gh) \xrightarrow{A} gh^g$. \square

Fixing g , then $A_x(g): g \rightarrow g$. This defines an action $G \times g \rightarrow g$, called the adjoint action on the Lie algebra, usually written $Ad(g)(v) = A_x(g)(v)$.

\rightarrow you're conjugating the derivative of a curve.

We can differentiate this map (take curve in \mathfrak{g} thru e \dot{x} diff) to get an action of \mathfrak{g} on itself, the adjoint action of \mathfrak{g} .

$\mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$, which defines the Lie bracket.

Problem: Think about $ad(\omega)(v) = [v, \omega]$.

Ex: Assume G a matrix \mathfrak{g} .

$$A_x(g)h = ghg^{-1}.$$

If $B = h/e$, then $Ad(g)(B) = gBg^{-1}$ (i.e. skew-symm conf by rotation is still skew-symm)

If $C = g'(t_0)$, $g(t_0) = e$, then $\frac{d}{dt} g(t_0) = g^{-1} g' g^{-1}$

$$Ad(e)(C) = \frac{d}{dt} \Big|_0 (gBg^{-1}) = C B - B C = [C, B]$$

Recall: We had a problem: $O(n) = \{A \in GL(n), A^T = -A\}$ is a mfd.

We do this by showing $A \rightarrow A^T$ has full rk around those for which $A^T = -A$, for $x \in I$, around I . So I is a regular value, & its preimage is a submfd of $GL(n)$. The rk is same everywhere

$A^T = -A$, w/c if v 's $L_{A^T} R_{A^T}(e)$, so rk at $A = rk$ at e . At e , we

ad to diff. $A^T = -A$, which gives representation of a Lie alg.

$$A \rightarrow \mathbb{R}A^T \text{ at } AA^T = I.$$

$$A'(a) = e$$

$$A'(a) = B \in \mathfrak{g} = T_e(\mathfrak{u}(n))$$

$$AA^T = I \xrightarrow{\text{diff}} A'(a) + A^T'(a) = 0, \text{ so } B = -B^T$$

So showing $\dim \text{Lie alg} = \dim \text{Lie grp}$ shows the Lie sp is a mfd.

Def: $H \subseteq G$ is a Lie subgrp if H is a submfd and a subgrp of G .

Let $\mathfrak{h} = T_e H = T_e G = \mathfrak{g}$. Since

$$\begin{array}{ccc} \mathfrak{h} & \xrightarrow{i} & \mathfrak{g} \\ \downarrow \text{Lie} & & \downarrow \text{Lie} \\ \mathfrak{h} & \xrightarrow{i} & \mathfrak{g} \end{array} \text{ commutes, } \mathfrak{h} \text{ is a } \underline{\text{Lie subalgebra}}$$

extend a vector by $L_a : \forall \eta \in \mathfrak{h}, X(a) = L_{a*} \eta$, then take brackets. So if take Lie bracket of \mathfrak{h} , you'll end up in \mathfrak{h} :

$$[v, w] = [X_v, X_w](e), \text{ but } [X_v, X_w] = L_{a*} [v, w] = L_{a*} [v, w]_{\mathfrak{h}}$$

So Lie subgp \Rightarrow Lie subalg. But we'll show next time that Lie subalg \Rightarrow Lie subgp as well, which is done being able to integrate.

Thm: $\mathfrak{h} \subseteq \mathfrak{g}$ a subalg, then $\exists!$ $\mathfrak{H} \subseteq \mathfrak{G}$ subgrp, s.t. \mathfrak{h} is a Lie alg of \mathfrak{H} .

\mathfrak{h} -subgrp that is also a subalgebra
ex: $\text{O}(n) \subseteq_{\text{Lie}} \text{GL}(n)$

Prf: Define $\Delta_a = \{v \in \mathfrak{g} \mid v = X(a), \text{ where } X \text{ is left-inv. } \& X(e) \in \mathfrak{h}\}$
(the portion of \mathfrak{g} in \mathfrak{h} -direction) This is integrable, b/c
 $v = L_{a^*} X(e)$, & since L_{a^*} preserves Lie brackets & \mathfrak{h} is a subalg,
then Δ is involutive & by Frobenius, integrable. So we have
many leaves, & we let \mathfrak{H} be the max'd integrable subalgebra
 $\mathfrak{h} \in \mathfrak{H}$, i.e. leaf through e .

\mathfrak{H} is a subgrp: $L_{a^*}(\Delta_a) = \Delta_{a^*}$. L_b takes integral subalgebras to
integral subalgebras. (In fact, the int. subalgebra through a to the
one through ab). Thus, $\forall a \in \mathfrak{H}, L_{a^{-1}}(\mathfrak{H}) = \mathfrak{H}$

So \mathfrak{H} is closed under $b \rightarrow a^{-1}b$, & hence \subseteq the leaf containing
it's a subgrp. It's a subalgebra by def, & $a \rightarrow a^{-1}e$.

The maps $(a,b) \rightarrow ab$ & $a \rightarrow a^{-1}$ are C^∞ since they are in
 \mathfrak{G} & \mathfrak{H} has the induced structure, so \mathfrak{H} is a Lie subgrp. \square

Def: The \mathfrak{g} -valued form ω , for $\forall a \in \mathfrak{g}, \omega(v_a) = L_{a^*} v_a$, i.e.
pull v_a back to the identity, & ω is called the Maurer-Cartan form.

$$\omega = \sum x_i dx_i, \text{ where } x_i: \mathfrak{G} \rightarrow \mathfrak{g}$$

$$= \omega^i v_i$$

$$= \omega \text{ is left-invariant, i.e. } (L_b^* \omega)(v_a) = \omega(L_{b^*} v_a) = L_{(ba)^*} L_b^* v_a$$

$$= L_{a^*} L_b^* L_b^* v_a = L_{a^*} v_a = \omega(v_a)$$

So ω depends only on its value at e , so constant on a

$$\text{Ex: } \mathfrak{GL}_n(\mathbb{R}) : \omega(v_a) = L_{a^*} \left(\overset{\text{TG}}{v} \right) = (e, a^{-1} v_a)$$

\uparrow matrix
 \mathfrak{g} matrix
 \downarrow Lie alg moved to a

Classically, one writes $\omega = g^{-1} dg$, representing by g the identity
map on \mathfrak{G} .

Def:

$$d\omega(X, Y) = X(\omega(Y)) - Y(\omega(X)) - \omega([X, Y])$$

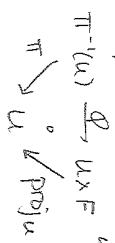
$\underbrace{\omega(Y)}_{\text{zero}}$ $\underbrace{\omega(X)}_{\text{zero}}$ $\underbrace{\omega([X, Y])}_{\text{constant} = \omega(Y_e)}$

So $d\omega(X, Y) + \omega([X, Y]) = 0$

$d\omega + \omega \wedge \omega = 0$ called the structure equation.

Def: Let F be a top. sp. We say (E, B, π, F) is a fiber bundle

if $E \xrightarrow{\pi} B$ is a fib. for every pt $p \in B$ \exists open set $U \subset B$ & homeomorphisms ϕ s.t. $\phi: \pi^{-1}(U) \rightarrow U \times F$ a homeo.



Def: An action of a Lie gp on a mfld M is a smooth map

$$\begin{aligned} \mu: G \times M &\rightarrow M & \text{s.t.} & \quad (1) \mu(e, p) = p \\ (g, p) &\mapsto \mu(g, p) & & \quad (2) \mu(h, \mu(g, p)) = \mu(hg, p) \end{aligned}$$

Def: μ is free if $(\mu(g, p) = \mu(h, p) \text{ for some } p) \Rightarrow g = h$. μ is transitive if given any $p, q \in M$, $\exists h$ s.t. $\mu(h, p) = q$.

$G_p = \{ \mu(g, p) \mid g \in G \}$ is the orbit of p . μ is transitive $\Leftrightarrow G_p = G$.

Def: Assume we have a fiber bundle & an action of G on F ,

$G \times F \rightarrow F$. A G-atlas is an atlas s.t. the transition fns $xy^{-1}: UNV \times F \rightarrow UNV \times F$ for some smooth map $h: UNV \rightarrow G$, $xy^{-1}(p, f) = (p, \mu(h, f))$

A G-bundle is a fiber bundle w/ a max. G-atlas.

Ex: Let $H \leq G$ be closed. Then one can prove that G/H is a mfld.
- closed needed b/c $\mathbb{Q} \leq (\mathbb{R}, +)$ & \mathbb{R}/\mathbb{Q} = irrationala, not a mfld.

Def: A principle G -bundle is a G -bundle with a transitive & free action of G on E preserving the fibers $G \times E \rightarrow E$

\downarrow
 G/H is a H -principle bundle w/ fiber H .
 This principle bundle of the Maurer-Cartan form is the Klein geometry.

Ex: $E(n)$, Euclidean sp.

$$E(n) = \text{So}(n) \times \mathbb{R}^n$$

$$(\theta_V)(\partial_i, \partial_j) = (\theta^i, \theta^j + v)$$

Let $H = \text{So}(n)$, $G = E(n)$. Then $G/H \cong \mathbb{R}^n$

$$[\theta_V] = [e_V], (\theta, \rho] \\ = [e_V]$$

There is a natural action $G \times G/H \rightarrow G/H$. If we identify

$$(g, [p]) \rightarrow [gp]$$

$E(n)/\text{So}(n)$ w/ the section $\mathbb{R}^n \rightarrow E(n)$, then
 $\text{So}(n) \backslash \mathbb{R}^n \rightarrow (e, p)$

$(\theta_V) \cdot [e, p] = [e, (\theta_V p)]$, which is the Euclidean action.

Note: Almost all classical geometries can be thought of this way.

Def: A pair (G, H) , $H \subseteq G$, together w/ $G \rightarrow G/H \cong \mathbb{R}^n$ is a Maurer-Cartan form, is called a Klein geometry.

Properties of H-C form, ω :

(1) ω is a linear iso. on the fibers of the tangent bundle

$$(2) R_h^* \omega = \text{Ad}(h^{-1}) \omega \quad \forall h \in H$$

$$(3) \omega(X_V) = v \quad \forall v \in \mathbb{R}^n \quad X_V|_p = \lambda_X(\rho(p))(\theta_V)$$

Cartan considered other forms w/ these 3 properties, & other principle bundles. From the structure eqn for that form $\neq \omega$, but a different form, which measures things like curvature (which you usually need a distance to measure (from Riemannian geom)).

